



HMD Next Generation- Servo motors with planetary gears

HeiMotion
Dynamic

■ Introduction

As additional extension to the HeiMotion servo range the HeiMotion Dynamic Next Generation series is now supplemented by compact directly mounted gears with diameters from 60 mm to 100 mm. The modular flanges allow besides the standard combinations even to combine different motor and gear sizes to realize special requirements such as high radial loads or various mounting types on the machine.

Since the advantages of the HMD Next Generation motors, such as the further improved dynamics and the more compact design compared to their predecessors, were to be supplemented even further, the focus of the design requirements was on reducing the overall length of the gear and keeping noise to a minimum.

The elimination of the clamp coupling and the more precise connection of the sun gear allowed the noise level to be reduced by up to 6 dB. The 1-stage gear unit is available in gear ratios of 1 to 10, and the dual-stage model is available in gear ratios from 9 to 64. Other advantages of direct mounting include the low mass moment of inertia and the light weight.

The HeiMotion Dynamic Next Generation motors are available in four standard frame sizes:

- 60 mm - HMD06
- 80 mm - HMD08
- 100 mm - HMD10
- 130 mm - HMD13

... and can be combined with the following gear unit sizes:

- E06 / E07 / P07 / H06 / F06 / V06
- E06 / E07 / E08 / E09 / P07 / P09 / H06 / H08 / F06 / F09 / V06 / V09
- E08 / E09 / E10 / P09 / H08 / F09 / V09 / V10
- E10 / V10

The features of the gear unit at a glance:

- Low backlash
- High output torques
- High efficiency
- Low noise
- The highest standards for quality
- Flexible mounting position
- Lifetime lubrication
- Same rotating direction of gear unit and motor
- Modular design with additional options available upon request

Advantages of the HMD Next Generation motor-gear unit combination:

- Short length
- Low mass moment of inertia
- Lightweight
- Low noise
- High efficiency

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Drives (motor-gear-combinations)



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Highest variance	
E07, E09 with square mounting flange	
E04, E06, E08 with round mounting flange	



Motors with P -gears (Powerful economy)	from p. 32
Economical gear	
Higher radial and axial forces	



Motors with H -gears (Heavy duty)	from p. 40
Highest radial and axial forces	



Motors with F -gears (Flange output)	from p. 48
Economical flange-gear	
Output flange according to DIN ISO 9409	
High tilting rigidity	



Motors mit V -gears (Vehicle optimized)	from p. 56
Economical gear with flange output	
Compact design	
Optimized for use in mobile robots (AMR's, AGV's, etc...)	
High tilting rigidity	

Overview output shaft and feather key	p. 68
Optional angular gearbox with direct mounting	p. 69

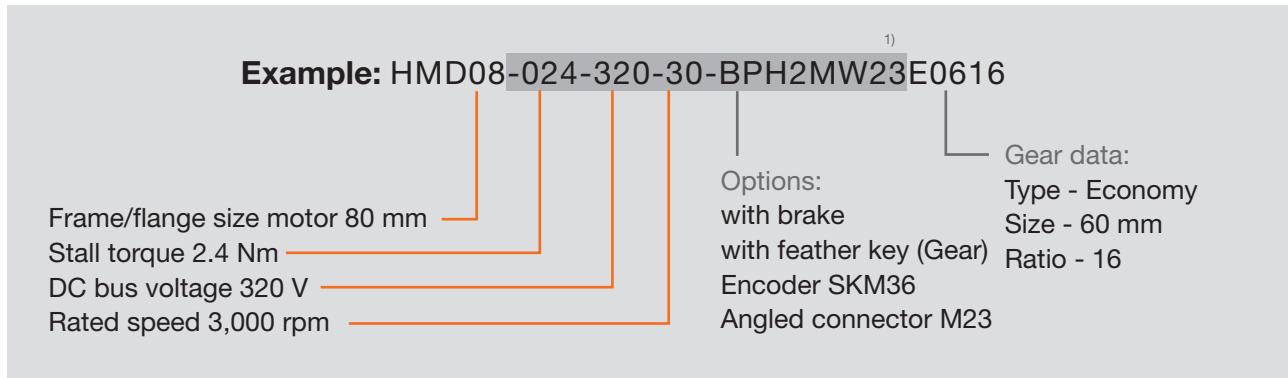
■ Order code

HMD08-024-320-30-BPH2MW23E0616	
Frame/flange size	60 mm → 06 80 mm → 08 100 mm → 10 130 mm → 13
Stall torque	1.1 Nm → 011 1.9 Nm → 019 2.4 Nm → 024 2.6 Nm → 026 3.2 Nm → 032 3.9 Nm → 039 4.2 Nm → 042 5.7 Nm → 057 7.6 Nm → 076 10.5 Nm → 105 13.3 Nm → 133 19.0 Nm → 190 24.5 Nm → 245
DC bus voltage	24 V → 024 48 V → 048 320 V → 320 560 V → 560
Rated speed	2,000 rpm → 20 3,000 rpm → 30 3,600 rpm → 36 5,000 rpm → 50 5,500 rpm → 55 6,000 rpm → 60
Gear type (p. 3)	Economy series → E ¹⁾ Powerful economy → P Heavy duty → H Flange output → F Vehicle optimized → V
Gear size	60 mm → 06 60/70 mm → 07 80 mm → 08 80/90 mm → 09 100 mm → 10
Ratio	i=3 → 03 i=4 → 04 i=5 → 05 i=7 → 07 i=8 → 08 i=10 → 10 i=9 → 09 i=12 → 12 i=15 → 15 i=16 → 16 i=20 → 20 i=25 → 25 i=32 → 32 i=40 → 40 i=64 → 64
Options	Without brake With brake Without feather key (Gear) With feather key (Gear) Resolver Resolver safely mounted HES 1 (1.0 V _{p-p}) HEM 1 (1.0 V _{p-p} without battery) HEM 1 (1.0 V _{p-p} with battery) HES 3 HS 16 HM 16 ECI 1118 EQI 1131 SEK 37 SEL 37 SKS 36 SKS 36S safely mounted SKM 36 SKM 36S safely mounted SRS 50 SRM 50 EES 37 EES 37-2 safely mounted EEM 37 EEM 37-2 safely mounted EKS 36 EKS 36-2 safely mounted EKM 36 EKM 36-2 safely mounted CKS 36 M23 angled Y-Tec I-Tec Cable outlet 1.5 m ³⁾ Cable outlet 5 m ³⁾ Terminal box ³⁾ Terminal box ³⁾ Terminal box ³⁾ Terminal box ³⁾
	0XXXXXXX BXXXXXXX X0XXXXXX ²⁾ XPXXXXXX ²⁾ XXR1PXXX XXRAPXXX XXM2SXXX XXM1MXXX XXM2MXXX XXM1IXXX XXS1SXXX XXB1MXXX XXE1SXXX XXE1MXXX XXH1SXXX XXH1MXXX XXH2SXXX XXHBSSXX XXH2MXXX XXHBMXXX XXH3SXXX XXH3MXXX XXD1SXXX XXDASXXX XXD1MXXX XXDAMXXX XXD2SXXX XXDBSSXXX XXD2MXXX XXDBMXXX XXI1SXXX XXXXXW23 XXXXXY17 XXXXXI17 XXXXXK15 XXXXXK50 XXXXXKB0 XXXXXKB2 XXXXXKA0 XXXXXKA2

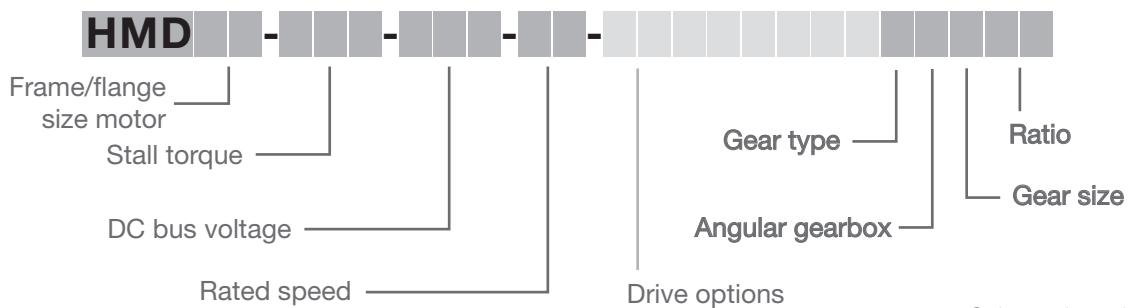
1) E06, E08, E10 with round mounting flange / E07 and E09 with square mounting flange (see also explanations on page 3).

2) Feather key option only available for E, P and H gear units. Details and definitions see page 68.

3) Only on request.



1) For the exact motor data, please refer to our main catalog "HeiMotion Dynamic Next Generation - Servo drive systems"

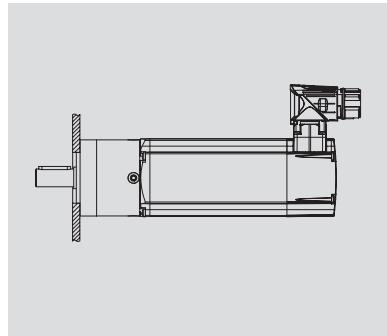


Option angular gearbox see from page 69

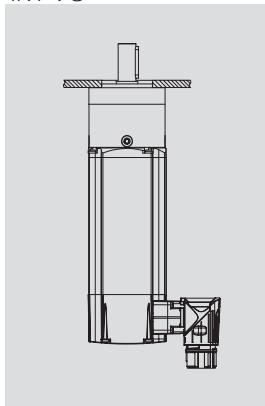
Mounting position

Please note: Specify the mounting position (IM = International Mounting) when placing an order! The following mounting positions comply with the DIN EN 600 34-7 standard (designation of machines with horizontal/vertical shafts in a flanged design).

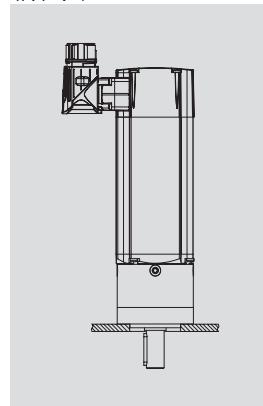
IM B5



IM V3

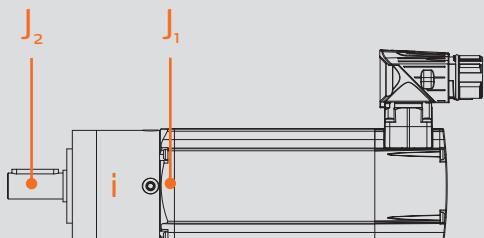


IM V1



■ General information

Calculation of the moments of inertia



$$\text{Formula: } J_2 = J_1 \cdot i^2$$

- The moments of inertia specified in this catalog refer to the motor shaft or the geared drive (J_1)
- Indicated is the total moment of inertia of the motor, the gear and (if mounted) the brake
- Designation moment of inertia: J_1 , unit: kg·cm²
- Calculation of the moment of inertia of the drive side (J_2), see formula

Abbreviations and definitions

Abbr.	Unit	Explanation
n_n	[rpm]	Rated speed of the motor
n_{out}	[rpm]	Output shaft speed at the gear unit
M_0	[Nm]	Stall torque of the motor-gear-unit, taking into account the gear ratio and the gear efficiency (see ambient conditions and technical characteristics)
M_n	[Nm]	Rated torque of the motor-gear-unit, taking into account the gear ratio and the gear efficiency (see ambient conditions and technical characteristics) as a function of the rated speed of the motor
M_{max}	[Nm]	Maximum torque of the motor-gear-unit, taking into account the gear ratio and the gear efficiency (see ambient conditions and technical characteristics)
$M_{G,n}$	[Nm]	Permissible rated torque of the gear
$M_{G,max}$	[Nm]	Permissible maximum torque of the gear for 30,000 rotations of the output shaft
J_1	[kg·cm ²]	Mass moment of inertia incl. gear unit and motor, as well as brake (if mounted)
i	[·]	Gear ratio
L	[mm]	Complete length of the motor-gear-unit
m	[kg]	Complete weight of the motor-gear-unit

Ambient conditions and technical characteristics

Service life at the rated operating conditions	20,000 h *
Minimum operating temperature	- 10 °C
Maximum operating temperature	40 °C
Maximum gear temperature	90 °C *
Lubrication	Lifetime lubrication
Coating motor and gear	Black top coat, RAL 9005
Protection class motor / gear (E, P, F)	IP65 / IP54
Protection class motor / gear (H, V)	IP65 / IP65

* Depending on application and environmental conditions

■ Drive selection

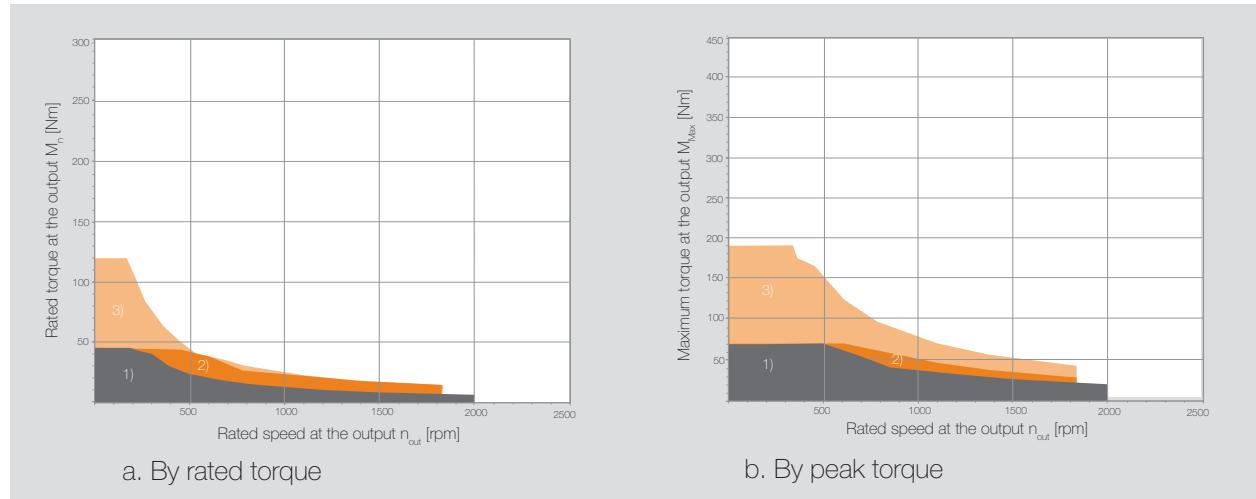
You can find overview diagrams to help you select your individualized drive on the following pages of the catalog. There are two different ways of selecting a motor and/or gear unit.

1. Drive selection by radial / axial forces (F_r , F_a)

Motor types	F_r [N]	F_a [N]	
HMD06 E06 / HMD08 E06	400	500	
HMD06 E07 / HMD08 E07	900	1,000	
HMD08 E08 / HMD10 E08	750	1,000	
HMD08 E09 / HMD10 E09	2,050	2,500	
...	Permissible values and design conditions for each gear unit can be found on page 11. Here you will also find information on backlash and torsional stiffness.

2. Drive selection by torque

2.1 Rough selection of the necessary size using the graphical preselection diagrams (see p. 8 / 9)



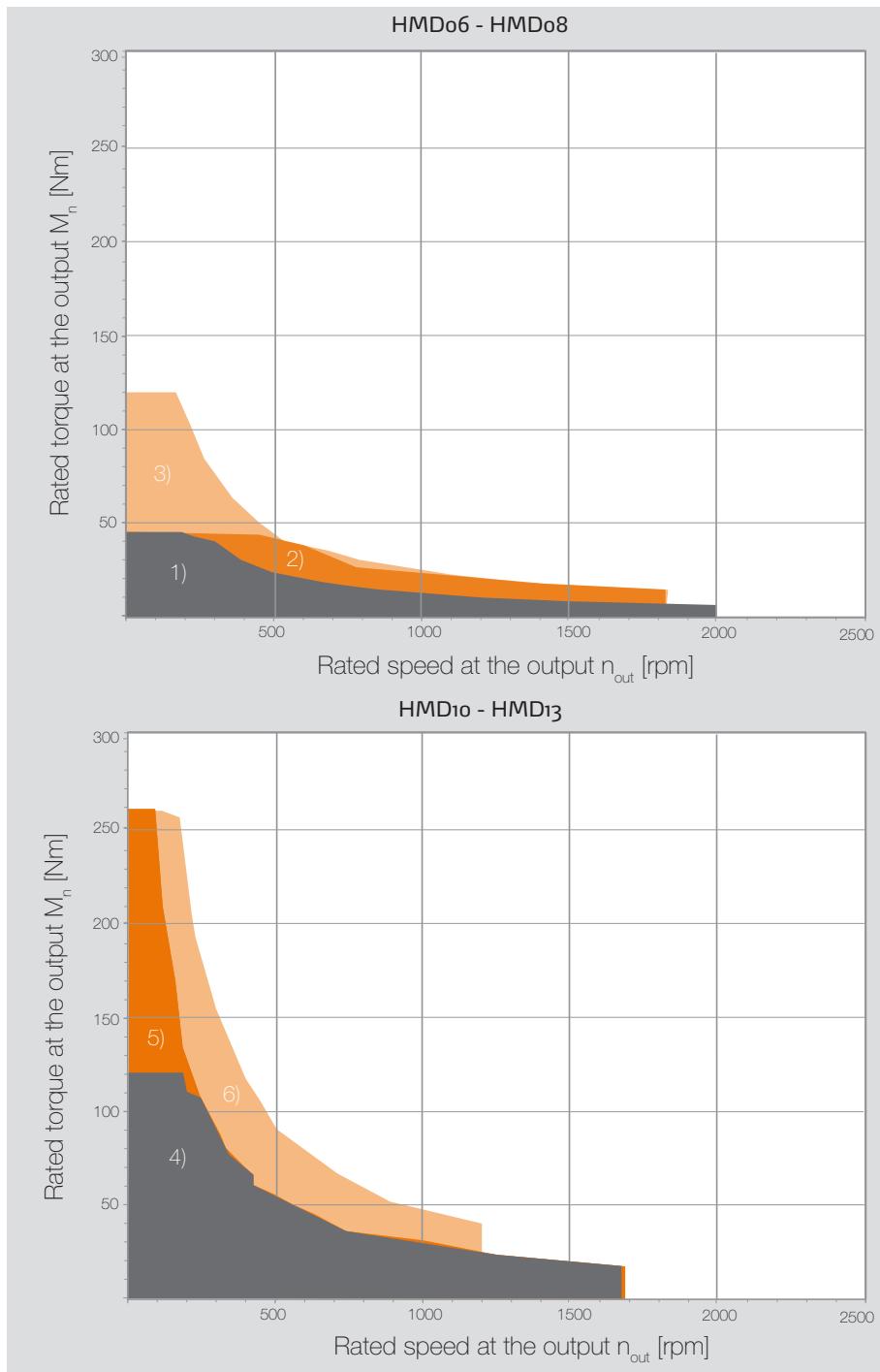
2.2 Detailed selection on the relevant pages about drives using size-specific selection tables to find the exact stall, rated and peak torques needed. The maximum torque of each gear unit is also shown in this section.

The gear unit efficiency and gear unit ratio are already taken into account in the diagrams. For the diagrams, the torques of the motor and the gear unit were compared and the maximum achievable values were used.

2.3 Determining the motor options such as connectors, brakes, etc. using the „HMD Next Generation- servo drive systems“ catalog.

Graphical preselection diagrams

Rated torque M_n of HMD06 - HMD13



1)	HMD06 E06	p. 12
	HMD06 E07	p. 14
	HMD06 P06	p. 32
	HMD06 H06	p. 40
	HMD06 F06	p. 48
	HMD06 V06	p. 56
2)	HMD08 E06	p. 16
	HMD08 E07	p. 18
	HMD08 P07	p. 34
	HMD08 H06	p. 42
	HMD08 F06	p. 50
	HMD08 V06	p. 58
	HMD08 E08	p. 20
	HMD08 E09	p. 22
	HMD08 P09	p. 36
	HMD08 H08	p. 44
	HMD08 F09	p. 52
	HMD08 V09	p. 60
3)	HMD10 E08	p. 24
	HMD10 E09	p. 26
	HMD10 P09	p. 38
	HMD10 H08	p. 46
	HMD10 F09	p. 54
	HMD10 V09	p. 62
4)	HMD10 E10	p. 28
	HMD10 V10	p. 64
5)	HMD13 E10	p. 30
6)	HMD13 V10	p. 66

Gear types



E-gear
(Economy series)



P-gear
(Powerful economy)



H-gear
(Heavy duty)

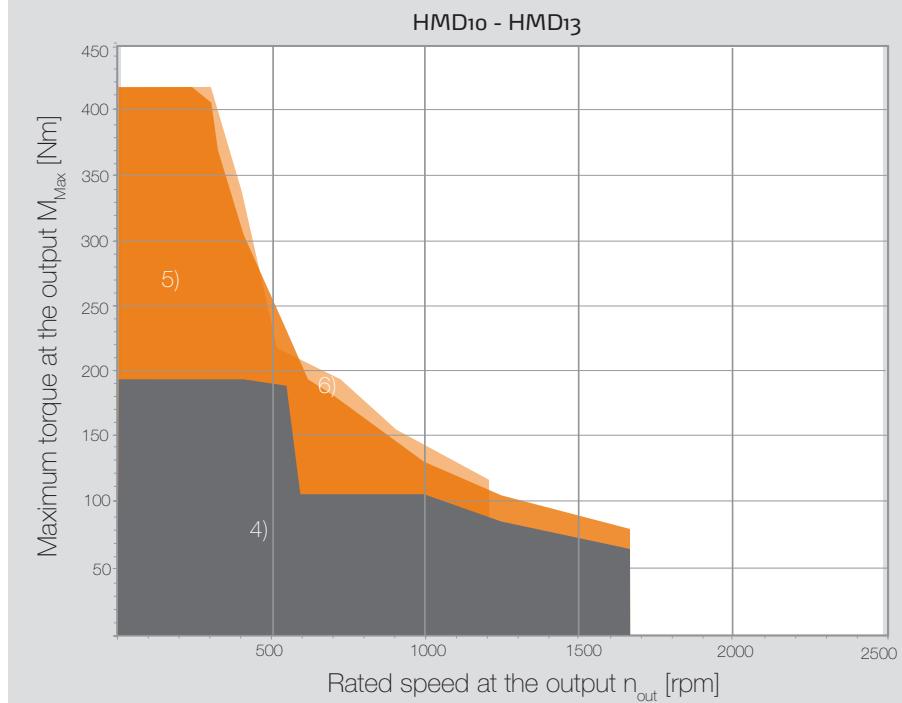
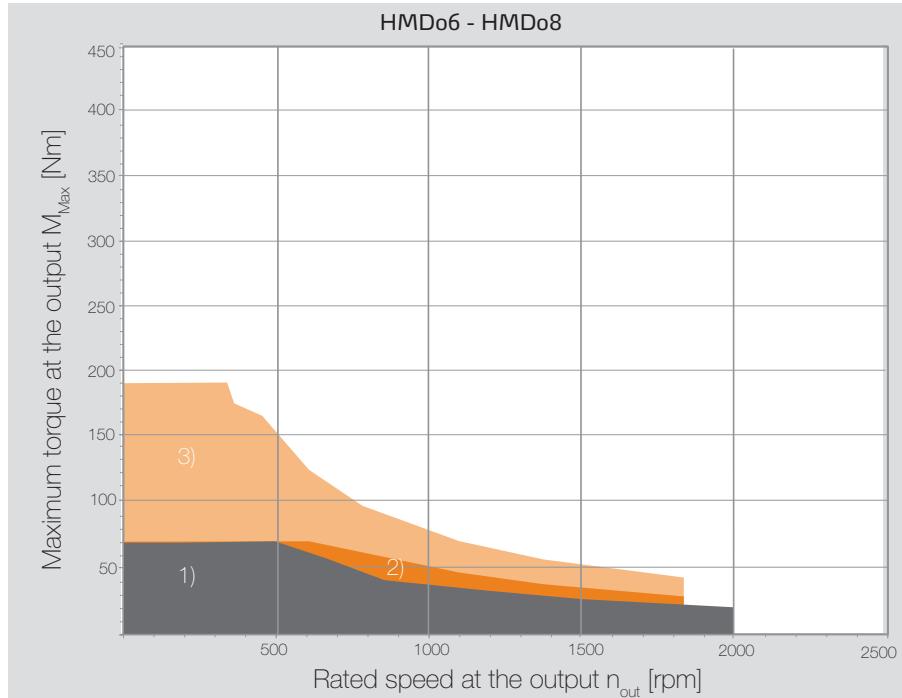


F-gear
(Flange output)



V-gear
(Vehicle optimized)

Maximum torque M_{\max} of HMD06 - HMD13



HMD06 E06	p. 12
HMD06 E07	p. 14
HMD06 P06	p. 32
HMD06 H06	p. 40
HMD06 F06	p. 48
HMD06 V06	p. 56
HMD08 E06	p. 16
HMD08 E07	p. 18
HMD08 P07	p. 34
HMD08 H06	p. 42
HMD08 F06	Pp. 50
HMD08 V06	p. 58
HMD08 E08	p. 20
HMD08 E09	p. 22
HMD08 P09	p. 36
HMD08 H08	p. 44
HMD08 F09	p. 52
HMD08 V09	p. 60

HMD10 E08	p. 24
HMD10 E09	p. 26
HMD10 P09	p. 38
HMD10 H08	p. 46
HMD10 F09	p. 54
HMD10 V09	p. 62
HMD10 E10	p. 28
HMD10 V10	p. 64
HMD13 E10	p. 30
HMD13 V10	p. 66

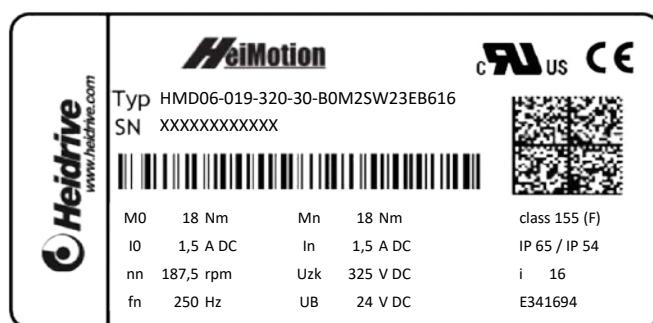
Technical data and additional information

Technical data motors

Motor description	Rated speed [rpm]	Stall torque [Nm]	Nominal torque [Nm]	Peak torque [Nm]
HMD06-011...	3000	1	1	2.5
	6000	1	1	2.5
HMD06-019...	3000	1.9	1.7	4.8
	6000	1.9	1.45	4.8
HMD06-026...	3000	2.6	2.5	6.5
	6000	2.6	2	6.5
HMD08-024...	3000	2.4	2.3	6
	5500	2.4	2.1	6
HMD08-032...	3000	3.2	3	8
	5500	3.2	2.6	8
HMD08-042...	3000	4.2	3.9	10.5
	5500	4.2	3.4	10.5
HMD08-057...	3000	5.7	5.3	14.3
	5500	5.7	4.3	14.3
HMD10-039....	3000	3.9	3.6	9.8
	5000	3.9	3.2	9.8
HMD10-057....	3000	5.7	5.2	14.3
	5000	5.7	4	14.3
HMD10-076....	3000	7.6	6.5	19
	5000	7.6	4.8	19
HMD10-105....	3000	10.5	8.6	26.3
	5000	10.5	5.5	26.3
HMD13-133....	2000	13.3	11.5	33.3
	3600	13.3	9	33.3
HMD13-190....	2000	19	16	47.5
	3600	19	11.2	47.5
HMD13-245....	2000	24.5	20.5	61.3
	3600	24.5	13.3	61.3

Type plate information

The torques and numbers on the type plate are calculated from the motor data, taking into account the gear ratio and the efficiency of the gear stages. If the permissible torques of the gear units are exceeded, the controller must derate the currents for the standstill and nominal torque to the specified value. There may be deviating values for the standstill torque or the rated torque for slowly rotating coils between the catalog and the type plate for versions with angular steps, since the catalog makes a more detailed distinction with regard to speed-dependent limit values for this option. The speed indicated on the type plate results from the rated motor speed and the gear ratio. It should be noted that the thermally permissible limit speed may differ in some cases.



Technical data gears

Gear type	Radial force [N] ³⁾	Axial force [N] ³⁾	Gear backlash [arcmin] at the output		Torsional stiffness [Nm /arcmin] ⁴⁾		Average thermal operating speed [rpm] ⁵⁾
			1-stage	2-stage	1-stage	2-stage	
...E06 ¹⁾	400	500	< 10	< 12	2.2 - 2.7	2.3 - 2.6	4500
...E07 ¹⁾	900	1000	< 10	< 12	3.1 - 4.1	3.3 - 3.9	4500
...E08 ¹⁾	750	1000	< 7	< 9	8.2 - 10.0	7.9 - 9.8	4000
...E09 ¹⁾	2050	2500	< 7	< 9	9.8 - 12.6	10.1 - 13.4	4000
...E10 ¹⁾	1200	2100	< 7	< 9	16.7 - 20.5	17.5 - 20.5	3500
...P07 ¹⁾	1050	1350	< 10	< 12	4.1 - 6.4	4.6 - 5.8	4500
...P09 ¹⁾	1900	2000	< 7	< 9	11.6 - 15.6	11.0 - 15.1	4000
...H06 ¹⁾	3200	4400	< 10	< 12	3.3 - 4.5	3.5 - 4.2	4500
...H08 ¹⁾	5500	6400	< 7	< 9	10.0 - 12.7	9.5 - 12.4	4000
...F06 ²⁾	550	1200	< 10	< 12	6.4 - 14.9	7.5 - 12.0	4500
...F09 ²⁾	1400	3000	< 7	< 9	22.0 - 44.0	20.0 - 40.5	4000
...V06 ²⁾	2300	2850	-	< 12	-	7.3 - 11.6	4500
...V09 ²⁾	4100	5450	-	< 9	-	19.5 - 39.5	4000
...V10 ²⁾	5150	6450	-	< 9	-	52.0 - 97.0	3500

1) Forces referred to the center of the output shaft.

2) Forces referred to end face of output shaft contour.

3) Permissible for nominal service life 20,000h at $n_{out} = 100\text{rpm}$ with application factor $K_a=1$ and radial or axial force not applied simultaneously.

4) Values dependent on transmission ratio.

5) Permissible for S1 operation and rated torque, except listed gear ratios in the following table.

Deviation from average thermal operating speed

Transmission	i = 3	i = 4	i = 5	i = 7	i = 9	i = 12	i = 15	i = 16
...E06	-	-	-	-	-	-	-	-
...E07	4200	4300	-	-	-	-	-	-
...E08	2700	2500	3000	-	3050	3750	-	-
...E09	2400	2350	2800	-	2950	3650	-	-
...E10	2550	2500	2500	-	2650	2600	3200	3100
...P07	3600	4100	-	-	-	-	-	-
...P09	2300	2600	3200	-	3400	-	-	-
...H06	2450	2800	3300	-	4100	-	-	-
...H08	1900	1950	2400	3900	2800	3500	-	-
...F06	3200	3400	3900	-	4400	-	-	-
...F09	2100	2100	2550	-	2800	3450	-	-
...V06	-	-	-	-	-	-	-	-
...V09	-	-	-	-	3400	-	-	-
...V10	-	-	-	-	2500	2900	-	-

■ Motor type HMDo6-011 /-019 /-026

Gear Eo6



Stall, rated and peak torque - M [Nm]

				HMDo6-011...Eo6 ¹⁾				HMDo6-019...Eo6 ¹⁾				Gear Eo6 ²⁾	
	i	$\eta_{out,3000 \text{ rpm}}^3)$	$\eta_{out,6000 \text{ rpm}}^3)$	$M_{n,3000 \text{ rpm}}$	$M_{n,6000 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,6000 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	2000	2.9	2.9	2.9	7.4	5.0	4.3	5.6	14.1	17	27.5
	4	750	1500	3.9	3.9	3.9	9.8	6.7	5.7	7.4	18.8	23	37
	5	600	1200	4.9	4.9	4.9	12.3	8.3	7.1	9.3	23.5	29	46
	7	429	857	6.8	6.8	6.8	17.0	11.5	9.8	12.9	32.6	25	40
	8	375	750	7.8	7.8	7.8	19.4	13.2	11.3	14.7	37.2	18	29
	10	300	600	9.6	9.6	9.6	24.0	16.3	13.9	18.2	46.1	15	24
2-stage	9	333	667	8.7	8.7	8.7	21.8	14.8	12.7	16.6	41.9	44	70
	12	250	500	11.5	11.5	11.5	28.8	19.6	16.7	21.9	55.3	44	70
	15	200	400	14.4	14.4	14.4	36.0	24.5	20.9	27.4	69.1	44	70
	16	188	375	15.4	15.4	15.4	38.4	26.1	22.3	29.2	73.7	44	70
	20	150	300	19.2	19.2	19.2	48.0	32.6	27.8	36.5	92.2	44	70
	25	120	240	23.8	23.8	23.8	59.4	40.4	34.4	45.1	114.0	40	64
	32	94	188	30.4	30.4	30.4	76.0	51.7	44.1	57.8	145.9	44	70
	40	75	150	37.6	37.6	37.6	94.0	-	54.5	71.4	180.5	40	64
	64	47	94	55.7	55.7	55.7	139.2	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm]

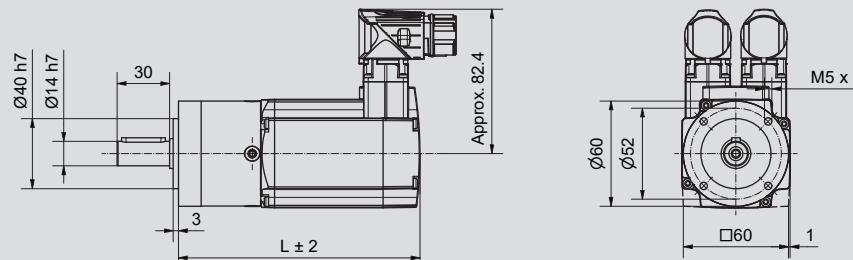
				HMDo6-026...Eo6 ¹⁾				Gear Eo6 ²⁾	
	i	$\eta_{out,3000 \text{ rpm}}^3)$	$\eta_{out,6000 \text{ rpm}}^3)$	$M_{n,3000 \text{ rpm}}$	$M_{n,6000 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	2000	7.4	5.9	7.6	19.1	17	27.5
	4	750	1500	9.8	7.8	10.2	25.5	23	37
	5	600	1200	12.3	9.8	12.7	31.9	29	46
	7	429	857	17.0	13.6	17.7	44.1	25	40
	8	375	750	19.4	15.5	20.2	50.4	18	29
	10	300	600	-	19.2	25.0	62.4	15	24
2-stage	9	333	667	21.8	17.5	22.7	56.7	44	70
	12	250	500	28.8	23.0	30.0	74.9	44	70
	15	200	400	36.0	28.8	37.4	93.6	44	70
	16	188	375	38.4	30.7	39.9	99.8	44	70
	20	150	300	48.0	38.4	49.9	124.8	44	70
	25	120	240	59.4	47.5	61.8	154.4	40	64
	32	94	188	-	60.8	79.0	197.6	44	70
	40	75	150	-	-	-	-	40	64
	64	47	94	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15% applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Details feather key and center hole please see page 68

Motor type		Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]	Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]
HMD06-011-...E06	without brake		138.0	156.0	1.80		150.5	168.5	2.00
	with brake		177.5	195.5	2.15		190.0	208.0	2.35
HMD06-019-...E06	without brake	1-stage	163.0	181.0	2.20	2-stage	175.5	193.5	2.40
	with brake		202.5	220.5	2.55		215.0	233.0	2.75
HMD06-026-...E06	without brake		193.0	211.0	2.60		205.5	223.5	2.80
	with brake		232.5	250.5	2.95		245.0	263.0	3.15

Moment of inertia ⁵⁾ - J_1 [kg·cm²]

	HMD06-011-...E06		HMD06-019-...E06		HMD06-026-...E06	
i	without brake	with brake	without brake	with brake	without brake	with brake
1-stage	3	3.35E-01		5.56E-01		7.78E-01
	4	2.99E-01		5.20E-01		7.42E-01
	5	2.87E-01		5.08E-01		7.30E-01
	7	2.76E-01		4.97E-01		7.19E-01
	8	2.75E-01		4.96E-01		7.18E-01
	10	2.72E-01		4.93E-01		7.15E-01
2-stage	9	3.28E-01		5.49E-01		7.71E-01
	12	3.25E-01		5.46E-01		7.68E-01
	15	2.83E-01		5.04E-01		7.26E-01
	16	2.92E-01		5.13E-01		7.35E-01
	20	2.83E-01		5.04E-01		7.26E-01
	25	2.82E-01		5.03E-01		7.25E-01
	32	2.73E-01		4.94E-01		7.16E-01
	40	2.73E-01		4.94E-01		7.16E-01
	64	2.73E-01		4.94E-01		7.16E-01

1) Data calculated with a gear efficiency grade defined at $n_g=1000$ rpm and the gear rated torque and a reference temperature of 70°C.

2) Data refer to an output shaft speed of $n_{out}=100$ rpm and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 V_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMDo6-011 /-019 /-026

Gear Eo7



Stall, rated and peak torque - M [Nm]

			HMDo6-011...Eo7 ¹⁾				HMDo6-019...Eo7 ¹⁾				Gear Eo7 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3)$	$\eta_{out,6000 \text{ rpm}}^3)$	$M_{n,3000 \text{ rpm}}$	$M_{n,6000 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,6000 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	2000	2.9	2.9	2.9	7.4	5.0	4.3	5.6	14.1	17	27.5
	4	750	1500	3.9	3.9	3.9	9.8	6.7	5.7	7.4	18.8	23	37
	5	600	1200	4.9	4.9	4.9	12.3	8.3	7.1	9.3	23.5	29	46
	7	429	857	6.8	6.8	6.8	17.0	11.5	9.8	12.9	32.6	25	40
	8	375	750	7.8	7.8	7.8	19.4	13.2	11.3	14.7	37.2	18	29
	10	300	600	9.6	9.6	9.6	24.0	16.3	13.9	18.2	46.1	15	24
2-stage	9	333	667	8.7	8.7	8.7	21.8	14.8	12.7	16.6	41.9	44	70
	12	250	500	11.5	11.5	11.5	28.8	19.6	16.7	21.9	55.3	44	70
	15	200	400	14.4	14.4	14.4	36.0	24.5	20.9	27.4	69.1	44	70
	16	188	375	15.4	15.4	15.4	38.4	26.1	22.3	29.2	73.7	44	70
	20	150	300	19.2	19.2	19.2	48.0	32.6	27.8	36.5	92.2	44	70
	25	120	240	23.8	23.8	23.8	59.4	40.4	34.4	45.1	114.0	40	64
	32	94	188	30.4	30.4	30.4	76.0	51.7	44.1	57.8	145.9	44	70
	40	75	150	37.6	37.6	37.6	94.0	-	54.5	71.4	180.5	40	64
	64	47	94	55.7	55.7	55.7	139.2	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm]

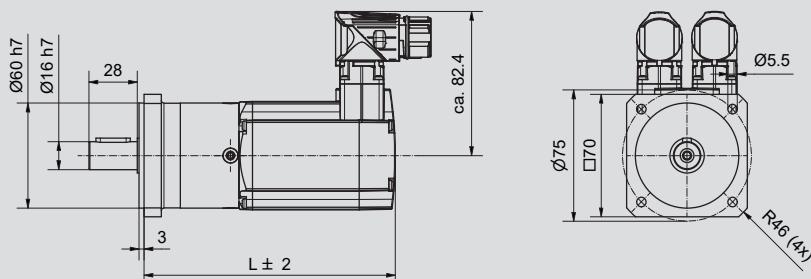
			HMDo6-026...Eo7 ¹⁾				Gear Eo7 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3)$	$\eta_{out,6000 \text{ rpm}}^3)$	$M_{n,3000 \text{ rpm}}$	$M_{n,6000 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	2000	7.4	5.9	7.6	19.1	17	27.5
	4	750	1500	9.8	7.8	10.2	25.5	23	37
	5	600	1200	12.3	9.8	12.7	31.9	29	46
	7	429	857	17.0	13.6	17.7	44.1	25	40
	8	375	750	19.4	15.5	20.2	50.4	18	29
	10	300	600	-	19.2	25.0	62.4	15	24
2-stage	9	333	667	21.8	17.5	22.7	56.7	44	70
	12	250	500	28.8	23.0	30.0	74.9	44	70
	15	200	400	36.0	28.8	37.4	93.6	44	70
	16	188	375	38.4	30.7	39.9	99.8	44	70
	20	150	300	48.0	38.4	49.9	124.8	44	70
	25	120	240	59.4	47.5	61.8	154.4	40	64
	32	94	188	-	60.8	79.0	197.6	44	70
	40	75	150	-	-	-	-	40	64
	64	47	94	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Details feather key and center hole please see page 68

Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	
HMD06-011-...E07		without brake	146.0	164.0	2.00		158.5	176.5	2.20
		with brake	185.5	203.5	2.35		198.0	216.0	2.55
HMD06-019-...E07	1-stage	without brake	171.0	189.0	2.40	2-stage	183.5	201.5	2.60
		with brake	210.5	228.5	2.75		223.0	241.0	2.95
HMD06-026-...E07		without brake	201.0	219.0	2.80		213.5	231.5	3.00
		with brake	240.5	258.5	3.15		253.0	271.0	3.35

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD06-011-...E07		HMD06-019-...E07		HMD06-026-...E07	
i	without brake	with brake	without brake	with brake	without brake	with brake
1-stage	3	3.49E-01		5.70E-01		7.92E-01
	4	3.07E-01		5.28E-01		7.50E-01
	5	2.92E-01		5.13E-01		7.35E-01
	7	2.79E-01		5.00E-01		7.22E-01
	8	2.77E-01		4.98E-01		7.20E-01
	10	2.73E-01		4.94E-01		7.16E-01
2-stage	9	3.30E-01		5.51E-01		7.73E-01
	12	3.26E-01		5.47E-01		7.69E-01
	15	2.84E-01		5.05E-01		7.27E-01
	16	2.93E-01		5.14E-01		7.36E-01
	20	2.83E-01		5.04E-01		7.26E-01
	25	2.82E-01		5.03E-01		7.25E-01
	32	2.74E-01		4.95E-01		7.17E-01
	40	2.73E-01		4.94E-01		7.16E-01
	64	2.73E-01		4.94E-01		7.16E-01

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMDo8-024 /-032 /-042 /-057

Gear Eo6



Stall, rated and peak torque - M [Nm]

			HMDo8-024-...Eo6 ¹⁾				HMDo8-032-...Eo6 ¹⁾				Gear Eo6 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3)$	$\eta_{out,5500 \text{ rpm}}^3)$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	6.8	6.2	7.1	17.6	8.8	7.6	9.4	23.5	17	27.5
	4	750	1375	9.0	8.2	9.4	23.5	11.8	10.2	12.5	31.4	23	37
	5	600	1100	11.3	10.3	11.8	29.4	14.7	12.7	15.7	39.2	29	46
	7	429	786	15.6	14.3	16.3	40.7	20.4	17.7	21.7	54.3	25	40
	8	375	688	17.8	16.3	18.6	46.6	23.3	20.2	24.8	62.1	18	29
	10	300	550	22.1	20.2	23.0	57.6	-	-	-	-	15	24
2-stage	9	333	611	20.1	18.3	21.0	52.4	26.2	22.7	27.9	69.8	44	70
	12	250	458	26.5	24.2	27.6	69.1	34.6	30.0	36.9	92.2	44	70
	15	200	367	33.1	30.2	34.6	86.4	43.2	37.4	46.1	115.2	44	70
	16	188	344	35.3	32.3	36.9	92.2	46.1	39.9	49.2	122.9	44	70
	20	150	275	44.2	40.3	46.1	115.2	57.6	49.9	61.4	153.6	44	70
	25	120	220	54.6	49.9	57.0	142.5	-	-	-	-	40	64
	32	94	172	-	63.8	73.0	182.4	-	-	-	-	44	70
	40	75	138	-	-	-	-	-	-	-	-	40	64
	64	47	86	-	-	-	-	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm]

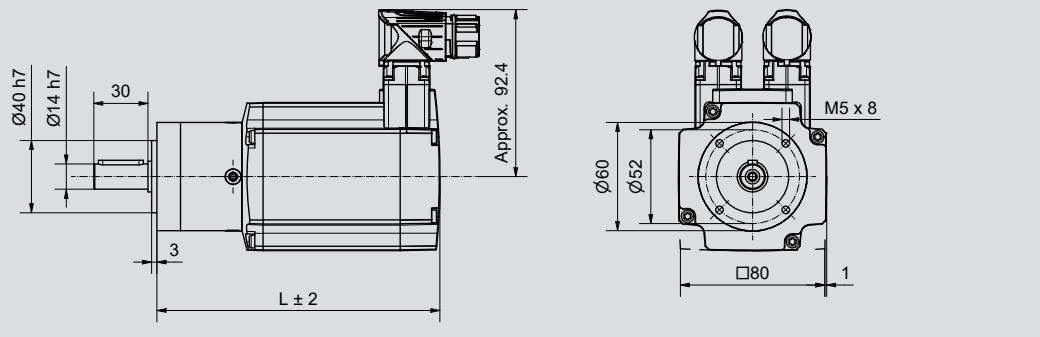
			HMDo8-042-...Eo6 ¹⁾				HMDo8-057-...Eo6 ¹⁾				Gear Eo6 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3)$	$\eta_{out,5500 \text{ rpm}}^3)$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	11.5	10.0	12.3	30.9	15.6	12.6	16.8	42.0	17	27.5
	4	750	1375	15.3	13.3	16.5	41.2	20.8	16.9	22.3	56.1	23	37
	5	600	1100	19.1	16.7	20.6	51.5	26.0	21.1	27.9	70.1	29	46
	7	429	786	26.5	23.1	28.5	71.3	36.0	29.2	38.7	97.1	25	40
	8	375	688	-	26.4	32.6	81.5	-	-	-	-	18	29
	10	300	550	-	-	-	-	-	-	-	-	15	24
2-stage	9	333	611	34.0	29.7	36.7	91.7	46.3	37.5	49.8	124.8	44	70
	12	250	458	44.9	39.2	48.4	121.0	61.1	49.5	65.7	164.7	44	70
	15	200	367	56.2	49.0	60.5	151.2	-	61.9	82.1	205.9	44	70
	16	188	344	59.9	52.2	64.5	161.3	-	-	-	-	44	70
	20	150	275	-	65.3	80.6	201.6	-	-	-	-	44	70
	25	120	220	-	-	-	-	-	-	-	-	40	64
	32	94	172	-	-	-	-	-	-	-	-	44	70
	40	75	138	-	-	-	-	-	-	-	-	40	64
	64	47	86	-	-	-	-	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	
HMD08-024...E06		without brake	156.8	178.8	3.10		169.3	191.3	3.30
		with brake	205.3	227.3	3.75		217.8	239.8	3.95
HMD08-032...E06	1-stage	without brake	171.8	193.8	3.50	2-stage	184.3	206.3	3.70
		with brake	220.3	242.3	4.15		232.8	254.8	4.35
HMD08-042...E06		without brake	186.8	208.8	3.90		199.3	221.3	4.10
		with brake	235.3	257.3	4.55		247.8	269.8	4.75
HMD08-057...E06		without brake	216.8	238.8	5.00		229.3	251.3	5.20
		with brake	265.3	287.3	5.65		277.8	299.8	5.85

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD08-024...E06		HMD08-032...E06		HMD08-042...E06		HMD08-057...E06	
i	without brake	with brake						
1-stage	3	8.67E-01		1.20E+00		1.53E+00		2.19E+00
	4	8.31E-01		1.16E+00		1.49E+00		2.15E+00
	5	8.19E-01		1.15E+00		1.48E+00		2.14E+00
	7	8.08E-01		1.14E+00		1.47E+00		2.13E+00
	8	8.07E-01		1.14E+00		1.47E+00		2.13E+00
	10	8.04E-01		1.13E+00		1.46E+00		2.12E+00
2-stage	9	8.60E-01	+2.40E-01	1.19E+00	+2.40E-01	1.52E+00	+2.40E-01	2.18E+00
	12	8.57E-01		1.19E+00		1.52E+00		2.18E+00
	15	8.15E-01		1.15E+00		1.48E+00		2.14E+00
	16	8.24E-01		1.15E+00		1.48E+00		2.14E+00
	20	8.15E-01		1.15E+00		1.48E+00		2.14E+00
	25	8.14E-01		1.14E+00		1.47E+00		2.13E+00
	32	8.05E-01		1.14E+00		1.47E+00		2.13E+00
	40	8.05E-01		1.14E+00		1.47E+00		2.13E+00
	64	8.05E-01		1.14E+00		1.47E+00		2.13E+00

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{zk} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

Motor type HMDo8-024 /-032 /-042 /-057

Gear Eo7



Stall, rated and peak torque - M [Nm]

			HMDo8-024-...Eo7 ¹⁾				HMDo8-032-...Eo7 ¹⁾				Gear Eo7 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	6.8	6.2	7.1	17.6	8.8	7.6	9.4	23.5	17	27.5
	4	750	1375	9.0	8.2	9.4	23.5	11.8	10.2	12.5	31.4	23	37
	5	600	1100	11.3	10.3	11.8	29.4	14.7	12.7	15.7	39.2	29	46
	7	429	786	15.6	14.3	16.3	40.7	20.4	17.7	21.7	54.3	25	40
	8	375	688	17.8	16.3	18.6	46.6	23.3	20.2	24.8	62.1	18	29
	10	300	550	22.1	20.2	23.0	57.6	-	-	-	-	15	24
2-stage	9	333	611	20.1	18.3	21.0	52.4	26.2	22.7	27.9	69.8	44	70
	12	250	458	26.5	24.2	27.6	69.1	34.6	30.0	36.9	92.2	44	70
	15	200	367	33.1	30.2	34.6	86.4	43.2	37.4	46.1	115.2	44	70
	16	188	344	35.3	32.3	36.9	92.2	46.1	39.9	49.2	122.9	44	70
	20	150	275	44.2	40.3	46.1	115.2	57.6	49.9	61.4	153.6	44	70
	25	120	220	54.6	49.9	57.0	142.5	-	-	-	-	40	64
	32	94	172	-	63.8	73.0	182.4	-	-	-	-	44	70
	40	75	138	-	-	-	-	-	-	-	-	40	64
	64	47	86	-	-	-	-	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm]

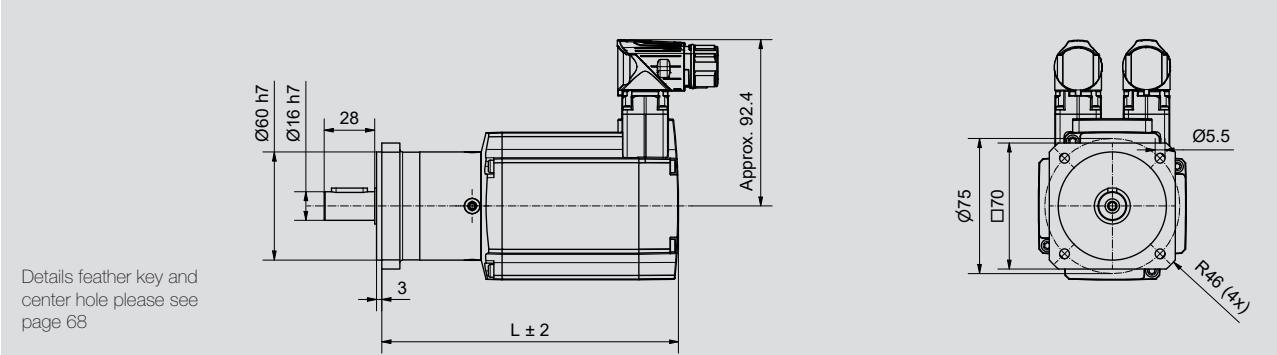
			HMDo8-042-...Eo7 ¹⁾				HMDo8-057-...Eo7 ¹⁾				Gear Eo7 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	11.5	10.0	12.3	30.9	15.6	12.6	16.8	42.0	17	27.5
	4	750	1375	15.3	13.3	16.5	41.2	20.8	16.9	22.3	56.1	23	37
	5	600	1100	19.1	16.7	20.6	51.5	26.0	21.1	27.9	70.1	29	46
	7	429	786	26.5	23.1	28.5	71.3	36.0	29.2	38.7	97.1	25	40
	8	375	688	-	26.4	32.6	81.5	-	-	-	-	18	29
	10	300	550	-	-	-	-	-	-	-	-	15	24
2-stage	9	333	611	34.0	29.7	36.7	91.7	46.3	37.5	49.8	124.8	44	70
	12	250	458	44.9	39.2	48.4	121.0	61.1	49.5	65.7	164.7	44	70
	15	200	367	56.2	49.0	60.5	151.2	-	61.9	82.1	205.9	44	70
	16	188	344	59.9	52.2	64.5	161.3	-	-	-	-	44	70
	20	150	275	-	65.3	80.6	201.6	-	-	-	-	44	70
	25	120	220	-	-	-	-	-	-	-	-	40	64
	32	94	172	-	-	-	-	-	-	-	-	44	70
	40	75	138	-	-	-	-	-	-	-	-	40	64
	64	47	86	-	-	-	-	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	
HMD08-024-...E07		without brake	164.8	186.8	3.30		177.3	199.3	3.50
		with brake	213.3	235.3	3.95		225.8	247.8	4.15
HMD08-032-...E07	1-stage	without brake	179.8	201.8	3.70	2-stage	192.3	214.3	3.90
		with brake	228.3	250.3	4.35		240.8	262.8	4.55
HMD08-042-...E07		without brake	194.8	216.8	4.10		207.3	229.3	4.30
		with brake	243.3	265.3	4.75		255.8	277.8	4.95
HMD08-057-...E07		without brake	224.8	246.8	5.20		237.3	259.3	5.40
		with brake	273.3	295.3	5.85		285.8	307.8	6.05

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD08-024-...E07		HMD08-032-...E07		HMD08-042-...E07		HMD08-057-...E07	
i	without brake	with brake						
1-stage	3	8.81E-01		1.21E+00		1.54E+00		2.20E+00
	4	8.39E-01		1.17E+00		1.50E+00		2.16E+00
	5	8.24E-01		1.15E+00		1.48E+00		2.14E+00
	7	8.11E-01		1.14E+00		1.47E+00		2.13E+00
	8	8.09E-01		1.14E+00		1.47E+00		2.13E+00
	10	8.05E-01		1.14E+00		1.47E+00		2.13E+00
2-stage	9	8.62E-01	+2.40E-01	1.19E+00	+2.40E-01	1.52E+00	+2.40E-01	2.18E+00
	12	8.58E-01		1.19E+00		1.52E+00		2.18E+00
	15	8.16E-01		1.15E+00		1.48E+00		2.14E+00
	16	8.25E-01		1.16E+00		1.49E+00		2.15E+00
	20	8.15E-01		1.15E+00		1.48E+00		2.14E+00
	25	8.14E-01		1.14E+00		1.47E+00		2.13E+00
	32	8.06E-01		1.14E+00		1.47E+00		2.13E+00
	40	8.05E-01		1.14E+00		1.47E+00		2.13E+00
	64	8.05E-01		1.14E+00		1.47E+00		2.13E+00

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMDo8-024 /-032 /-042 /-057

Gear Eo8



Stall, rated and peak torque - M [Nm]

			HMDo8-024-...Eo8 ¹⁾				HMDo8-032-...Eo8 ¹⁾				Gear Eo8 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	6.8	6.2	7.1	17.6	8.8	7.6	9.4	23.5	39	62
	4	750	1375	9.0	8.2	9.4	23.5	11.8	10.2	12.5	31.4	52	83
	5	600	1100	11.3	10.3	11.8	29.4	14.7	12.7	15.7	39.2	65	104
	7	429	786	15.6	14.3	16.3	40.7	20.4	17.7	21.7	54.3	65	104
	8	375	688	17.8	16.3	18.6	46.6	23.3	20.2	24.8	62.1	50	80
	10	300	550	22.1	20.2	23.0	57.6	28.8	25.0	30.7	76.8	38	61
2-stage	9	333	611	20.1	18.3	21.0	52.4	26.2	22.7	27.9	69.8	117	187
	12	250	458	26.8	24.4	27.9	69.8	34.9	30.3	37.2	93.1	120	192
	15	200	367	33.1	30.2	34.6	86.4	43.2	37.4	46.1	115.2	110	176
	16	188	344	35.3	32.3	36.9	92.2	46.1	39.9	49.2	122.9	120	192
	20	150	275	44.2	40.3	46.1	115.2	57.6	49.9	61.4	153.6	120	192
	25	120	220	54.6	49.9	57.0	142.5	71.3	61.8	76.0	190.0	110	176
	32	94	172	69.9	63.8	73.0	182.4	91.2	79.0	97.3	243.2	120	192
	40	75	138	86.5	79.0	90.2	225.6	112.8	97.8	120.3	300.8	110	176
	64	47	86	131.0	119.6	136.7	341.8	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

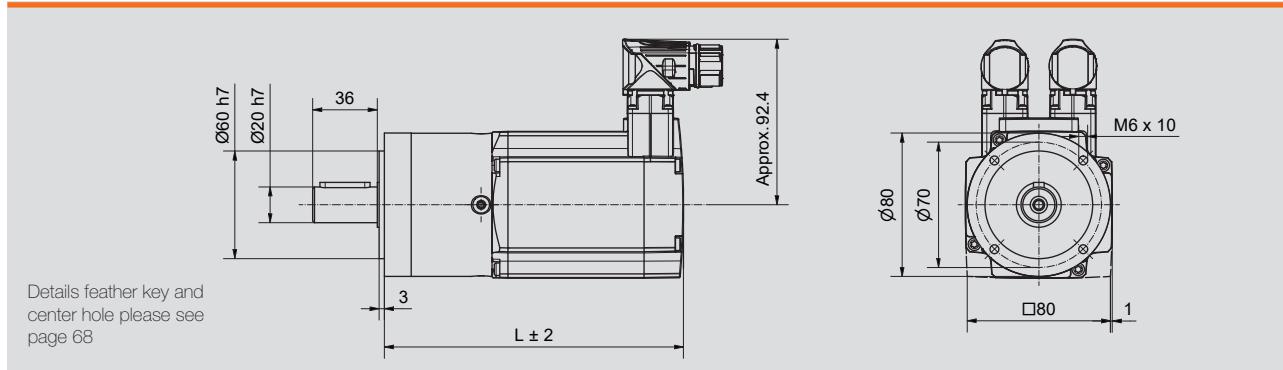
			HMDo8-042-...Eo8 ¹⁾				HMDo8-057-...Eo8 ¹⁾				Gear Eo8 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	11.5	10.0	12.3	30.9	15.6	12.6	16.8	42.0	39	62
	4	750	1375	15.3	13.3	16.5	41.2	20.8	16.9	22.3	56.1	52	83
	5	600	1100	19.1	16.7	20.6	51.5	26.0	21.1	27.9	70.1	65	104
	7	429	786	26.5	23.1	28.5	71.3	36.0	29.2	38.7	97.1	65	104
	8	375	688	30.3	26.4	32.6	81.5	41.1	33.4	44.2	111.0	50	80
	10	300	550	37.4	32.6	40.3	100.8	50.9	41.3	54.7	137.3	38	61
2-stage	9	333	611	34.0	29.7	36.7	91.7	46.3	37.5	49.8	124.8	117	187
	12	250	458	45.4	39.6	48.9	122.2	61.7	50.1	66.3	166.5	120	192
	15	200	367	56.2	49.0	60.5	151.2	76.3	61.9	82.1	205.9	110	176
	16	188	344	59.9	52.2	64.5	161.3	81.4	66.0	87.6	219.6	120	192
	20	150	275	74.9	65.3	80.6	201.6	101.8	82.6	109.4	274.6	120	192
	25	120	220	92.6	80.8	99.8	249.4	125.9	102.1	135.4	339.6	110	176
	32	94	172	118.6	103.4	127.7	319.2	161.1	130.7	173.3	434.7	120	192
	40	75	138	146.6	127.8	157.9	394.8	-	161.7	214.3	537.7	110	176
	64	47	86	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	
HMD08-024...E08		without brake	167.0	189.0	3.90		184.5	206.5	4.40
		with brake	215.5	237.5	4.55		233.0	255.0	5.05
HMD08-032...E08	1-stage	without brake	182.0	204.0	4.30	2-stage	199.5	221.5	4.80
		with brake	230.5	252.5	4.95		248.0	270.0	5.45
HMD08-042...E08		without brake	197.0	219.0	4.70		214.5	236.5	5.20
		with brake	245.5	267.5	5.35		263.0	285.0	5.85
HMD08-057...E08		without brake	227.0	249.0	5.80		244.5	266.5	6.30
		with brake	275.5	297.5	6.45		293.0	315.0	6.95

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD08-024...E08		HMD08-032...E08		HMD08-042...E08		HMD08-057...E08	
i	without brake	with brake						
1-stage	3	1.11E+00		1.44E+00		1.77E+00		2.43E+00
	4	9.12E-01		1.24E+00		1.57E+00		2.23E+00
	5	8.80E-01		1.21E+00		1.54E+00		2.20E+00
	7	8.36E-01		1.17E+00		1.50E+00		2.16E+00
	8	8.27E-01		1.16E+00		1.49E+00		2.15E+00
	10	8.17E-01		1.15E+00		1.48E+00		2.14E+00
2-stage	9	1.07E+00	+2.40E-01	1.40E+00	+2.40E-01	1.73E+00	+2.40E-01	2.39E+00
	12	1.05E+00		1.38E+00		1.71E+00		2.37E+00
	15	1.04E+00		1.37E+00		1.70E+00		2.36E+00
	16	9.03E-01		1.23E+00		1.56E+00		2.22E+00
	20	8.63E-01		1.19E+00		1.52E+00		2.18E+00
	25	8.61E-01		1.19E+00		1.52E+00		2.18E+00
	32	8.23E-01		1.15E+00		1.48E+00		2.14E+00
	40	8.23E-01		1.15E+00		1.48E+00		2.14E+00
	64	8.23E-01		1.15E+00		1.48E+00		2.14E+00

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{\text{DC}}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMDo8-024 /-032 /-042 /-057

Gear Eog



Stall, rated and peak torque - M [Nm]

			HMDo8-024-...Eog ¹⁾				HMDo8-032-...Eog ¹⁾				Gear Eog ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	6.8	6.2	7.1	17.6	8.8	7.6	9.4	23.5	39	62
	4	750	1375	9.0	8.2	9.4	23.5	11.8	10.2	12.5	31.4	52	83
	5	600	1100	11.3	10.3	11.8	29.4	14.7	12.7	15.7	39.2	65	104
	7	429	786	15.6	14.3	16.3	40.7	20.4	17.7	21.7	54.3	65	104
	8	375	688	17.8	16.3	18.6	46.6	23.3	20.2	24.8	62.1	50	80
	10	300	550	22.1	20.2	23.0	57.6	28.8	25.0	30.7	76.8	38	61
2-stage	9	333	611	20.1	18.3	21.0	52.4	26.2	22.7	27.9	69.8	117	187
	12	250	458	26.5	24.2	27.6	69.1	34.6	30.0	36.9	92.2	120	192
	15	200	367	33.1	30.2	34.6	86.4	43.2	37.4	46.1	115.2	110	176
	16	188	344	35.3	32.3	36.9	92.2	46.1	39.9	49.2	122.9	120	192
	20	150	275	44.2	40.3	46.1	115.2	57.6	49.9	61.4	153.6	120	192
	25	120	220	54.6	49.9	57.0	142.5	71.3	61.8	76.0	190.0	110	176
	32	94	172	69.9	63.8	73.0	182.4	91.2	79.0	97.3	243.2	120	192
	40	75	138	86.5	79.0	90.2	225.6	112.8	97.8	120.3	300.8	110	176
	64	47	86	131.0	119.6	136.7	341.8	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

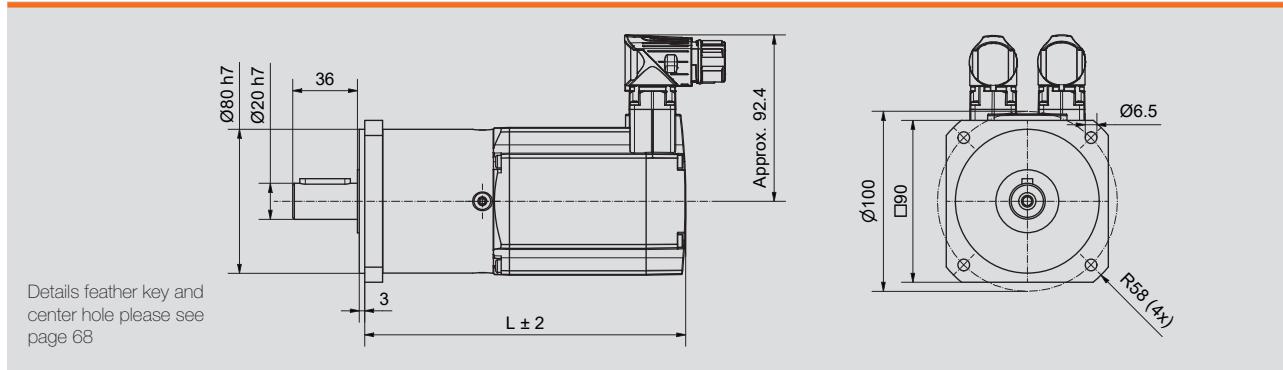
			HMDo8-042-...Eog ¹⁾				HMDo8-057-...Eog ¹⁾				Gear Eog ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	11.5	10.0	12.3	30.9	15.6	12.6	16.8	42.0	39	62
	4	750	1375	15.3	13.3	16.5	41.2	20.8	16.9	22.3	56.1	52	83
	5	600	1100	19.1	16.7	20.6	51.5	26.0	21.1	27.9	70.1	65	104
	7	429	786	26.5	23.1	28.5	71.3	36.0	29.2	38.7	97.1	65	104
	8	375	688	30.3	26.4	32.6	81.5	41.1	33.4	44.2	111.0	50	80
	10	300	550	37.4	32.6	40.3	100.8	50.9	41.3	54.7	137.3	38	61
2-stage	9	333	611	34.0	29.7	36.7	91.7	46.3	37.5	49.8	124.8	117	187
	12	250	458	44.9	39.2	48.4	121.0	61.1	49.5	65.7	164.7	120	192
	15	200	367	56.2	49.0	60.5	151.2	76.3	61.9	82.1	205.9	110	176
	16	188	344	59.9	52.2	64.5	161.3	81.4	66.0	87.6	219.6	120	192
	20	150	275	74.9	65.3	80.6	201.6	101.8	82.6	109.4	274.6	120	192
	25	120	220	92.6	80.8	99.8	249.4	125.9	102.1	135.4	339.6	110	176
	32	94	172	118.6	103.4	127.7	319.2	161.1	130.7	173.3	434.7	120	192
	40	75	138	146.6	127.8	157.9	394.8	-	161.7	214.3	537.7	110	176
	64	47	86	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	
HMD08-024-...E09		without brake	178.5	200.5	4.70		196.0	218.0	5.15
		with brake	227.0	249.0	5.35		244.5	266.5	5.80
HMD08-032-...E09	1-stage	without brake	193.5	215.5	5.10	2-stage	211.0	233.0	5.55
		with brake	242.0	264.0	5.75		259.5	281.5	6.20
HMD08-042-...E09		without brake	208.5	230.5	5.50		226.0	248.0	5.95
		with brake	257.0	279.0	6.15		274.5	296.5	6.60
HMD08-057-...E09		without brake	238.5	260.5	6.60		256.0	278.0	7.05
		with brake	287.0	309.0	7.25		304.5	326.5	7.70

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD08-024-...E09		HMD08-032-...E09		HMD08-042-...E09		HMD08-057-...E09	
i	without brake	with brake						
1-stage	3	1.24E+00		1.57E+00		1.90E+00		2.56E+00
	4	1.01E+00		1.34E+00		1.67E+00		2.33E+00
	5	9.26E-01		1.26E+00		1.59E+00		2.25E+00
	7	8.59E-01		1.19E+00		1.52E+00		2.18E+00
	8	8.45E-01		1.18E+00		1.51E+00		2.17E+00
	10	8.28E-01		1.16E+00		1.49E+00		2.15E+00
2-stage	9	1.08E+00	+2.40E-01	1.41E+00	+2.40E-01	1.74E+00	+2.40E-01	2.40E+00
	12	1.06E+00		1.39E+00		1.72E+00		2.38E+00
	15	1.05E+00		1.38E+00		1.71E+00		2.37E+00
	16	9.11E-01		1.24E+00		1.57E+00		2.23E+00
	20	8.66E-01		1.20E+00		1.53E+00		2.19E+00
	25	8.63E-01		1.19E+00		1.52E+00		2.18E+00
	32	8.25E-01		1.16E+00		1.49E+00		2.15E+00
	40	8.23E-01		1.15E+00		1.48E+00		2.14E+00
	64	8.24E-01		1.15E+00		1.48E+00		2.14E+00

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMD10-039 /-057 /-076 /-105 Gear Eo8



Stall, rated and peak torque - M [Nm]

			HMD10-039...Eo8 ¹⁾				HMD10-057...Eo8 ¹⁾				Gear Eo8 ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	10.6	9.4	11.5	28.8	15.3	11.8	16.8	42.0	39	62
	4	750	1250	14.1	12.5	15.3	38.4	20.4	15.7	22.3	56.1	52	83
	5	600	1000	17.6	15.7	19.1	48.0	25.5	19.6	27.9	70.1	65	104
	7	429	714	24.4	21.7	26.5	66.5	35.3	27.2	38.7	97.1	65	104
	8	375	625	27.9	24.8	30.3	76.0	40.4	31.0	44.2	111.0	50	80
	10	300	500	34.6	30.7	37.4	94.1	49.9	38.4	54.7	137.3	38	61
2-stage	9	333	556	31.4	27.9	34.0	85.6	45.4	34.9	49.8	124.8	117	187
	12	250	417	41.9	37.2	45.4	114.1	60.5	46.6	66.3	166.5	120	192
	15	200	333	51.8	46.1	56.2	141.1	74.9	57.6	82.1	205.9	110	176
	16	188	313	55.3	49.2	59.9	150.5	79.9	61.4	87.6	219.6	120	192
	20	150	250	69.1	61.4	74.9	188.2	99.8	76.8	109.4	274.6	120	192
	25	120	200	85.5	76.0	92.6	232.8	123.5	95.0	135.4	339.6	110	176
	32	94	156	109.4	97.3	118.6	297.9	158.1	121.6	173.3	434.7	120	192
	40	75	125	135.4	120.3	146.6	368.5	-	150.4	214.3	537.7	110	176
	64	47	78	-	-	-	-	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

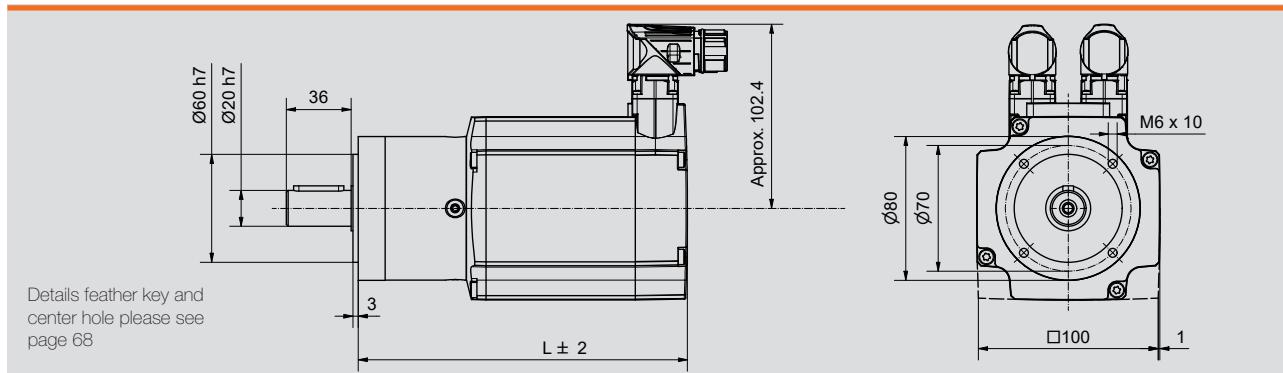
			HMD10-076...Eo8 ¹⁾				HMD10-105...Eo8 ¹⁾				Gear Eo8 ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	19.1	14.1	22.3	55.9	25.3	16.2	30.9	77.3	39	62
	4	750	1250	25.5	18.8	29.8	74.5	33.7	21.6	41.2	103.1	52	83
	5	600	1000	31.9	23.5	37.2	93.1	42.1	27.0	51.5	128.9	65	104
	7	429	714	44.1	32.6	51.6	129.0	58.4	37.3	71.3	178.6	65	104
	8	375	625	50.4	37.2	59.0	147.4	66.7	42.7	81.5	204.1	50	80
	10	300	500	-	46.1	73.0	182.4	-	52.8	100.8	252.5	38	61
2-stage	9	333	556	56.7	41.9	66.3	165.9	75.1	48.0	91.7	229.6	117	187
	12	250	417	75.7	55.9	88.5	221.2	100.1	64.0	122.2	306.1	120	192
	15	200	333	93.6	69.1	109.4	273.6	123.8	79.2	151.2	378.7	110	176
	16	188	313	99.8	73.7	116.7	291.8	132.1	84.5	161.3	404.0	120	192
	20	150	250	124.8	92.2	145.9	364.8	165.1	105.6	201.6	505.0	120	192
	25	120	200	154.4	114.0	180.5	451.3	-	130.6	249.4	624.6	110	176
	32	94	156	-	145.9	231.0	577.6	-	167.2	319.2	799.5	120	192
	40	75	125	-	-	-	-	-	-	-	-	110	176
	64	47	78	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]	Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]	
HMD10-039...E08		without brake	183.2	204.2	5.90		200.7	221.7	6.40
		with brake	230.2	251.2	6.90		247.7	268.7	7.40
HMD10-057...E08	1-stage	without brake	198.2	219.2	6.40	2-stage	215.7	236.7	6.90
		with brake	245.2	266.2	7.40		262.7	283.7	7.90
HMD10-076...E08		without brake	213.2	234.2	6.90		230.7	251.7	7.40
		with brake	260.2	281.2	7.90		277.7	298.7	8.40
HMD10-105...E08		without brake	243.2	264.2	7.90		260.7	281.7	8.40
		with brake	290.2	311.2	8.90		307.7	328.7	9.40

Moment of inertia ⁵⁾ - J_1 [kg·cm²]

	HMD10-039...E08		HMD10-057...E08		HMD10-076...E08		HMD10-105...E08	
i	without brake	with brake						
1-stage	3	2.25E+00		3.06E+00		3.88E+00		5.52E+00
	4	2.05E+00		2.86E+00		3.68E+00		5.32E+00
	5	2.02E+00		2.83E+00		3.65E+00		5.29E+00
	7	1.98E+00		2.79E+00		3.61E+00		5.25E+00
	8	1.97E+00		2.78E+00		3.60E+00		5.24E+00
	10	1.96E+00		2.77E+00		3.59E+00		5.23E+00
2-stage	9	2.21E+00		3.02E+00		3.84E+00		5.48E+00
	12	2.19E+00		3.00E+00		3.82E+00		5.46E+00
	15	2.18E+00		2.99E+00		3.81E+00		5.45E+00
	16	2.04E+00		2.85E+00		3.67E+00		5.31E+00
	20	2.00E+00		2.81E+00		3.63E+00		5.27E+00
	25	2.00E+00		2.81E+00		3.63E+00		5.27E+00
	32	1.96E+00		2.77E+00		3.59E+00		5.23E+00
	40	1.96E+00		2.77E+00		3.59E+00		5.23E+00
	64	1.96E+00		2.77E+00		3.59E+00		5.23E+00

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMD10-039 /-057 /-076 /-105

Gear Eog



Stall, rated and peak torque - M [Nm]

			HMD10-039-...Eog ¹⁾				HMD10-057-...Eog ¹⁾				Gear Eog ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	10.6	9.4	11.5	28.8	15.3	11.8	16.8	42.0	39	62
	4	750	1250	14.1	12.5	15.3	38.4	20.4	15.7	22.3	56.1	52	83
	5	600	1000	17.6	15.7	19.1	48.0	25.5	19.6	27.9	70.1	65	104
	7	429	714	24.4	21.7	26.5	66.5	35.3	27.2	38.7	97.1	65	104
	8	375	625	27.9	24.8	30.3	76.0	40.4	31.0	44.2	111.0	50	80
	10	300	500	34.6	30.7	37.4	94.1	49.9	38.4	54.7	137.3	38	61
2-stage	9	333	556	31.4	27.9	34.0	85.6	45.4	34.9	49.8	124.8	117	187
	12	250	417	41.5	36.9	44.9	112.9	59.9	46.1	65.7	164.7	120	192
	15	200	333	51.8	46.1	56.2	141.1	74.9	57.6	82.1	205.9	110	176
	16	188	313	55.3	49.2	59.9	150.5	79.9	61.4	87.6	219.6	120	192
	20	150	250	69.1	61.4	74.9	188.2	99.8	76.8	109.4	274.6	120	192
	25	120	200	85.5	76.0	92.6	232.8	123.5	95.0	135.4	339.6	110	176
	32	94	156	109.4	97.3	118.6	297.9	158.1	121.6	173.3	434.7	120	192
	40	75	125	135.4	120.3	146.6	368.5	-	150.4	214.3	537.7	110	176
	64	47	78	-	-	-	-	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

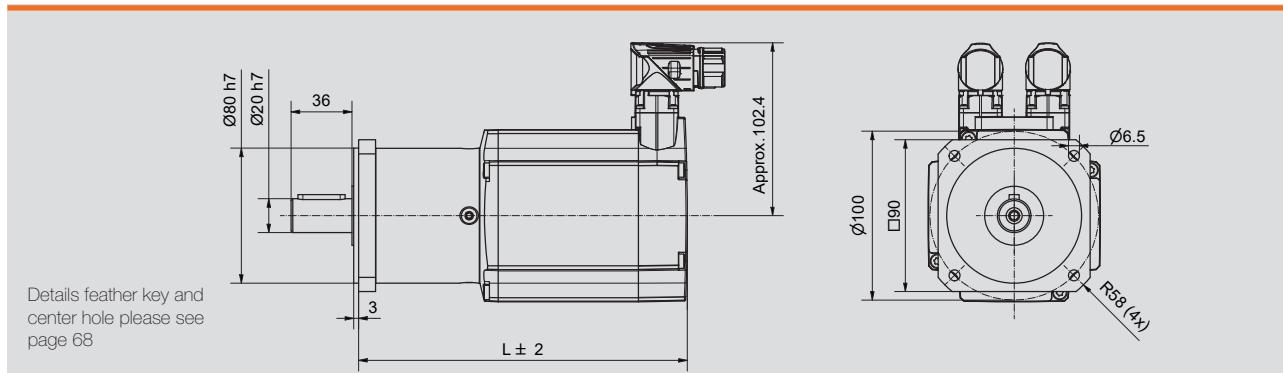
			HMD10-076-...Eog ¹⁾				HMD10-105-...Eog ¹⁾				Gear Eog ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	19.1	14.1	22.3	55.9	25.3	16.2	30.9	77.3	39	62
	4	750	1250	25.5	18.8	29.8	74.5	33.7	21.6	41.2	103.1	52	83
	5	600	1000	31.9	23.5	37.2	93.1	42.1	27.0	51.5	128.9	65	104
	7	429	714	44.1	32.6	51.6	129.0	58.4	37.3	71.3	178.6	65	104
	8	375	625	50.4	37.2	59.0	147.4	66.7	42.7	81.5	204.1	50	80
	10	300	500	-	46.1	73.0	182.4	-	52.8	100.8	252.5	38	61
2-stage	9	333	556	56.7	41.9	66.3	165.9	75.1	48.0	91.7	229.6	117	187
	12	250	417	74.9	55.3	87.6	218.9	99.1	63.4	121.0	303.0	120	192
	15	200	333	93.6	69.1	109.4	273.6	123.8	79.2	151.2	378.7	110	176
	16	188	313	99.8	73.7	116.7	291.8	132.1	84.5	161.3	404.0	120	192
	20	150	250	124.8	92.2	145.9	364.8	165.1	105.6	201.6	505.0	120	192
	25	120	200	154.4	114.0	180.5	451.3	-	130.6	249.4	624.6	110	176
	32	94	156	-	145.9	231.0	577.6	-	167.2	319.2	799.5	120	192
	40	75	125	-	-	-	-	-	-	-	-	110	176
	64	47	78	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]	Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]	
HMD10-039...E09		without brake	194.7	215.7	6.70		212.2	233.2	7.15
		with brake	241.7	262.7	7.70		259.2	280.2	8.15
HMD10-057...E09	1-stage	without brake	209.7	230.7	7.20	2-stage	227.2	248.2	7.65
		with brake	256.7	277.7	8.20		274.2	295.2	8.65
HMD10-076...E09		without brake	224.7	245.7	7.70		242.2	263.2	8.15
		with brake	271.7	292.7	8.70		289.2	310.2	9.15
HMD10-105...E09		without brake	254.7	275.7	8.70		272.2	293.2	9.15
		with brake	301.7	322.7	9.70		319.2	340.2	10.15

Moment of inertia ⁵⁾ - J_1 [kg·cm²]

		HMD10-039...E09		HMD10-057...E09		HMD10-076...E09		HMD10-105...E09	
i		without brake	with brake						
1-stage	3	2.38E+00		3.19E+00		4.01E+00		5.65E+00	
	4	2.15E+00		2.96E+00		3.78E+00		5.42E+00	
	5	2.07E+00		2.88E+00		3.70E+00		5.34E+00	
	7	2.00E+00		2.81E+00		3.63E+00		5.27E+00	
	8	1.99E+00		2.80E+00		3.62E+00		5.26E+00	
	10	1.97E+00		2.78E+00		3.60E+00		5.24E+00	
2-stage	9	2.22E+00	+6.80E-01	3.03E+00	+6.80E-01	3.85E+00	+6.80E-01	5.49E+00	+6.80E-01
	12	2.20E+00		3.01E+00		3.83E+00		5.47E+00	
	15	2.19E+00		3.00E+00		3.82E+00		5.46E+00	
	16	2.05E+00		2.86E+00		3.68E+00		5.32E+00	
	20	2.01E+00		2.82E+00		3.64E+00		5.28E+00	
	25	2.00E+00		2.81E+00		3.63E+00		5.27E+00	
	32	1.97E+00		2.78E+00		3.60E+00		5.24E+00	
	40	1.96E+00		2.77E+00		3.59E+00		5.23E+00	
	64	1.96E+00		2.77E+00		3.59E+00		5.23E+00	

1) Data calculated with a gear efficiency grade defined at $n_g=1000$ rpm and the gear rated torque and a reference temperature of 70°C.

2) Data refer to an output shaft speed of $n_{out}=100$ rpm and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 V_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

Motor type HMD10-039 /-057 /-076 /-105

Gear E10



Stall, rated and peak torque - M [Nm]

			HMD10-039-...E10 ¹⁾				HMD10-057-...E10 ¹⁾				Gear E10 ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,5000\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	10.6	9.4	11.5	28.8	15.3	11.8	16.8	42.0	72	115
	4	750	1250	14.1	12.5	15.3	38.4	20.4	15.7	22.3	56.1	96	153.5
	5	600	1000	17.6	15.7	19.1	48.0	25.5	19.6	27.9	70.1	120	192
	7	429	714	24.4	21.7	26.5	66.5	35.3	27.2	38.7	97.1	135	216
	8	375	625	27.9	24.8	30.3	76.0	40.4	31.0	44.2	111.0	120	192
	10	300	500	34.9	31.0	37.8	95.1	50.4	38.8	55.3	138.7	95	152
2-stage	9	333	556	31.4	27.9	34.0	85.6	45.4	34.9	49.8	124.8	210	336
	12	250	417	41.5	36.9	44.9	112.9	59.9	46.1	65.7	164.7	260	416
	15	200	333	51.8	46.1	56.2	141.1	74.9	57.6	82.1	205.9	230	368
	16	188	313	55.3	49.2	59.9	150.5	79.9	61.4	87.6	219.6	260	416
	20	150	250	69.1	61.4	74.9	188.2	99.8	76.8	109.4	274.6	260	416
	25	120	200	85.5	76.0	92.6	232.8	123.5	95.0	135.4	339.6	230	368
	32	94	156	109.4	97.3	118.6	297.9	158.1	121.6	173.3	434.7	260	416
	40	75	125	135.4	120.3	146.6	368.5	195.5	150.4	214.3	537.7	230	368
	64	47	78	205.1	182.3	222.1	558.2	-	-	-	-	120	192

Stall, rated and peak torque - M [Nm]

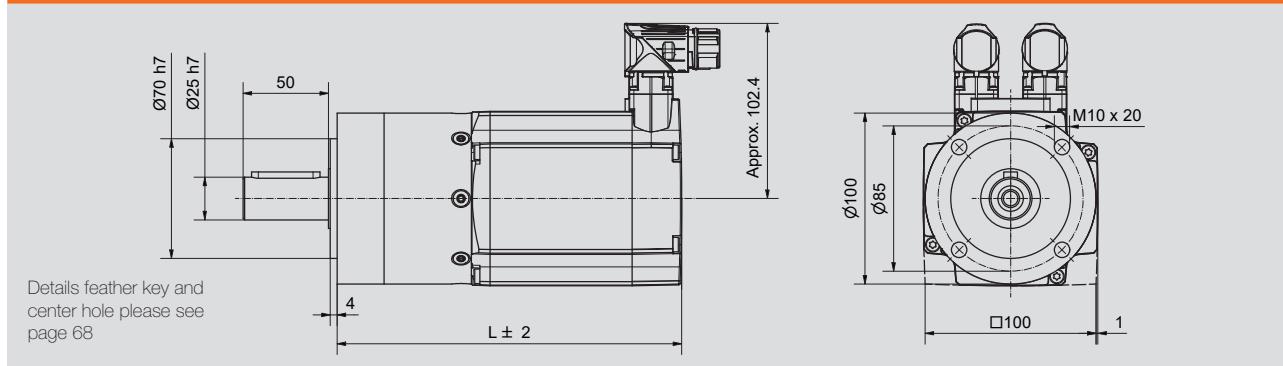
			HMD10-076-...E10 ¹⁾				HMD10-105-...E10 ¹⁾				Gear E10 ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,5000\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	19.1	14.1	22.3	55.9	25.3	16.2	30.9	77.3	72	115
	4	750	1250	25.5	18.8	29.8	74.5	33.7	21.6	41.2	103.1	96	153.5
	5	600	1000	31.9	23.5	37.2	93.1	42.1	27.0	51.5	128.9	120	192
	7	429	714	44.1	32.6	51.6	129.0	58.4	37.3	71.3	178.6	135	216
	8	375	625	50.4	37.2	59.0	147.4	66.7	42.7	81.5	204.1	120	192
	10	300	500	63.1	46.6	73.7	184.3	83.4	53.4	101.9	255.1	95	152
2-stage	9	333	556	56.7	41.9	66.3	165.9	75.1	48.0	91.7	229.6	210	336
	12	250	417	74.9	55.3	87.6	218.9	99.1	63.4	121.0	303.0	260	416
	15	200	333	93.6	69.1	109.4	273.6	123.8	79.2	151.2	378.7	230	368
	16	188	313	99.8	73.7	116.7	291.8	132.1	84.5	161.3	404.0	260	416
	20	150	250	124.8	92.2	145.9	364.8	165.1	105.6	201.6	505.0	260	416
	25	120	200	154.4	114.0	180.5	451.3	204.3	130.6	249.4	624.6	230	368
	32	94	156	197.6	145.9	231.0	577.6	261.4	167.2	319.2	799.5	260	416
	40	75	125	244.4	180.5	285.8	714.4	323.4	206.8	394.8	988.9	230	368
	64	47	78	-	-	-	-	-	-	-	-	120	192

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]
HMD10-039-...E10		without brake	201.5	222.5		229.5	250.5	8.70
		with brake	248.5	269.5		276.5	297.5	9.70
HMD10-057-...E10	1-stage	without brake	216.5	237.5		244.5	265.5	9.20
		with brake	263.5	284.5		291.5	312.5	10.20
HMD10-076-...E10		without brake	231.5	252.5		259.5	280.5	9.70
		with brake	278.5	299.5		306.5	327.5	10.70
HMD10-105-...E10		without brake	261.5	282.5		289.5	310.5	10.70
		with brake	308.5	329.5		336.5	357.5	11.70

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

		HMD10-039-...E10		HMD10-057-...E10		HMD10-076-...E10		HMD10-105-...E10	
	i	without brake	with brake						
1-stage	3	2.98E+00		3.79E+00		4.61E+00		6.25E+00	
	4	2.45E+00		3.26E+00		4.08E+00		5.72E+00	
	5	2.25E+00		3.06E+00		3.88E+00		5.52E+00	
	7	2.08E+00		2.89E+00		3.71E+00		5.35E+00	
	8	2.05E+00		2.86E+00		3.68E+00		5.32E+00	
	10	1.99E+00		2.80E+00		3.62E+00		5.26E+00	
2-stage	9	2.90E+00	+6.80E-01	3.71E+00	+6.80E-01	4.53E+00	+6.80E-01	6.17E+00	+6.80E-01
	12	2.84E+00		3.65E+00		4.47E+00		6.11E+00	
	15	2.82E+00		3.63E+00		4.45E+00		6.09E+00	
	16	2.30E+00		3.11E+00		3.93E+00		5.57E+00	
	20	2.19E+00		3.00E+00		3.82E+00		5.46E+00	
	25	2.18E+00		2.99E+00		3.81E+00		5.45E+00	
	32	2.04E+00		2.85E+00		3.67E+00		5.31E+00	
	40	2.03E+00		2.84E+00		3.66E+00		5.30E+00	
	64	2.03E+00		2.84E+00		3.66E+00		5.30E+00	

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the geared torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

**■ Motor type HMD13-113 /-190 /-245
Gear E10**



Stall, rated and peak torque - M [Nm]

				HMD13-133-...E10 ¹⁾				HMD13-190-...E10 ¹⁾				Gear E10 ²⁾	
	i	$\eta_{out, 2000 \text{ rpm}}^3$	$\eta_{out, 3600 \text{ rpm}}^3$	$M_{n_r, 2000 \text{ rpm}}$	$M_{n_r, 3600 \text{ rpm}}$	M_o	M_{max}	$M_{n_r, 2000 \text{ rpm}}$	$M_{n_r, 3600 \text{ rpm}}$	M_o	M_{max}	$M_{G, n}$	$M_{G, max}$
1-stage	3	667	1200	33.8	26.5	39.1	97.9	47.0	32.9	55.9	139.7	72	115
	4	500	900	45.1	35.3	52.1	130.5	62.7	43.9	74.5	186.2	96	153.5
	5	400	720	56.4	44.1	65.2	163.2	78.4	54.9	93.1	232.8	120	192
	7	286	514	78.1	61.1	90.3	226.1	108.6	76.0	129.0	322.5	135	216
	8	250	450	89.2	69.8	103.2	258.4	124.2	86.9	147.4	368.6	120	192
	10	200	360	111.6	87.3	129.0	323.0	-	108.6	184.3	460.8	95	152
2-stage	9	222	400	100.4	78.6	116.1	290.7	139.7	97.8	165.9	414.7	210	336
	12	167	300	132.5	103.7	153.2	383.6	184.3	129.0	218.9	547.2	260	416
	15	133	240	165.6	129.6	191.5	479.5	230.4	161.3	273.6	684.0	230	368
	16	125	225	176.6	138.2	204.3	511.5	245.8	172.0	291.8	729.6	260	416
	20	100	180	220.8	172.8	255.4	639.4	307.2	215.0	364.8	912.0	260	416
	25	80	144	273.1	213.8	315.9	790.9	-	266.0	451.3	1128.1	230	368
	32	63	113	349.6	273.6	404.3	1012.3	-	340.5	577.6	1444.0	260	416
	40	50	90	-	338.4	500.1	1252.1	-	-	-	-	230	368
	64	31	56	-	-	-	-	-	-	-	-	120	192

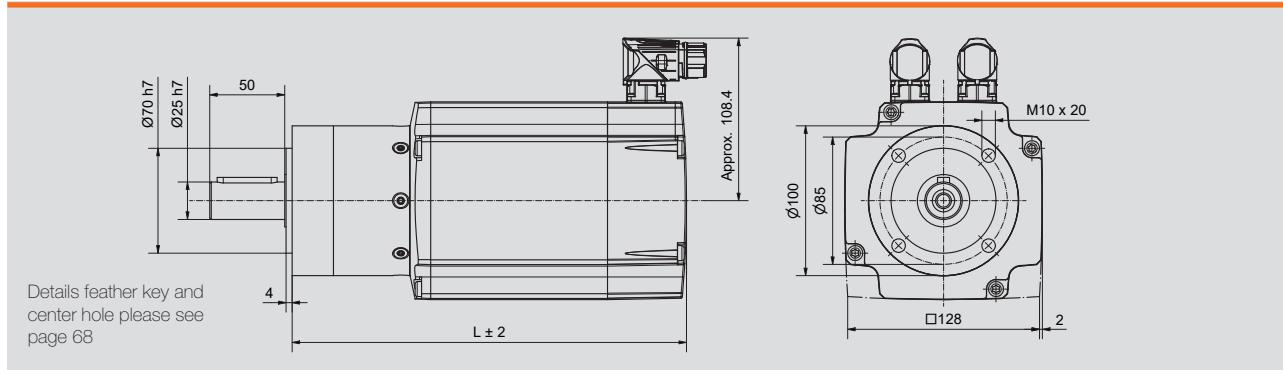
Stall, rated and peak torque - M [Nm]

				HMD13-245-...E10 ¹⁾				Gear E10 ²⁾	
	i	$\eta_{out, 2000 \text{ rpm}}^3$	$\eta_{out, 3600 \text{ rpm}}^3$	$M_{n_r, 2000 \text{ rpm}}$	$M_{n_r, 3600 \text{ rpm}}$	M_o	M_{max}	$M_{G, n}$	$M_{G, max}$
1-stage	3	667	1200	60.3	39.1	72.0	180.2	72	115
	4	500	900	80.4	52.1	96.0	240.3	96	153.5
	5	400	720	100.5	65.2	120.1	300.4	120	192
	7	286	514	139.2	90.3	166.4	416.2	135	216
	8	250	450	159.1	103.2	190.1	475.7	120	192
	10	200	360	-	129.0	237.7	594.6	95	152
2-stage	9	222	400	179.0	116.1	213.9	535.1	210	336
	12	167	300	236.2	153.2	282.2	706.2	260	416
	15	133	240	295.2	191.5	352.8	882.7	230	368
	16	125	225	314.9	204.3	376.3	941.6	260	416
	20	100	180	-	255.4	470.4	1177.0	260	416
	25	80	144	-	315.9	581.9	1455.9	230	368
	32	63	113	-	-	-	-	260	416
	40	50	90	-	-	-	-	230	368
	64	31	56	-	-	-	-	120	192

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]
HMD13-133-...E10		without brake	-	263.3		-	291.3	12.60
		with brake	-	301.0		-	329.0	13.70
HMD13-190-...E10	1-stage	without brake	-	293.3	2-stage	-	321.3	15.20
		with brake	-	331.0		-	359.0	16.30
HMD13-245-...E10		without brake	-	323.3		-	351.3	17.70
		with brake	-	384.3		-	412.3	20.70

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD13-133-...E10		HMD13-190-...E10		HMD13-245-...E10	
i	without brake	with brake	without brake	with brake	without brake	with brake
1-stage	3	9.24E+00		1.30E+01		1.68E+01
	4	8.71E+00		1.25E+01		1.63E+01
	5	8.51E+00		1.23E+01		1.61E+01
	7	8.34E+00		1.21E+01		1.59E+01
	8	8.31E+00		1.21E+01		1.59E+01
	10	8.25E+00		1.21E+01		1.59E+01
2-stage	9	9.16E+00	+1.90E+00	1.30E+01	+1.90E+00	1.68E+01
	12	9.10E+00		1.29E+01		1.67E+01
	15	9.08E+00		1.29E+01		1.67E+01
	16	8.56E+00		1.24E+01		1.62E+01
	20	8.45E+00		1.22E+01		1.60E+01
	25	8.44E+00		1.22E+01		1.60E+01
	32	8.30E+00		1.21E+01		1.59E+01
	40	8.29E+00		1.21E+01		1.59E+01
	64	8.29E+00		1.21E+01		1.59E+01

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

**■ Motor type HMDo6-011 /-019 /-026
Gear Po7**



Stall, rated and peak torque - M [Nm]

				HMDo6-011...Po7 ¹⁾				HMDo6-019...Po7 ¹⁾				Gear Po7 ²⁾	
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,6000\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	2000	2.9	2.9	2.9	7.4	5.0	4.3	5.6	14.1	17	27.5
	4	750	1500	3.9	3.9	3.9	9.8	6.7	5.7	7.4	18.8	23	37
	5	600	1200	4.9	4.9	4.9	12.1	8.2	7.0	9.2	23.3	29	46
	7	429	857	6.8	6.8	6.8	17.0	11.5	9.8	12.9	32.6	25	40
	8	375	750	7.7	7.7	7.7	19.2	13.1	11.1	14.6	36.9	18	29
	10	300	600	9.5	9.5	9.5	23.8	16.2	13.8	18.1	45.6	15	24
2-stage	9	333	667	8.6	8.6	8.6	21.6	14.7	12.5	16.4	41.5	33	53
	12	250	500	11.5	11.5	11.5	28.8	19.6	16.7	21.9	55.3	33	53
	15	200	400	14.3	14.3	14.3	35.6	24.2	20.7	27.1	68.4	33	53
	16	188	375	15.2	15.2	15.2	38.0	25.8	22.0	28.9	73.0	33	53
	20	150	300	19.0	19.0	19.0	47.5	32.3	27.6	36.1	91.2	33	53
	25	120	240	23.5	23.5	23.5	58.8	40.0	34.1	44.7	112.8	30	48
	32	94	188	30.1	30.1	30.1	75.2	-	43.6	57.2	144.4	33	53
	40	75	150	37.2	37.2	37.2	93.0	-	-	-	-	30	48
	64	47	94	55.0	55.0	55.0	137.6	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm]

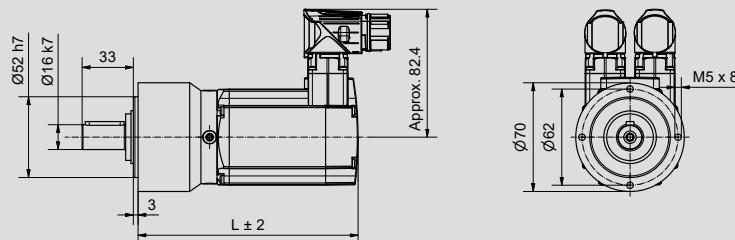
				HMDo6-026...Po7 ¹⁾				Gear Po7 ²⁾	
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,6000\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	2000	7.4	5.9	7.6	19.1	17	27.5
	4	750	1500	9.8	7.8	10.2	25.5	23	37
	5	600	1200	12.1	9.7	12.6	31.5	29	46
	7	429	857	17.0	13.6	17.7	44.1	25	40
	8	375	750	19.2	15.4	20.0	49.9	18	29
	10	300	600	-	19.0	24.7	61.8	15	24
2-stage	9	333	667	21.6	17.3	22.5	56.2	33	53
	12	250	500	28.8	23.0	30.0	74.9	33	53
	15	200	400	35.6	28.5	37.1	92.6	33	53
	16	188	375	38.0	30.4	39.5	98.8	33	53
	20	150	300	47.5	38.0	49.4	123.5	33	53
	25	120	240	-	-	-	-	30	48
	32	94	188	-	-	-	-	33	53
	40	75	150	-	-	-	-	30	48
	64	47	94	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Details feather key and center hole please see page 68

Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	
HMD06-011-...P07		without brake	142.0	160.0	2.40		155.0	173.0	2.70
		with brake	181.5	199.5	2.75		194.5	212.5	3.05
HMD06-019-...P07	1-stage	without brake	167.0	185.0	2.80		180.0	198.0	3.10
		with brake	206.5	224.5	3.15		219.5	237.5	3.45
HMD06-026-...P07		without brake	197.0	215.0	3.20		210.0	228.0	3.50
		with brake	236.5	254.5	3.55		249.5	267.5	3.85

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD06-011-...P07		HMD06-019-...P07		HMD06-026-...P07	
i	without brake	with brake	without brake	with brake	without brake	with brake
1-stage	3	3.81E-01		6.02E-01		8.24E-01
	4	3.24E-01		5.45E-01		7.67E-01
	5	3.03E-01		5.24E-01		7.46E-01
	7	2.85E-01		5.06E-01		7.28E-01
	8	2.81E-01		5.02E-01		7.24E-01
	10	2.76E-01		4.97E-01		7.19E-01
2-stage	9	3.33E-01		5.54E-01		7.76E-01
	12	3.28E-01		5.49E-01		7.71E-01
	15	2.85E-01		5.06E-01		7.28E-01
	16	2.94E-01		5.15E-01		7.37E-01
	20	2.84E-01		5.05E-01		7.27E-01
	25	2.82E-01		5.03E-01		7.25E-01
	32	2.74E-01		4.95E-01		7.17E-01
	40	2.74E-01		4.95E-01		7.17E-01
	64	2.73E-01		4.94E-01		7.16E-01

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

Motor type HMDo8-024 /-032 /-042 /-057

Gear Po7



Stall, rated and peak torque - M [Nm]

			HMDo8-024-...Po7 ¹⁾				HMDo8-032-...Po7 ¹⁾				Gear Po7 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	6.8	6.2	7.1	17.6	8.8	7.6	9.4	23.5	17	27.5
	4	750	1375	9.0	8.2	9.4	23.5	11.8	10.2	12.5	31.4	23	37
	5	600	1100	11.2	10.2	11.6	29.1	14.6	12.6	15.5	38.8	29	46
	7	429	786	15.6	14.3	16.3	40.7	20.4	17.7	21.7	54.3	25	40
	8	375	688	17.7	16.1	18.4	46.1	23.0	20.0	24.6	61.4	18	29
	10	300	550	21.9	20.0	22.8	57.0	-	-	-	-	15	24
2-stage	9	333	611	19.9	18.1	20.7	51.8	25.9	22.5	27.6	69.1	33	53
	12	250	458	26.5	24.2	27.6	69.1	34.6	30.0	36.9	92.2	33	53
	15	200	367	32.8	29.9	34.2	85.5	42.8	37.1	45.6	114.0	33	53
	16	188	344	35.0	31.9	36.5	91.2	45.6	39.5	48.6	121.6	33	53
	20	150	275	43.7	39.9	45.6	114.0	-	49.4	60.8	152.0	33	53
	25	120	220	-	-	-	-	-	-	-	-	30	48
	32	94	172	-	-	-	-	-	-	-	-	33	53
	40	75	138	-	-	-	-	-	-	-	-	30	48
	64	47	86	-	-	-	-	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm]

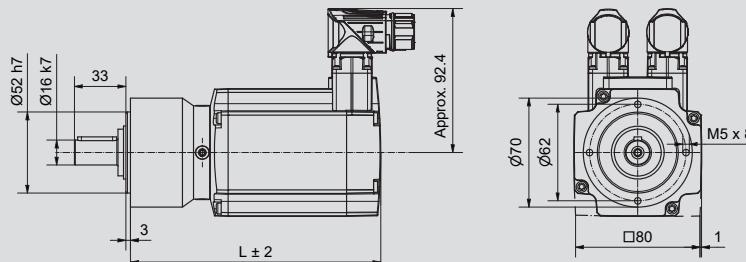
			HMDo8-042-...Po7 ¹⁾				HMDo8-057-...Po7 ¹⁾				Gear Po7 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	11.5	10.0	12.3	30.9	15.6	12.6	16.8	42.0	17	27.5
	4	750	1375	15.3	13.3	16.5	41.2	20.8	16.9	22.3	56.1	23	37
	5	600	1100	18.9	16.5	20.4	50.9	25.7	20.9	27.6	69.4	29	46
	7	429	786	26.5	23.1	28.5	71.3	36.0	29.2	38.7	97.1	25	40
	8	375	688	-	26.1	32.3	80.6	-	-	-	-	18	29
	10	300	550	-	-	-	-	-	-	-	-	15	24
2-stage	9	333	611	33.7	29.4	36.3	90.7	45.8	37.2	49.2	123.6	33	53
	12	250	458	44.9	39.2	48.4	121.0	-	-	-	-	33	53
	15	200	367	-	48.5	59.9	149.6	-	-	-	-	33	53
	16	188	344	-	-	-	-	-	-	-	-	33	53
	20	150	275	-	-	-	-	-	-	-	-	33	53
	25	120	220	-	-	-	-	-	-	-	-	30	48
	32	94	172	-	-	-	-	-	-	-	-	33	53
	40	75	138	-	-	-	-	-	-	-	-	30	48
	64	47	86	-	-	-	-	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Details feather key and center hole please see page 68

Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]
HMD08-024-...P07		without brake	160.8	182.8		173.8	195.8	4.00
		with brake	209.3	231.3		222.3	244.3	4.65
HMD08-032-...P07	1-stage	without brake	175.8	197.8		188.8	210.8	4.40
		with brake	224.3	246.3		237.3	259.3	5.05
HMD08-042-...P07		without brake	190.8	212.8		203.8	225.8	4.80
		with brake	239.3	261.3		252.3	274.3	5.45
HMD08-057-...P07		without brake	220.8	242.8		233.8	255.8	5.90
		with brake	269.3	291.3		282.3	304.3	6.55

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

		HMD08-024-...P07		HMD08-032-...P07		HMD08-042-...P07		HMD08-057-...P07	
	i	without brake	with brake						
1-stage	3	9.13E-01		1.24E+00		1.57E+00		2.23E+00	
	4	8.56E-01		1.19E+00		1.52E+00		2.18E+00	
	5	8.35E-01		1.17E+00		1.50E+00		2.16E+00	
	7	8.17E-01		1.15E+00		1.48E+00		2.14E+00	
	8	8.13E-01		1.14E+00		1.47E+00		2.13E+00	
	10	8.08E-01		1.14E+00		1.47E+00		2.13E+00	
2-stage	9	8.65E-01	+2.40E-01	1.20E+00	+2.40E-01	1.53E+00	+2.40E-01	2.19E+00	+2.40E-01
	12	8.60E-01		1.19E+00		1.52E+00		2.18E+00	
	15	8.17E-01		1.15E+00		1.48E+00		2.14E+00	
	16	8.26E-01		1.16E+00		1.49E+00		2.15E+00	
	20	8.16E-01		1.15E+00		1.48E+00		2.14E+00	
	25	8.14E-01		1.14E+00		1.47E+00		2.13E+00	
	32	8.06E-01		1.14E+00		1.47E+00		2.13E+00	
	40	8.06E-01		1.14E+00		1.47E+00		2.13E+00	
	64	8.05E-01		1.14E+00		1.47E+00		2.13E+00	

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMDo8-024 /-032 /-042 /-057

Gear Pog



Stall, rated and peak torque - M [Nm]

			HMDo8-024-...Pog ¹⁾				HMDo8-032-...Pog ¹⁾				Gear Pog ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	6.8	6.2	7.1	17.6	8.8	7.6	9.4	23.5	39	62
	4	750	1375	9.0	8.2	9.4	23.5	11.8	10.2	12.5	31.4	52	83
	5	600	1100	11.3	10.3	11.8	29.4	14.7	12.7	15.7	39.2	65	104
	7	429	786	15.6	14.3	16.3	40.7	20.4	17.7	21.7	54.3	65	104
	8	375	688	17.8	16.3	18.6	46.6	23.3	20.2	24.8	62.1	50	80
	10	300	550	22.1	20.2	23.0	57.6	28.8	25.0	30.7	76.8	38	61
2-stage	9	333	611	20.1	18.3	21.0	52.4	26.2	22.7	27.9	69.8	97	155
	12	250	458	26.5	24.2	27.6	69.1	34.6	30.0	36.9	92.2	90	144
	15	200	367	33.1	30.2	34.6	86.4	43.2	37.4	46.1	115.2	82	131
	16	188	344	35.3	32.3	36.9	92.2	46.1	39.9	49.2	122.9	90	144
	20	150	275	43.7	39.9	45.6	114.0	57.0	49.4	60.8	152.0	90	144
	25	120	220	54.6	49.9	57.0	142.5	71.3	61.8	76.0	190.0	82	131
	32	94	172	69.2	63.2	72.2	180.5	90.2	78.2	96.3	240.6	90	144
	40	75	138	86.5	79.0	90.2	225.6	112.8	97.8	120.3	300.8	82	131
	64	47	86	131.0	119.6	136.7	341.8	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

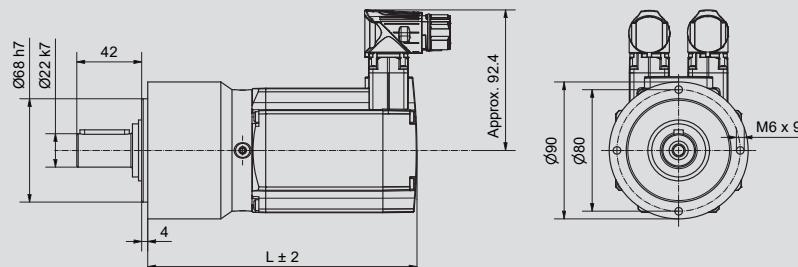
			HMDo8-042-...Pog ¹⁾				HMDo8-057-...Pog ¹⁾				Gear Pog ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	11.5	10.0	12.3	30.9	15.6	12.6	16.8	42.0	39	62
	4	750	1375	15.3	13.3	16.5	41.2	20.8	16.9	22.3	56.1	52	83
	5	600	1100	19.1	16.7	20.6	51.5	26.0	21.1	27.9	70.1	65	104
	7	429	786	26.5	23.1	28.5	71.3	36.0	29.2	38.7	97.1	65	104
	8	375	688	30.3	26.4	32.6	81.5	41.1	33.4	44.2	111.0	50	80
	10	300	550	37.4	32.6	40.3	100.8	50.9	41.3	54.7	137.3	38	61
2-stage	9	333	611	34.0	29.7	36.7	91.7	46.3	37.5	49.8	124.8	97	155
	12	250	458	44.9	39.2	48.4	121.0	61.1	49.5	65.7	164.7	90	144
	15	200	367	56.2	49.0	60.5	151.2	76.3	61.9	82.1	205.9	82	131
	16	188	344	59.9	52.2	64.5	161.3	81.4	66.0	87.6	219.6	90	144
	20	150	275	74.1	64.6	79.8	199.5	100.7	81.7	108.3	271.7	90	144
	25	120	220	92.6	80.8	99.8	249.4	-	102.1	135.4	339.6	82	131
	32	94	172	117.3	102.3	126.3	315.8	-	129.3	171.5	430.1	90	144
	40	75	138	-	-	-	-	-	-	-	-	82	131
	64	47	86	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Details feather key and center hole please see page 68

Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	
HMD08-024-...P09		without brake	174.5	196.5	5.10		192.5	214.5	5.70
		with brake	223.0	245.0	5.75		241.0	263.0	6.35
HMD08-032-...P09	1-stage	without brake	189.5	211.5	5.50	2-stage	207.5	229.5	6.10
		with brake	238.0	260.0	6.15		256.0	278.0	6.75
HMD08-042-...P09		without brake	204.5	226.5	5.90		222.5	244.5	6.50
		with brake	253.0	275.0	6.55		271.0	293.0	7.15
HMD08-057-...P09		without brake	234.5	256.5	7.00		252.5	274.5	7.60
		with brake	283.0	305.0	7.65		301.0	323.0	8.25

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD08-024-...P09		HMD08-032-...P09		HMD08-042-...P09		HMD08-057-...P09	
i	without brake	with brake						
1-stage	3	1.25E+00		1.58E+00		1.91E+00		2.57E+00
	4	1.01E+00		1.34E+00		1.67E+00		2.33E+00
	5	9.34E-01		1.26E+00		1.59E+00		2.25E+00
	7	8.67E-01		1.20E+00		1.53E+00		2.19E+00
	8	8.51E-01		1.18E+00		1.51E+00		2.17E+00
	10	8.32E-01		1.16E+00		1.49E+00		2.15E+00
2-stage	9	1.08E+00	+2.40E-01	1.41E+00	+2.40E-01	1.74E+00	+2.40E-01	2.40E+00
	12	1.06E+00		1.39E+00		1.72E+00		2.38E+00
	15	1.05E+00		1.38E+00		1.71E+00		2.37E+00
	16	9.09E-01		1.24E+00		1.57E+00		2.23E+00
	20	8.67E-01		1.20E+00		1.53E+00		2.19E+00
	25	8.64E-01		1.19E+00		1.52E+00		2.18E+00
	32	8.25E-01		1.16E+00		1.49E+00		2.15E+00
	40	8.24E-01		1.15E+00		1.48E+00		2.14E+00
	64	8.24E-01		1.15E+00		1.48E+00		2.14E+00

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMD10-039 /-057 /-076 /-105

Gear Pog



Stall, rated and peak torque - M [Nm]

			HMD10-039-...Pog ¹⁾				HMD10-057-...Pog ¹⁾				Gear Pog ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	10.6	9.4	11.5	28.8	15.3	11.8	16.8	42.0	39	62
	4	750	1250	14.1	12.5	15.3	38.4	20.4	15.7	22.3	56.1	52	83
	5	600	1000	17.6	15.7	19.1	48.0	25.5	19.6	27.9	70.1	65	104
	7	429	714	24.4	21.7	26.5	66.5	35.3	27.2	38.7	97.1	65	104
	8	375	625	27.9	24.8	30.3	76.0	40.4	31.0	44.2	111.0	50	80
	10	300	500	34.6	30.7	37.4	94.1	49.9	38.4	54.7	137.3	38	61
2-stage	9	333	556	31.4	27.9	34.0	85.6	45.4	34.9	49.8	124.8	97	155
	12	250	417	41.5	36.9	44.9	112.9	59.9	46.1	65.7	164.7	90	144
	15	200	333	51.8	46.1	56.2	141.1	74.9	57.6	82.1	205.9	82	131
	16	188	313	55.3	49.2	59.9	150.5	79.9	61.4	87.6	219.6	90	144
	20	150	250	68.4	60.8	74.1	186.2	98.8	76.0	108.3	271.7	90	144
	25	120	200	85.5	76.0	92.6	232.8	-	95.0	135.4	339.6	82	131
	32	94	156	108.3	96.3	117.3	294.8	-	120.3	171.5	430.1	90	144
	40	75	125	-	120.3	146.6	368.5	-	-	-	-	82	131
	64	47	78	-	-	-	-	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

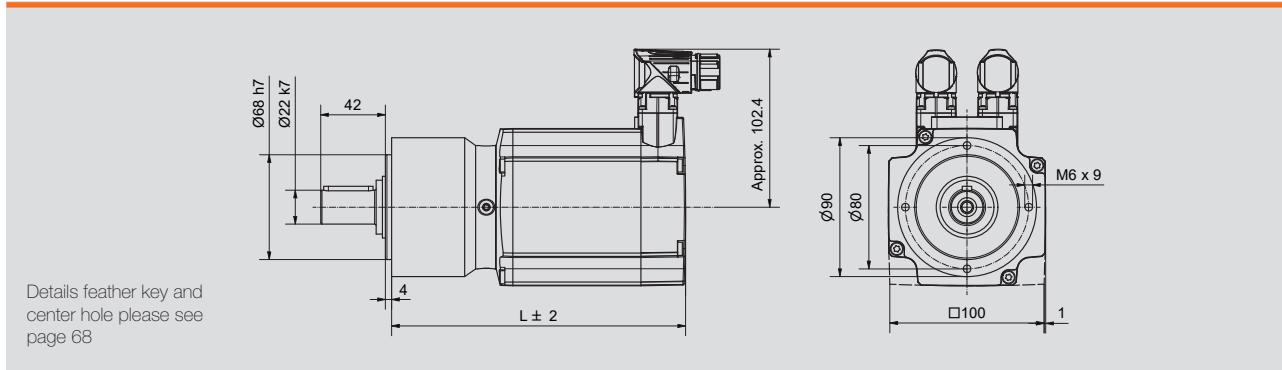
			HMD10-076-...Pog ¹⁾				HMD10-105-...Pog ¹⁾				Gear Pog ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	19.1	14.1	22.3	55.9	25.3	16.2	30.9	77.3	39	62
	4	750	1250	25.5	18.8	29.8	74.5	33.7	21.6	41.2	103.1	52	83
	5	600	1000	31.9	23.5	37.2	93.1	42.1	27.0	51.5	128.9	65	104
	7	429	714	44.1	32.6	51.6	129.0	58.4	37.3	71.3	178.6	65	104
	8	375	625	50.4	37.2	59.0	147.4	66.7	42.7	81.5	204.1	50	80
	10	300	500	-	46.1	73.0	182.4	-	52.8	100.8	252.5	38	61
2-stage	9	333	556	56.7	41.9	66.3	165.9	75.1	48.0	91.7	229.6	97	155
	12	250	417	74.9	55.3	87.6	218.9	99.1	63.4	121.0	303.0	90	144
	15	200	333	93.6	69.1	109.4	273.6	-	79.2	151.2	378.7	82	131
	16	188	313	99.8	73.7	116.7	291.8	132.1	84.5	161.3	404.0	90	144
	20	150	250	123.5	91.2	144.4	361.0	-	104.5	199.5	499.7	90	144
	25	120	200	-	114.0	180.5	451.3	-	-	-	-	82	131
	32	94	156	-	-	-	-	-	-	-	-	90	144
	40	75	125	-	-	-	-	-	-	-	-	82	131
	64	47	78	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]
HMD10-039-...P09		without brake	190.7	211.7		208.7	229.7	7.70
		with brake	237.7	258.7		255.7	276.7	8.70
HMD10-057-...P09	1-stage	without brake	205.7	226.7		223.7	244.7	8.20
		with brake	252.7	273.7		270.7	291.7	9.20
HMD10-076-...P09		without brake	220.7	241.7		238.7	259.7	8.70
		with brake	267.7	288.7		285.7	306.7	9.70
HMD10-105-...P09		without brake	250.7	271.7		268.7	289.7	9.70
		with brake	297.7	318.7		315.7	336.7	10.70

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

		HMD10-039-...P09		HMD10-057-...P09		HMD10-076-...P09		HMD10-105-...P09	
	i	without brake	with brake						
1-stage	3	2.39E+00		3.20E+00		4.02E+00		5.66E+00	
	4	2.15E+00		2.96E+00		3.78E+00		5.42E+00	
	5	2.07E+00		2.88E+00		3.70E+00		5.34E+00	
	7	2.01E+00		2.82E+00		3.64E+00		5.28E+00	
	8	1.99E+00		2.80E+00		3.62E+00		5.26E+00	
	10	1.97E+00		2.78E+00		3.60E+00		5.24E+00	
2-stage	9	2.22E+00	+6.80E-01	3.03E+00	+6.80E-01	3.85E+00	+6.80E-01	5.49E+00	+6.80E-01
	12	2.20E+00		3.01E+00		3.83E+00		5.47E+00	
	15	2.19E+00		3.00E+00		3.82E+00		5.46E+00	
	16	2.05E+00		2.86E+00		3.68E+00		5.32E+00	
	20	2.01E+00		2.82E+00		3.64E+00		5.28E+00	
	25	2.00E+00		2.81E+00		3.63E+00		5.27E+00	
	32	1.97E+00		2.78E+00		3.60E+00		5.24E+00	
	40	1.96E+00		2.77E+00		3.59E+00		5.23E+00	
	64	1.96E+00		2.77E+00		3.59E+00		5.23E+00	

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMDo6-011 /-019 /-026

Gear Ho6



Stall, rated and peak torque - M [Nm]

			HMDo6-011...Ho6 ¹⁾				HMDo6-019...Ho6 ¹⁾				Gear Ho6 ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,6000\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	2000	2.9	2.9	2.9	7.2	4.9	4.2	5.5	13.8	17	27.5
	4	750	1500	3.9	3.9	3.9	9.7	6.6	5.6	7.4	18.6	23	37
	5	600	1200	4.9	4.9	4.9	12.1	8.2	7.0	9.2	23.3	29	46
	7	429	857	6.7	6.7	6.7	16.6	11.3	9.6	12.6	31.9	25	40
	8	375	750	7.5	7.5	7.5	18.8	12.8	10.9	14.3	36.1	18	29
	10	300	600	9.2	9.2	9.2	23.0	15.6	13.3	17.5	44.2	15	24
2-stage	9	333	667	8.6	8.6	8.6	21.6	14.7	12.5	16.4	41.5	44	70
	12	250	500	11.4	11.4	11.4	28.5	19.4	16.5	21.7	54.7	44	70
	15	200	400	14.3	14.3	14.3	35.6	24.2	20.7	27.1	68.4	44	70
	16	188	375	15.2	15.2	15.2	38.0	25.8	22.0	28.9	73.0	44	70
	20	150	300	19.0	19.0	19.0	47.5	32.3	27.6	36.1	91.2	44	70
	25	120	240	23.5	23.5	23.5	58.8	40.0	34.1	44.7	112.8	40	64
	32	94	188	30.1	30.1	30.1	75.2	51.1	43.6	57.2	144.4	44	70
	40	75	150	37.2	37.2	37.2	93.0	-	53.9	70.7	178.6	40	64
	64	47	94	54.4	54.4	54.4	136.0	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm] [Nm]

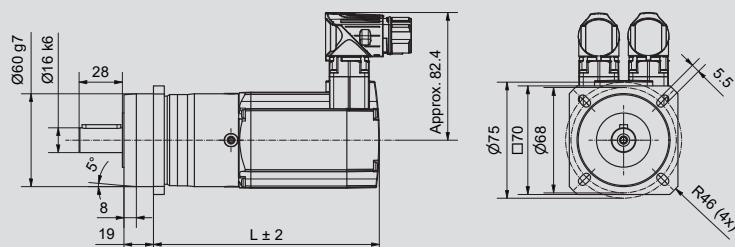
			HMDo6-026...Ho6 ¹⁾				Gear Ho6 ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,6000\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	2000	7.2	5.8	7.5	18.7	17	27.5
	4	750	1500	9.7	7.8	10.1	25.2	23	37
	5	600	1200	12.1	9.7	12.6	31.5	29	46
	7	429	857	16.6	13.3	17.3	43.2	25	40
	8	375	750	18.8	15.0	19.6	48.9	18	29
	10	300	600	-	18.4	23.9	59.8	15	24
2-stage	9	333	667	21.6	17.3	22.5	56.2	44	70
	12	250	500	28.5	22.8	29.6	74.1	44	70
	15	200	400	35.6	28.5	37.1	92.6	44	70
	16	188	375	38.0	30.4	39.5	98.8	44	70
	20	150	300	47.5	38.0	49.4	123.5	44	70
	25	120	240	58.8	47.0	61.1	152.8	40	64
	32	94	188	-	60.2	78.2	195.5	44	70
	40	75	150	-	-	-	-	40	64
	64	47	94	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]		
HMD06-011-...H06	1-stage	without brake	146.0	164.0	2.50	2-stage	158.5	176.5	2.70	
		with brake	185.5	203.5	2.85		198.0	216.0	3.05	
HMD06-019-...H06		without brake	171.0	189.0	2.90		183.5	201.5	3.10	
		with brake	210.5	228.5	3.25		223.0	241.0	3.45	
HMD06-026-...H06		without brake	201.0	219.0	3.30		213.5	231.5	3.50	
		with brake	240.5	258.5	3.65		253.0	271.0	3.85	

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD06-011-...H06		HMD06-019-...H06		HMD06-026-...H06		
i	without brake	with brake	without brake	with brake	without brake	with brake	
1-stage	3	3.85E-01		6.06E-01		8.28E-01	
	4	3.27E-01		5.48E-01		7.70E-01	
	5	3.05E-01		5.26E-01		7.48E-01	
	7	2.85E-01		5.06E-01		7.28E-01	
	8	2.82E-01		5.03E-01		7.25E-01	
	10	2.76E-01		4.97E-01		7.19E-01	
2-stage	9	3.42E-01		5.63E-01		7.85E-01	
	12	3.36E-01		5.57E-01		7.79E-01	
	15	2.88E-01		5.09E-01		7.31E-01	
	16	2.99E-01		5.20E-01		7.42E-01	
	20	2.87E-01		5.08E-01		7.30E-01	
	25	2.86E-01		5.07E-01		7.29E-01	
	32	2.75E-01		4.96E-01		7.18E-01	
	40	2.75E-01		4.96E-01		7.18E-01	
	64	2.75E-01		4.96E-01		7.18E-01	
		+8.90E-02		+8.90E-02		+8.90E-02	

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

Motor type HMDo8-024 /-032 /-042 /-057

Gear Ho6



Stall, rated and peak torque - M [Nm]

			HMDo8-024-...Ho6 ¹⁾				HMDo8-032-...Ho6 ¹⁾				Gear Ho6 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3)$	$\eta_{out,5500 \text{ rpm}}^3)$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	6.6	6.0	6.9	17.3	8.6	7.5	9.2	23.0	17	27.5
	4	750	1375	8.9	8.1	9.3	23.3	11.6	10.1	12.4	31.0	23	37
	5	600	1100	11.2	10.2	11.6	29.1	14.6	12.6	15.5	38.8	29	46
	7	429	786	15.3	14.0	16.0	39.9	20.0	17.3	21.3	53.2	25	40
	8	375	688	17.3	15.8	18.0	45.1	22.6	19.6	24.1	60.2	18	29
	10	300	550	21.2	19.3	22.1	55.2	-	-	-	-	15	24
2-stage	9	333	611	19.9	18.1	20.7	51.8	25.9	22.5	27.6	69.1	44	70
	12	250	458	26.2	23.9	27.4	68.4	34.2	29.6	36.5	91.2	44	70
	15	200	367	32.8	29.9	34.2	85.5	42.8	37.1	45.6	114.0	44	70
	16	188	344	35.0	31.9	36.5	91.2	45.6	39.5	48.6	121.6	44	70
	20	150	275	43.7	39.9	45.6	114.0	57.0	49.4	60.8	152.0	44	70
	25	120	220	54.1	49.4	56.4	141.0	-	-	-	-	40	64
	32	94	172	-	63.2	72.2	180.5	-	-	-	-	44	70
	40	75	138	-	-	-	-	-	-	-	-	40	64
	64	47	86	-	-	-	-	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm]

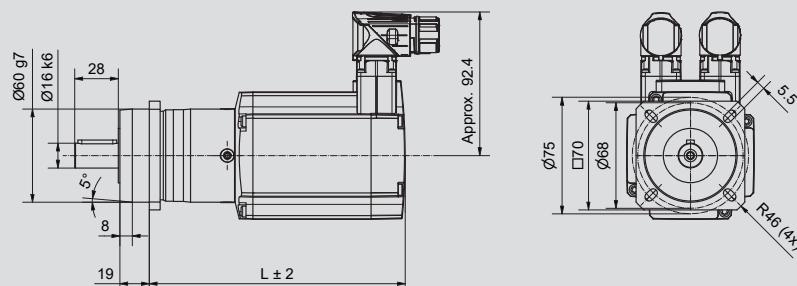
			HMDo8-042-...Ho6 ¹⁾				HMDo8-057-...Ho6 ¹⁾				Gear Ho6 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3)$	$\eta_{out,5500 \text{ rpm}}^3)$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	11.2	9.8	12.1	30.2	15.3	12.4	16.4	41.2	17	27.5
	4	750	1375	15.1	13.2	16.3	40.7	20.6	16.7	22.1	55.5	23	37
	5	600	1100	18.9	16.5	20.4	50.9	25.7	20.9	27.6	69.4	29	46
	7	429	786	25.9	22.6	27.9	69.8	35.2	28.6	37.9	95.1	25	40
	8	375	688	-	25.6	31.6	79.0	-	-	-	-	18	29
	10	300	550	-	-	-	-	-	-	-	-	15	24
2-stage	9	333	611	33.7	29.4	36.3	90.7	45.8	37.2	49.2	123.6	44	70
	12	250	458	44.5	38.8	47.9	119.7	60.4	49.0	65.0	163.0	44	70
	15	200	367	55.6	48.5	59.9	149.6	-	61.3	81.2	203.8	44	70
	16	188	344	59.3	51.7	63.8	159.6	-	65.4	86.6	217.4	44	70
	20	150	275	-	64.6	79.8	199.5	-	-	-	-	44	70
	25	120	220	-	-	-	-	-	-	-	-	40	64
	32	94	172	-	-	-	-	-	-	-	-	44	70
	40	75	138	-	-	-	-	-	-	-	-	40	64
	64	47	86	-	-	-	-	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]
HMD08-024-...H06		without brake	164.8	186.8		177.3	199.3	4.00
		with brake	213.3	235.3		225.8	247.8	4.65
HMD08-032-...H06	1-stage	without brake	179.8	201.8		192.3	214.3	4.40
		with brake	228.3	250.3		240.8	262.8	5.05
HMD08-042-...H06		without brake	194.8	216.8		207.3	229.3	4.80
		with brake	243.3	265.3		255.8	277.8	5.45
HMD08-057-...H06		without brake	224.8	246.8		237.3	259.3	5.90
		with brake	273.3	295.3		285.8	307.8	6.55

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

		HMD08-024-...H06		HMD08-032-...H06		HMD08-042-...H06		HMD08-057-...H06	
	i	without brake	with brake						
1-stage	3	9.17E-01		1.25E+00		1.58E+00		2.24E+00	
	4	8.59E-01		1.19E+00		1.52E+00		2.18E+00	
	5	8.37E-01		1.17E+00		1.50E+00		2.16E+00	
	7	8.17E-01		1.15E+00		1.48E+00		2.14E+00	
	8	8.14E-01		1.14E+00		1.47E+00		2.13E+00	
	10	8.08E-01		1.14E+00		1.47E+00		2.13E+00	
2-stage	9	8.74E-01	+2.40E-01	1.20E+00		1.53E+00		2.19E+00	
	12	8.68E-01		1.20E+00		1.53E+00		2.19E+00	
	15	8.20E-01		1.15E+00	+2.40E-01	1.48E+00		2.14E+00	
	16	8.31E-01		1.16E+00		1.49E+00		2.15E+00	
	20	8.19E-01		1.15E+00		1.48E+00		2.14E+00	
	25	8.18E-01		1.15E+00		1.48E+00		2.14E+00	
	32	8.07E-01		1.14E+00		1.47E+00		2.13E+00	
	40	8.07E-01		1.14E+00		1.47E+00		2.13E+00	
	64	8.07E-01		1.14E+00		1.47E+00		2.13E+00	

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMDo8-024 /-032 /-042 /-057

Gear Ho8



Stall, rated and peak torque - M [Nm]

			HMDo8-024-...Ho8 ¹⁾				HMDo8-032-...Ho8 ¹⁾				Gear Ho8 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	6.7	6.1	7.0	17.5	8.7	7.6	9.3	23.3	39	62
	4	750	1375	8.9	8.1	9.3	23.3	11.6	10.1	12.4	31.0	52	83
	5	600	1100	11.2	10.2	11.6	29.1	14.6	12.6	15.5	38.8	65	104
	7	429	786	15.5	14.1	16.1	40.3	20.2	17.5	21.5	53.8	65	104
	8	375	688	17.7	16.1	18.4	46.1	23.0	20.0	24.6	61.4	50	80
	10	300	550	21.6	19.7	22.6	56.4	28.2	24.4	30.1	75.2	38	61
2-stage	9	333	611	19.9	18.1	20.7	51.8	25.9	22.5	27.6	69.1	117	187
	12	250	458	26.5	24.2	27.6	69.1	34.6	30.0	36.9	92.2	120	192
	15	200	367	32.8	29.9	34.2	85.5	42.8	37.1	45.6	114.0	110	176
	16	188	344	35.3	32.3	36.9	92.2	46.1	39.9	49.2	122.9	120	192
	20	150	275	43.7	39.9	45.6	114.0	57.0	49.4	60.8	152.0	120	192
	25	120	220	54.6	49.9	57.0	142.5	71.3	61.8	76.0	190.0	110	176
	32	94	172	69.9	63.8	73.0	182.4	91.2	79.0	97.3	243.2	120	192
	40	75	138	86.5	79.0	90.2	225.6	112.8	97.8	120.3	300.8	110	176
	64	47	86	129.5	118.3	135.2	337.9	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

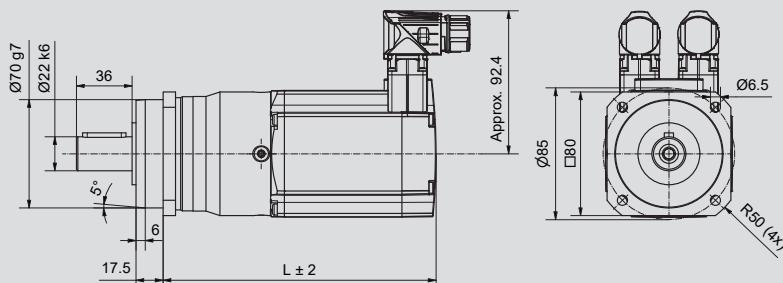
			HMDo8-042-...Ho8 ¹⁾				HMDo8-057-...Ho8 ¹⁾				Gear Ho8 ²⁾		
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	11.3	9.9	12.2	30.6	15.4	12.5	16.6	41.6	39	62
	4	750	1375	15.1	13.2	16.3	40.7	20.6	16.7	22.1	55.5	52	83
	5	600	1100	18.9	16.5	20.4	50.9	25.7	20.9	27.6	69.4	65	104
	7	429	786	26.2	22.8	28.2	70.6	35.6	28.9	38.3	96.1	65	104
	8	375	688	30.0	26.1	32.3	80.6	40.7	33.0	43.8	109.8	50	80
	10	300	550	36.7	32.0	39.5	98.7	49.8	40.4	53.6	134.4	38	61
2-stage	9	333	611	33.7	29.4	36.3	90.7	45.8	37.2	49.2	123.6	117	187
	12	250	458	44.9	39.2	48.4	121.0	61.1	49.5	65.7	164.7	120	192
	15	200	367	55.6	48.5	59.9	149.6	75.5	61.3	81.2	203.8	110	176
	16	188	344	59.9	52.2	64.5	161.3	81.4	66.0	87.6	219.6	120	192
	20	150	275	74.1	64.6	79.8	199.5	100.7	81.7	108.3	271.7	120	192
	25	120	220	92.6	80.8	99.8	249.4	125.9	102.1	135.4	339.6	110	176
	32	94	172	118.6	103.4	127.7	319.2	161.1	130.7	173.3	434.7	120	192
	40	75	138	146.6	127.8	157.9	394.8	-	161.7	214.3	537.7	110	176
	64	47	86	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]
HMD08-024-...H08	without brake	176.5	198.5	4.80	2-stage	194.5	216.5	5.30
		225.0	247.0	5.45		243.0	265.0	5.95
	with brake	191.5	213.5	5.20		209.5	231.5	5.70
		240.0	262.0	5.85		258.0	280.0	6.35
HMD08-032-...H08	without brake	206.5	228.5	5.60		224.5	246.5	6.10
		255.0	277.0	6.25		273.0	295.0	6.75
	with brake	236.5	258.5	6.70		254.5	276.5	7.20
		285.0	307.0	7.35		303.0	325.0	7.85

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

		HMD08-024-...H08		HMD08-032-...H08		HMD08-042-...H08		HMD08-057-...H08	
	i	without brake	with brake						
1-stage	3	1.23E+00		1.56E+00		1.89E+00		2.55E+00	
	4	9.97E-01		1.33E+00		1.66E+00		2.32E+00	
	5	9.23E-01		1.25E+00		1.58E+00		2.24E+00	
	7	8.58E-01		1.19E+00		1.52E+00		2.18E+00	
	8	8.44E-01		1.17E+00		1.50E+00		2.16E+00	
	10	8.27E-01		1.16E+00		1.49E+00		2.15E+00	
2-stage	9	1.10E+00	+2.40E-01	1.43E+00	+2.40E-01	1.76E+00	+2.40E-01	2.42E+00	+2.40E-01
	12	1.07E+00		1.40E+00		1.73E+00		2.39E+00	
	15	9.70E-01		1.30E+00		1.63E+00		2.29E+00	
	16	9.17E-01		1.25E+00		1.58E+00		2.24E+00	
	20	8.72E-01		1.20E+00		1.53E+00		2.19E+00	
	25	8.69E-01		1.20E+00		1.53E+00		2.19E+00	
	32	8.27E-01		1.16E+00		1.49E+00		2.15E+00	
	40	8.26E-01		1.16E+00		1.49E+00		2.15E+00	
	64	8.26E-01		1.16E+00		1.49E+00		2.15E+00	

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMD10-039 /-057 /-076 /-105

Gear Ho8



Stall, rated and peak torque - M [Nm]

			HMD10-039...Ho8 ¹⁾				HMD10-057...Ho8 ¹⁾				Gear Ho8 ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	10.5	9.3	11.3	28.5	15.1	11.6	16.6	41.6	39	62
	4	750	1250	14.0	12.4	15.1	38.0	20.2	15.5	22.1	55.5	52	83
	5	600	1000	17.5	15.5	18.9	47.5	25.2	19.4	27.6	69.4	65	104
	7	429	714	24.2	21.5	26.2	65.9	34.9	26.9	38.3	96.1	65	104
	8	375	625	27.6	24.6	30.0	75.3	39.9	30.7	43.8	109.8	50	80
	10	300	500	33.8	30.1	36.7	92.1	48.9	37.6	53.6	134.4	38	61
2-stage	9	333	556	31.1	27.6	33.7	84.7	44.9	34.6	49.2	123.6	117	187
	12	250	417	41.5	36.9	44.9	112.9	59.9	46.1	65.7	164.7	120	192
	15	200	333	51.3	45.6	55.6	139.7	74.1	57.0	81.2	203.8	110	176
	16	188	313	55.3	49.2	59.9	150.5	79.9	61.4	87.6	219.6	120	192
	20	150	250	68.4	60.8	74.1	186.2	98.8	76.0	108.3	271.7	120	192
	25	120	200	85.5	76.0	92.6	232.8	123.5	95.0	135.4	339.6	110	176
	32	94	156	109.4	97.3	118.6	297.9	158.1	121.6	173.3	434.7	120	192
	40	75	125	135.4	120.3	146.6	368.5	-	150.4	214.3	537.7	110	176
	64	47	78	-	-	-	-	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

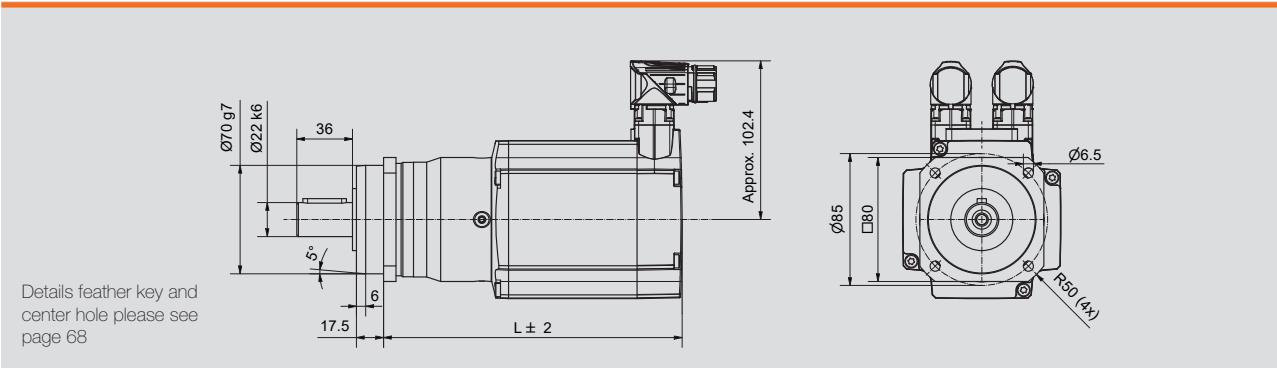
			HMD10-076...Ho8 ¹⁾				HMD10-105...Ho8 ¹⁾				Gear Ho8 ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	18.9	14.0	22.1	55.3	25.0	16.0	30.6	76.5	39	62
	4	750	1250	25.2	18.6	29.5	73.7	33.4	21.3	40.7	102.0	52	83
	5	600	1000	31.5	23.3	36.9	92.2	41.7	26.7	50.9	127.6	65	104
	7	429	714	43.7	32.3	51.1	127.7	57.8	37.0	70.6	176.7	65	104
	8	375	625	49.9	36.9	58.4	145.9	66.0	42.2	80.6	202.0	50	80
	10	300	500	-	45.1	71.4	178.6	-	51.7	98.7	247.2	38	61
2-stage	9	333	556	56.2	41.5	65.7	164.2	74.3	47.5	90.7	227.2	117	187
	12	250	417	74.9	55.3	87.6	218.9	99.1	63.4	121.0	303.0	120	192
	15	200	333	92.6	68.4	108.3	270.8	122.6	78.4	149.6	374.8	110	176
	16	188	313	99.8	73.7	116.7	291.8	132.1	84.5	161.3	404.0	120	192
	20	150	250	123.5	91.2	144.4	361.0	163.4	104.5	199.5	499.7	120	192
	25	120	200	154.4	114.0	180.5	451.3	-	130.6	249.4	624.6	110	176
	32	94	156	-	145.9	231.0	577.6	-	167.2	319.2	799.5	120	192
	40	75	125	-	-	-	-	-	-	-	-	110	176
	64	47	78	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]	Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]	
HMD10-039-...H08		without brake	192.7	213.7	6.80		210.7	231.7	7.30
		with brake	239.7	260.7	7.80		257.7	278.7	8.30
HMD10-057-...H08	1-stage	without brake	207.7	228.7	7.30	2-stage	225.7	246.7	7.80
		with brake	254.7	275.7	8.30		272.7	293.7	8.80
HMD10-076-...H08		without brake	222.7	243.7	7.80		240.7	261.7	8.30
		with brake	269.7	290.7	8.80		287.7	308.7	9.30
HMD10-105-...H08		without brake	252.7	273.7	8.80		270.7	291.7	9.30
		with brake	299.7	320.7	9.80		317.7	338.7	10.30

Moment of inertia ⁵⁾ - J_1 [kg·cm²]

	HMD10-039-...H08		HMD10-057-...H08		HMD10-076-...H08		HMD10-105-...H08	
i	without brake	with brake						
1-stage	3	2.37E+00		3.18E+00		4.00E+00		5.64E+00
	4	2.14E+00		2.95E+00		3.77E+00		5.41E+00
	5	2.06E+00		2.87E+00		3.69E+00		5.33E+00
	7	2.00E+00		2.81E+00		3.63E+00		5.27E+00
	8	1.98E+00		2.79E+00		3.61E+00		5.25E+00
	10	1.97E+00		2.78E+00		3.60E+00		5.24E+00
2-stage	9	2.24E+00	+6.80E-01	3.05E+00	+6.80E-01	3.87E+00	+6.80E-01	5.51E+00
	12	2.21E+00		3.02E+00		3.84E+00		5.48E+00
	15	2.11E+00		2.92E+00		3.74E+00		5.38E+00
	16	2.06E+00		2.87E+00		3.69E+00		5.33E+00
	20	2.01E+00		2.82E+00		3.64E+00		5.28E+00
	25	2.01E+00		2.82E+00		3.64E+00		5.28E+00
	32	1.97E+00		2.78E+00		3.60E+00		5.24E+00
	40	1.97E+00		2.78E+00		3.60E+00		5.24E+00
	64	1.97E+00		2.78E+00		3.60E+00		5.24E+00

1) Data calculated with a gear efficiency grade defined at $n_g=1000$ rpm and the gear rated torque and a reference temperature of 70°C.

2) Data refer to an output shaft speed of $n_{out}=100$ rpm and an application factor $K_a=1$ as well as S1 operating mode with purely pulsating load.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 V_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMDo6-011 /-019 /-026

Gear Fo6



Stall, rated and peak torque - M [Nm]

			HMDo6-011...Fo6 ¹⁾				HMDo6-019...Fo6 ¹⁾				Gear Fo6 ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,6000\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	2000	2.9	2.9	2.9	7.3	4.9	4.2	5.5	14.0	17	27.5
	4	750	1500	3.9	3.9	3.9	9.7	6.6	5.6	7.4	18.6	23	37
	5	600	1200	4.9	4.9	4.9	12.1	8.2	7.0	9.2	23.3	29	46
	7	429	857	6.7	6.7	6.7	16.8	11.4	9.7	12.8	32.3	25	40
	8	375	750	7.6	7.6	7.6	19.0	12.9	11.0	14.4	36.5	18	29
	10	300	600	9.4	9.4	9.4	23.5	16.0	13.6	17.9	45.1	15	24
2-stage	9	333	667	8.6	8.6	8.6	21.6	14.7	12.5	16.4	41.5	44	70
	12	250	500	11.5	11.5	11.5	28.8	19.6	16.7	21.9	55.3	44	70
	15	200	400	14.4	14.4	14.4	36.0	24.5	20.9	27.4	69.1	44	70
	16	188	375	15.2	15.2	15.2	38.0	25.8	22.0	28.9	73.0	44	70
	20	150	300	19.0	19.0	19.0	47.5	32.3	27.6	36.1	91.2	44	70
	25	120	240	23.8	23.8	23.8	59.4	40.4	34.4	45.1	114.0	40	64
	32	94	188	30.1	30.1	30.1	75.2	51.1	43.6	57.2	144.4	44	70
	40	75	150	37.2	37.2	37.2	93.0	-	53.9	70.7	178.6	40	64
	64	47	94	55.0	55.0	55.0	137.6	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm]

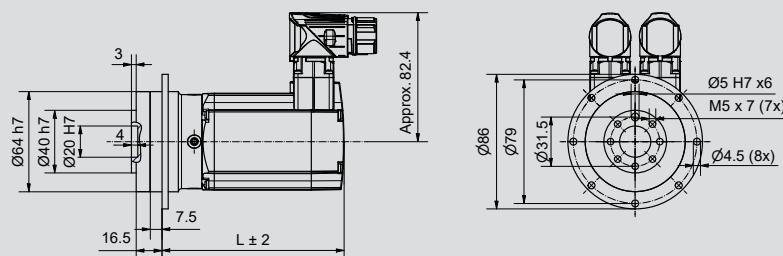
			HMDo6-026...Fo6 ¹⁾				Gear Fo6 ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,6000\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	2000	7.3	5.8	7.6	18.9	17	27.5
	4	750	1500	9.7	7.8	10.1	25.2	23	37
	5	600	1200	12.1	9.7	12.6	31.5	29	46
	7	429	857	16.8	13.4	17.5	43.7	25	40
	8	375	750	19.0	15.2	19.8	49.4	18	29
	10	300	600	-	18.8	24.4	61.1	15	24
2-stage	9	333	667	21.6	17.3	22.5	56.2	44	70
	12	250	500	28.8	23.0	30.0	74.9	44	70
	15	200	400	36.0	28.8	37.4	93.6	44	70
	16	188	375	38.0	30.4	39.5	98.8	44	70
	20	150	300	47.5	38.0	49.4	123.5	44	70
	25	120	240	59.4	47.5	61.8	154.4	40	64
	32	94	188	-	60.2	78.2	195.5	44	70
	40	75	150	-	-	-	-	40	64
	64	47	94	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]	Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]	
HMD06-011-...F06		without brake	116.5	134.5	2.00		129.0	147.0	2.40
		with brake	156.0	174.0	2.35		168.5	186.5	2.75
HMD06-019-...F06	1-stage	without brake	141.5	159.5	2.40		154.0	172.0	2.80
		with brake	181.0	199.0	2.75		193.5	211.5	3.15
HMD06-026-...F06		without brake	171.5	189.5	2.80		184.0	202.0	3.20
		with brake	211.0	229.0	3.15		223.5	241.5	3.55

Moment of inertia ⁵⁾ - J_1 [kg·cm²]

	HMD06-011-...F06		HMD06-019-...F06		HMD06-026-...F06	
i	without brake	with brake	without brake	with brake	without brake	with brake
1-stage	3	4.17E-01		6.38E-01		8.60E-01
	4	3.45E-01		5.66E-01		7.88E-01
	5	3.16E-01		5.37E-01		7.59E-01
	7	2.92E-01		5.13E-01		7.35E-01
	8	2.86E-01		5.07E-01		7.29E-01
	10	2.79E-01		5.00E-01		7.22E-01
2-stage	9	3.37E-01	+8.90E-02	5.58E-01	+8.90E-02	7.80E-01
	12	3.30E-01		5.51E-01		7.73E-01
	15	2.87E-01		5.08E-01		7.30E-01
	16	2.95E-01		5.16E-01		7.38E-01
	20	2.84E-01		5.05E-01		7.27E-01
	25	2.83E-01		5.04E-01		7.26E-01
	32	2.74E-01		4.95E-01		7.17E-01
	40	2.74E-01		4.95E-01		7.17E-01
	64	2.73E-01		4.94E-01		7.16E-01

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

Motor type HMDo8-024 /-032 /-042 /-057

Gear Fo6



Stall, rated and peak torque - M [Nm]

				HMDo8-024-...Fo6 ¹⁾				HMDo8-032-...Fo6 ¹⁾				Gear Fo6 ²⁾	
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,5500\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,5500\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5500\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	6.7	6.1	7.0	17.5	8.7	7.6	9.3	23.3	17	27.5
	4	750	1375	8.9	8.1	9.3	23.3	11.6	10.1	12.4	31.0	23	37
	5	600	1100	11.2	10.2	11.6	29.1	14.6	12.6	15.5	38.8	29	46
	7	429	786	15.5	14.1	16.1	40.3	20.2	17.5	21.5	53.8	25	40
	8	375	688	17.5	16.0	18.2	45.6	22.8	19.8	24.3	60.8	18	29
	10	300	550	21.6	19.7	22.6	56.4	-	-	-	-	15	24
2-stage	9	333	611	19.9	18.1	20.7	51.8	25.9	22.5	27.6	69.1	44	70
	12	250	458	26.5	24.2	27.6	69.1	34.6	30.0	36.9	92.2	44	70
	15	200	367	33.1	30.2	34.6	86.4	43.2	37.4	46.1	115.2	44	70
	16	188	344	35.0	31.9	36.5	91.2	45.6	39.5	48.6	121.6	44	70
	20	150	275	43.7	39.9	45.6	114.0	57.0	49.4	60.8	152.0	44	70
	25	120	220	54.6	49.9	57.0	142.5	-	-	-	-	40	64
	32	94	172	-	63.2	72.2	180.5	-	-	-	-	44	70
	40	75	138	-	-	-	-	-	-	-	-	40	64
	64	47	86	-	-	-	-	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm]

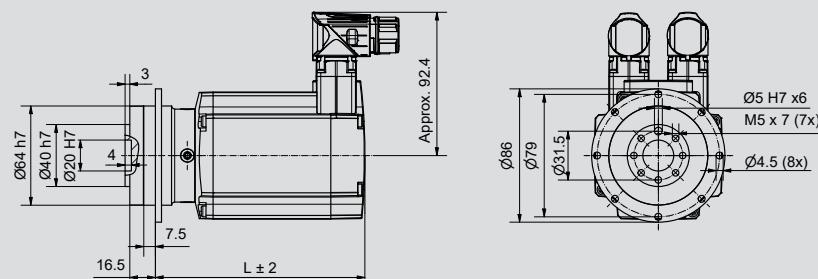
				HMDo8-042-...Fo6 ¹⁾				HMDo8-057-...Fo6 ¹⁾				Gear Fo6 ²⁾	
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,5500\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,5500\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5500\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	11.3	9.9	12.2	30.6	15.4	12.5	16.6	41.6	17	27.5
	4	750	1375	15.1	13.2	16.3	40.7	20.6	16.7	22.1	55.5	23	37
	5	600	1100	18.9	16.5	20.4	50.9	25.7	20.9	27.6	69.4	29	46
	7	429	786	26.2	22.8	28.2	70.6	35.6	28.9	38.3	96.1	25	40
	8	375	688	-	25.8	31.9	79.8	-	-	-	-	18	29
	10	300	550	-	-	-	-	-	-	-	-	15	24
2-stage	9	333	611	33.7	29.4	36.3	90.7	45.8	37.2	49.2	123.6	44	70
	12	250	458	44.9	39.2	48.4	121.0	61.1	49.5	65.7	164.7	44	70
	15	200	367	56.2	49.0	60.5	151.2	-	61.9	82.1	205.9	44	70
	16	188	344	59.3	51.7	63.8	159.6	-	65.4	86.6	217.4	44	70
	20	150	275	-	64.6	79.8	199.5	-	-	-	-	44	70
	25	120	220	-	-	-	-	-	-	-	-	40	64
	32	94	172	-	-	-	-	-	-	-	-	44	70
	40	75	138	-	-	-	-	-	-	-	-	40	64
	64	47	86	-	-	-	-	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]
HMD08-024-...F06		without brake	135.3	157.3		147.8	169.8	3.70
		with brake	183.8	205.8		196.3	218.3	4.35
HMD08-032-...F06	1-stage	without brake	150.3	172.3		162.8	184.8	4.10
		with brake	198.8	220.8		211.3	233.3	4.75
HMD08-042-...F06		without brake	165.3	187.3		177.8	199.8	4.50
		with brake	213.8	235.8		226.3	248.3	5.15
HMD08-057-...F06		without brake	195.3	217.3		207.8	229.8	5.60
		with brake	243.8	265.8		256.3	278.3	6.25

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

		HMD08-024-...F06		HMD08-032-...F06		HMD08-042-...F06		HMD08-057-...F06	
	i	without brake	with brake						
1-stage	3	9.49E-01		1.28E+00		1.61E+00		2.27E+00	
	4	8.77E-01		1.21E+00		1.54E+00		2.20E+00	
	5	8.48E-01		1.18E+00		1.51E+00		2.17E+00	
	7	8.24E-01		1.15E+00		1.48E+00		2.14E+00	
	8	8.18E-01		1.15E+00		1.48E+00		2.14E+00	
	10	8.11E-01		1.14E+00		1.47E+00		2.13E+00	
2-stage	9	8.69E-01	+2.40E-01	1.20E+00		1.53E+00		2.19E+00	
	12	8.62E-01		1.19E+00		1.52E+00		2.18E+00	
	15	8.19E-01		1.15E+00	+2.40E-01	1.48E+00		2.14E+00	
	16	8.27E-01		1.16E+00		1.49E+00		2.15E+00	
	20	8.16E-01		1.15E+00		1.48E+00		2.14E+00	
	25	8.15E-01		1.15E+00		1.48E+00		2.14E+00	
	32	8.06E-01		1.14E+00		1.47E+00		2.13E+00	
	40	8.06E-01		1.14E+00		1.47E+00		2.13E+00	
	64	8.05E-01		1.14E+00		1.47E+00		2.13E+00	

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMDo8-024 /-032 /-042 /-057

Gear Fog



Stall, rated and peak torque - M [Nm]

			HMDo8-024-...Fog ¹⁾				HMDo8-032-...Fog ¹⁾				Gear Fog ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5500\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5500\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5500\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	6.8	6.2	7.1	17.6	8.8	7.6	9.4	23.5	39	62
	4	750	1375	9.0	8.2	9.4	23.5	11.8	10.2	12.5	31.4	52	83
	5	600	1100	11.3	10.3	11.8	29.4	14.7	12.7	15.7	39.2	65	104
	7	429	786	15.6	14.3	16.3	40.7	20.4	17.7	21.7	54.3	65	104
	8	375	688	17.7	16.1	18.4	46.1	23.0	20.0	24.6	61.4	50	80
	10	300	550	21.9	20.0	22.8	57.0	28.5	24.7	30.4	76.0	38	61
2-stage	9	333	611	20.1	18.3	21.0	52.4	26.2	22.7	27.9	69.8	117	187
	12	250	458	26.5	24.2	27.6	69.1	34.6	30.0	36.9	92.2	120	192
	15	200	367	33.1	30.2	34.6	86.4	43.2	37.4	46.1	115.2	110	176
	16	188	344	35.3	32.3	36.9	92.2	46.1	39.9	49.2	122.9	120	192
	20	150	275	44.2	40.3	46.1	115.2	57.6	49.9	61.4	153.6	120	192
	25	120	220	54.6	49.9	57.0	142.5	71.3	61.8	76.0	190.0	110	176
	32	94	172	69.9	63.8	73.0	182.4	91.2	79.0	97.3	243.2	120	192
	40	75	138	86.5	79.0	90.2	225.6	112.8	97.8	120.3	300.8	110	176
	64	47	86	129.5	118.3	135.2	337.9	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

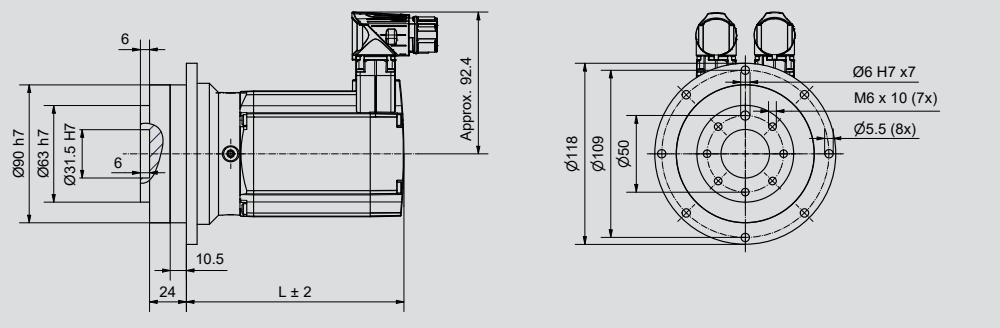
			HMDo8-042-...Fog ¹⁾				HMDo8-057-...Fog ¹⁾				Gear Fog ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5500\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5500\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5500\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1833	11.5	10.0	12.3	30.9	15.6	12.6	16.8	42.0	39	62
	4	750	1375	15.3	13.3	16.5	41.2	20.8	16.9	22.3	56.1	52	83
	5	600	1100	19.1	16.7	20.6	51.5	26.0	21.1	27.9	70.1	65	104
	7	429	786	26.5	23.1	28.5	71.3	36.0	29.2	38.7	97.1	65	104
	8	375	688	30.0	26.1	32.3	80.6	40.7	33.0	43.8	109.8	50	80
	10	300	550	37.1	32.3	39.9	99.8	50.4	40.9	54.2	135.9	38	61
2-stage	9	333	611	34.0	29.7	36.7	91.7	46.3	37.5	49.8	124.8	117	187
	12	250	458	44.9	39.2	48.4	121.0	61.1	49.5	65.7	164.7	120	192
	15	200	367	56.2	49.0	60.5	151.2	76.3	61.9	82.1	205.9	110	176
	16	188	344	59.9	52.2	64.5	161.3	81.4	66.0	87.6	219.6	120	192
	20	150	275	74.9	65.3	80.6	201.6	101.8	82.6	109.4	274.6	120	192
	25	120	220	92.6	80.8	99.8	249.4	125.9	102.1	135.4	339.6	110	176
	32	94	172	118.6	103.4	127.7	319.2	161.1	130.7	173.3	434.7	120	192
	40	75	138	146.6	127.8	157.9	394.8	-	161.7	214.3	537.7	110	176
	64	47	86	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	
HMD08-024-...F09		without brake	142.0	164.0	4.80		159.5	181.5	5.30
		with brake	190.5	212.5	5.45		208.0	230.0	5.95
HMD08-032-...F09	1-stage	without brake	157.0	179.0	5.20	2-stage	174.5	196.5	5.70
		with brake	205.5	227.5	5.85		223.0	245.0	6.35
HMD08-042-...F09		without brake	172.0	194.0	5.60		189.5	211.5	6.10
		with brake	220.5	242.5	6.25		238.0	260.0	6.75
HMD08-057-...F09		without brake	202.0	224.0	6.70		219.5	241.5	7.20
		with brake	250.5	272.5	7.35		268.0	290.0	7.85

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

		HMD08-024-...F09		HMD08-032-...F09		HMD08-042-...F09		HMD08-057-...F09	
	i	without brake	with brake						
1-stage	3	1.62E+00		1.95E+00		2.28E+00		2.94E+00	
	4	1.22E+00		1.55E+00		1.88E+00		2.54E+00	
	5	1.07E+00		1.40E+00		1.73E+00		2.39E+00	
	7	9.31E-01		1.26E+00		1.59E+00		2.25E+00	
	8	9.00E-01		1.23E+00		1.56E+00		2.22E+00	
	10	8.63E-01		1.19E+00		1.52E+00		2.18E+00	
2-stage	9	1.12E+00	+2.40E-01	1.45E+00	+2.40E-01	1.78E+00	+2.40E-01	2.44E+00	+2.40E-01
	12	1.08E+00		1.41E+00		1.74E+00		2.40E+00	
	15	1.06E+00		1.39E+00		1.72E+00		2.38E+00	
	16	9.22E-01		1.25E+00		1.58E+00		2.24E+00	
	20	8.75E-01		1.21E+00		1.54E+00		2.20E+00	
	25	8.67E-01		1.20E+00		1.53E+00		2.19E+00	
	32	8.28E-01		1.16E+00		1.49E+00		2.15E+00	
	40	8.26E-01		1.16E+00		1.49E+00		2.15E+00	
	64	8.25E-01		1.16E+00		1.49E+00		2.15E+00	

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{zk} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMD10-039 /-057 /-076 /-105 Gear Fog



Stall, rated and peak torque - M [Nm]

			HMD10-039-...Fog ¹⁾				HMD10-057-...Fog ¹⁾				Gear Fog ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	10.6	9.4	11.5	28.8	15.3	11.8	16.8	42.0	39	62
	4	750	1250	14.1	12.5	15.3	38.4	20.4	15.7	22.3	56.1	52	83
	5	600	1000	17.6	15.7	19.1	48.0	25.5	19.6	27.9	70.1	65	104
	7	429	714	24.4	21.7	26.5	66.5	35.3	27.2	38.7	97.1	65	104
	8	375	625	27.6	24.6	30.0	75.3	39.9	30.7	43.8	109.8	50	80
	10	300	500	34.2	30.4	37.1	93.1	49.4	38.0	54.2	135.9	38	61
2-stage	9	333	556	31.4	27.9	34.0	85.6	45.4	34.9	49.8	124.8	117	187
	12	250	417	41.5	36.9	44.9	112.9	59.9	46.1	65.7	164.7	120	192
	15	200	333	51.8	46.1	56.2	141.1	74.9	57.6	82.1	205.9	110	176
	16	188	313	55.3	49.2	59.9	150.5	79.9	61.4	87.6	219.6	120	192
	20	150	250	69.1	61.4	74.9	188.2	99.8	76.8	109.4	274.6	120	192
	25	120	200	85.5	76.0	92.6	232.8	123.5	95.0	135.4	339.6	110	176
	32	94	156	109.4	97.3	118.6	297.9	158.1	121.6	173.3	434.7	120	192
	40	75	125	135.4	120.3	146.6	368.5	-	150.4	214.3	537.7	110	176
	64	47	78	-	-	-	-	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

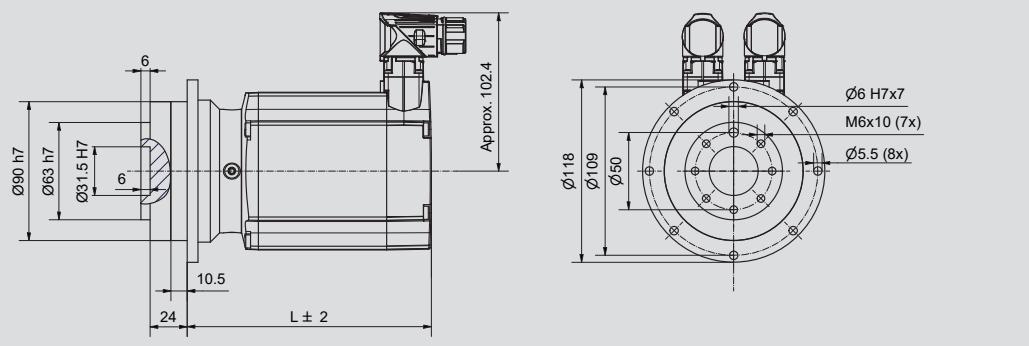
			HMD10-076-...Fog ¹⁾				HMD10-105-...Fog ¹⁾				Gear Fog ²⁾		
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	3	1000	1667	19.1	14.1	22.3	55.9	25.3	16.2	30.9	77.3	39	62
	4	750	1250	25.5	18.8	29.8	74.5	33.7	21.6	41.2	103.1	52	83
	5	600	1000	31.9	23.5	37.2	93.1	42.1	27.0	51.5	128.9	65	104
	7	429	714	44.1	32.6	51.6	129.0	58.4	37.3	71.3	178.6	65	104
	8	375	625	49.9	36.9	58.4	145.9	66.0	42.2	80.6	202.0	50	80
	10	300	500	-	45.6	72.2	180.5	-	52.3	99.8	249.9	38	61
2-stage	9	333	556	56.7	41.9	66.3	165.9	75.1	48.0	91.7	229.6	117	187
	12	250	417	74.9	55.3	87.6	218.9	99.1	63.4	121.0	303.0	120	192
	15	200	333	93.6	69.1	109.4	273.6	123.8	79.2	151.2	378.7	110	176
	16	188	313	99.8	73.7	116.7	291.8	132.1	84.5	161.3	404.0	120	192
	20	150	250	124.8	92.2	145.9	364.8	165.1	105.6	201.6	505.0	120	192
	25	120	200	154.4	114.0	180.5	451.3	-	130.6	249.4	624.6	110	176
	32	94	156	-	145.9	231.0	577.6	-	167.2	319.2	799.5	120	192
	40	75	125	-	-	-	-	-	-	-	-	110	176
	64	47	78	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]	Stage	L_{short} [mm] ⁴⁾	L_{long} [mm] ⁴⁾	m [kg]	
HMD10-039-...F09		without brake	158.2	179.2	6.80		175.7	196.7	7.30
		with brake	205.2	226.2	7.80		222.7	243.7	8.30
HMD10-057-...F09	1-stage	without brake	173.2	194.2	7.30	2-stage	190.7	211.7	7.80
		with brake	220.2	241.2	8.30		237.7	258.7	8.80
HMD10-076-...F09		without brake	188.2	209.2	7.80		205.7	226.7	8.30
		with brake	235.2	256.2	8.80		252.7	273.7	9.30
HMD10-105-...F09		without brake	218.2	239.2	8.80		235.7	256.7	9.30
		with brake	265.2	286.2	9.80		282.7	303.7	10.30

Moment of inertia ⁵⁾ - J_1 [kg·cm²]

		HMD10-039-...F09		HMD10-057-...F09		HMD10-076-...F09		HMD10-105-...F09	
	i	without brake	with brake						
1-stage	3	2.76E+00		3.57E+00		4.39E+00		6.03E+00	
	4	2.36E+00		3.17E+00		3.99E+00		5.63E+00	
	5	2.21E+00		3.02E+00		3.84E+00		5.48E+00	
	7	2.07E+00		2.88E+00		3.70E+00		5.34E+00	
	8	2.04E+00		2.85E+00		3.67E+00		5.31E+00	
	10	2.00E+00		2.81E+00		3.63E+00		5.27E+00	
2-stage	9	2.26E+00	+6.80E-01	3.07E+00	+6.80E-01	3.89E+00	+6.80E-01	5.53E+00	+6.80E-01
	12	2.22E+00		3.03E+00		3.85E+00		5.49E+00	
	15	2.20E+00		3.01E+00		3.83E+00		5.47E+00	
	16	2.06E+00		2.87E+00		3.69E+00		5.33E+00	
	20	2.02E+00		2.83E+00		3.65E+00		5.29E+00	
	25	2.01E+00		2.82E+00		3.64E+00		5.28E+00	
	32	1.97E+00		2.78E+00		3.60E+00		5.24E+00	
	40	1.97E+00		2.78E+00		3.60E+00		5.24E+00	
	64	1.97E+00		2.78E+00		3.60E+00		5.24E+00	

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMDo6-011 /-019 /-026
Gear **Vo6**



Stall, rated and peak torque - M [Nm]

				HMDo6-011...Vo6 ¹⁾				HMDo6-019...Vo6 ¹⁾				Gear Vo6 ²⁾	
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,6000\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
2-stage	9	333	667	8.6	8.6	8.6	21.6	14.7	12.5	16.4	41.5	44	70
	12	250	500	11.5	11.5	11.5	28.8	19.6	16.7	21.9	55.3	44	70
	15	200	400	14.4	14.4	14.4	36.0	24.5	20.9	27.4	69.1	44	70
	16	188	375	15.2	15.2	15.2	38.0	25.8	22.0	28.9	73.0	44	70
	20	150	300	19.0	19.0	19.0	47.5	32.3	27.6	36.1	91.2	44	70
	25	120	240	23.8	23.8	23.8	59.4	40.4	34.4	45.1	114.0	40	64
	32	94	188	30.4	30.4	30.4	76.0	51.7	44.1	57.8	145.9	44	70
	40	75	150	38.0	38.0	38.0	95.0	-	55.1	72.2	182.4	40	64
	64	47	94	58.2	58.2	58.2	145.6	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm]

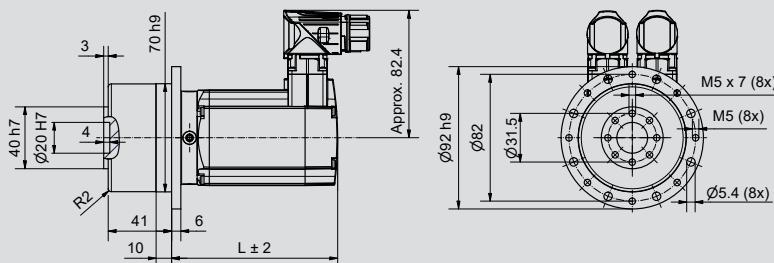
				HMDo6-026...Vo6 ¹⁾				Gear Vo6 ²⁾	
	i	$\eta_{out,3000\text{ rpm}}^3)$	$\eta_{out,6000\text{ rpm}}^3)$	$M_{n,3000\text{ rpm}}$	$M_{n,6000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-
2-stage	9	333	667	21.6	17.3	22.5	56.2	44	70
	12	250	500	28.8	23.0	30.0	74.9	44	70
	15	200	400	36.0	28.8	37.4	93.6	44	70
	16	188	375	38.0	30.4	39.5	98.8	44	70
	20	150	300	47.5	38.0	49.4	123.5	44	70
	25	120	240	59.4	47.5	61.8	154.4	40	64
	32	94	188	-	60.8	79.0	197.6	44	70
	40	75	150	-	-	-	-	40	64
	64	47	94	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type		Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]
HMD06-011-...V06	without brake		-	-	-		107.5	125.5	2.40
	with brake		-	-	-		147.0	165.0	2.75
HMD06-019-...V06	without brake	1-stage	-	-	-	2-stage	132.5	150.5	2.80
	with brake		-	-	-		172.0	190.0	3.15
HMD06-026-...V06	without brake		-	-	-		162.5	180.5	3.20
	with brake		-	-	-		202.0	220.0	3.55

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD06-011-...V06		HMD06-019-...V06		HMD06-026-...V06	
i	without brake	with brake	without brake	with brake	without brake	with brake
1-stage	-	-			-	
	-	-			-	
	-	-			-	
	-	-			-	
	-	-			-	
	-	-			-	
2-stage	9	3.39E-01		5.60E-01	+8.90E-02	7.82E-01
	12	3.31E-01		5.52E-01		7.74E-01
	15	2.88E-01		5.09E-01		7.31E-01
	16	2.96E-01		5.17E-01		7.39E-01
	20	2.85E-01		5.06E-01		7.28E-01
	25	2.84E-01		5.05E-01		7.27E-01
	32	2.74E-01		4.95E-01		7.17E-01
	40	2.74E-01		4.95E-01		7.17E-01
	64	2.73E-01		4.94E-01		7.16E-01

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the geared torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{zk} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

Motor type HMDo8-024 /-032 /-042 /-057
Gear Vo6



Stall, rated and peak torque - M [Nm]

				HMDo8-024-...Vo6 ¹⁾				HMDo8-032-...Vo6 ¹⁾				Gear Vo6 ²⁾	
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
2-stage	9	333	611	19.9	18.1	20.7	51.8	25.9	22.5	27.6	69.1	44	70
	12	250	458	26.5	24.2	27.6	69.1	34.6	30.0	36.9	92.2	44	70
	15	200	367	33.1	30.2	34.6	86.4	43.2	37.4	46.1	115.2	44	70
	16	188	344	35.0	31.9	36.5	91.2	45.6	39.5	48.6	121.6	44	70
	20	150	275	43.7	39.9	45.6	114.0	57.0	49.4	60.8	152.0	44	70
	25	120	220	54.6	49.9	57.0	142.5	-	-	-	-	40	64
	32	94	172	-	63.8	73.0	182.4	-	-	-	-	44	70
	40	75	138	-	-	-	-	-	-	-	-	40	64
	64	47	86	-	-	-	-	-	-	-	-	18	29

Stall, rated and peak torque - M [Nm]

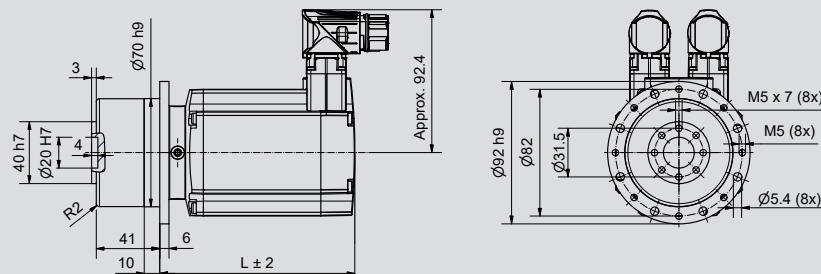
				HMDo8-042-...Vo6 ¹⁾				HMDo8-057-...Vo6 ¹⁾				Gear Vo6 ²⁾	
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
2-stage	9	333	611	33.7	29.4	36.3	90.7	45.8	37.2	49.2	123.6	44	70
	12	250	458	44.9	39.2	48.4	121.0	61.1	49.5	65.7	164.7	44	70
	15	200	367	56.2	49.0	60.5	151.2	-	61.9	82.1	205.9	44	70
	16	188	344	59.3	51.7	63.8	159.6	-	65.4	86.6	217.4	44	70
	20	150	275	-	64.6	79.8	199.5	-	-	-	-	44	70
	25	120	220	-	-	-	-	-	-	-	-	40	64
	32	94	172	-	-	-	-	-	-	-	-	44	70
	40	75	138	-	-	-	-	-	-	-	-	40	64
	64	47	86	-	-	-	-	-	-	-	-	18	29

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]
HMD08-024-...V06	without brake	-	-	-	2-stage	126.3	148.3	3.70
		-	-	-		174.8	196.8	4.35
	with brake	-	-	-		141.3	163.3	4.10
		-	-	-		189.8	211.8	4.75
HMD08-032-...V06	without brake	-	-	-		156.3	178.3	4.50
		-	-	-		204.8	226.8	5.15
	with brake	-	-	-		186.3	208.3	5.60
		-	-	-		234.8	256.8	6.25
HMD08-042-...V06	without brake	-	-	-		-	-	-
		-	-	-		-	-	-
	with brake	-	-	-		-	-	-
		-	-	-		-	-	-
HMD08-057-...V06	without brake	-	-	-		-	-	-
		-	-	-		-	-	-
	with brake	-	-	-		-	-	-
		-	-	-		-	-	-

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

		HMD08-024-...V06		HMD08-032-...V06		HMD08-042-...V06		HMD08-057-...V06	
	i	without brake	with brake						
1-stage	-	-		-		-		-	
	-	-		-		-		-	
	-	-		-		-		-	
	-	-		-		-		-	
	-	-		-		-		-	
	-	-		-		-		-	
	-	-		-		-		-	
2-stage	9	8.71E-01		1.20E+00		1.53E+00		2.19E+00	
	12	8.63E-01		1.19E+00		1.52E+00		2.18E+00	
	15	8.20E-01		1.15E+00		1.48E+00		2.14E+00	
	16	8.28E-01		1.16E+00		1.49E+00		2.15E+00	
	20	8.17E-01		1.15E+00		1.48E+00		2.14E+00	
	25	8.16E-01		1.15E+00		1.48E+00		2.14E+00	
	32	8.06E-01		1.14E+00		1.47E+00		2.13E+00	
	40	8.06E-01		1.14E+00		1.47E+00		2.13E+00	
	64	8.05E-01		1.14E+00		1.47E+00		2.13E+00	

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMDo8-024 /-032 /-042 /-057

Gear Vog



Stall, rated and peak torque - M [Nm]

				HMDo8-024-...Vog ¹⁾				HMDo8-032-...Vog ¹⁾				Gear Vog ²⁾	
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
2-stage	9	333	611	20.1	18.3	21.0	52.4	26.2	22.7	27.9	69.8	117	187
	12	250	458	26.5	24.2	27.6	69.1	34.6	30.0	36.9	92.2	120	192
	15	200	367	33.1	30.2	34.6	86.4	43.2	37.4	46.1	115.2	110	176
	16	188	344	35.3	32.3	36.9	92.2	46.1	39.9	49.2	122.9	120	192
	20	150	275	44.2	40.3	46.1	115.2	57.6	49.9	61.4	153.6	120	192
	25	120	220	55.2	50.4	57.6	144.0	72.0	62.4	76.8	192.0	110	176
	32	94	172	70.7	64.5	73.7	184.3	92.2	79.9	98.3	245.8	120	192
	40	75	138	87.4	79.8	91.2	228.0	114.0	98.8	121.6	304.0	110	176
	64	47	86	136.9	125.0	142.8	357.1	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

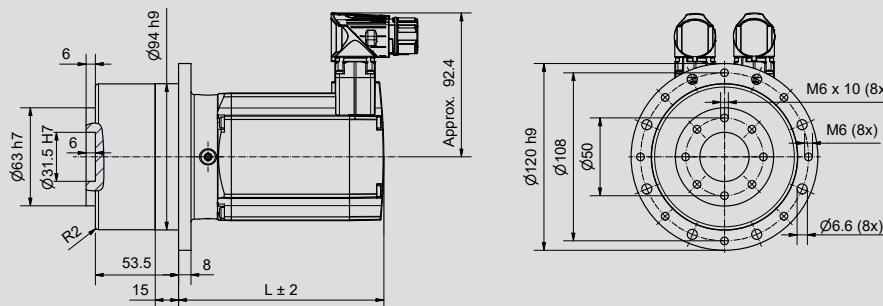
				HMDo8-042-...Vog ¹⁾				HMDo8-057-...Vog ¹⁾				Gear Vog ²⁾	
	i	$\eta_{out,3000 \text{ rpm}}^3$	$\eta_{out,5500 \text{ rpm}}^3$	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5500 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
2-stage	9	333	611	34.0	29.7	36.7	91.7	46.3	37.5	49.8	124.8	117	187
	12	250	458	44.9	39.2	48.4	121.0	61.1	49.5	65.7	164.7	120	192
	15	200	367	56.2	49.0	60.5	151.2	76.3	61.9	82.1	205.9	110	176
	16	188	344	59.9	52.2	64.5	161.3	81.4	66.0	87.6	219.6	120	192
	20	150	275	74.9	65.3	80.6	201.6	101.8	82.6	109.4	274.6	120	192
	25	120	220	93.6	81.6	100.8	252.0	127.2	103.2	136.8	343.2	110	176
	32	94	172	119.8	104.4	129.0	322.6	162.8	132.1	175.1	439.3	120	192
	40	75	138	148.2	129.2	159.6	399.0	-	163.4	216.6	543.4	110	176
	64	47	86	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	
HMD08-024-...V09	1-stage	without brake	-	-	2-stage	132.0	154.0	5.30	
		with brake	-	-		180.5	202.5	5.95	
HMD08-032-...V09		without brake	-	-		147.0	169.0	5.70	
		with brake	-	-		195.5	217.5	6.35	
HMD08-042-...V09		without brake	-	-		162.0	184.0	6.10	
		with brake	-	-		210.5	232.5	6.75	
HMD08-057-...V09		without brake	-	-		192.0	214.0	7.20	
		with brake	-	-		240.5	262.5	7.85	

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD08-024-...V09		HMD08-032-...V09		HMD08-042-...V09		HMD08-057-...V09	
i	without brake	with brake						
1-stage	-	-	+2.40E-01	-	+2.40E-01	-	+2.40E-01	-
	-	-		-		-		-
	-	-		-		-		-
	-	-		-		-		-
	-	-		-		-		-
	-	-		-		-		-
	-	-		-		-		-
9	1.13E+00		1.46E+00		1.79E+00		2.45E+00	
12	1.09E+00		1.42E+00		1.75E+00		2.41E+00	
15	1.07E+00		1.40E+00		1.73E+00		2.39E+00	
16	9.28E-01		1.26E+00		1.59E+00		2.25E+00	
20	8.80E-01		1.21E+00		1.54E+00		2.20E+00	
25	8.74E-01		1.20E+00		1.53E+00		2.19E+00	
32	8.28E-01		1.16E+00		1.49E+00		2.15E+00	
40	8.26E-01		1.16E+00		1.49E+00		2.15E+00	
64	8.25E-01		1.16E+00		1.49E+00		2.15E+00	

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{zk} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMD10-039 /-057 /-076 /-105

Gear Vog



Stall, rated and peak torque - M [Nm]

				HMD10-039...Vog ¹⁾				HMD10-057...Vog ¹⁾				Gear Vog ²⁾	
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
2-stage	9	333	556	31.4	27.9	34.0	85.6	45.4	34.9	49.8	124.8	117	187
	12	250	417	41.5	36.9	44.9	112.9	59.9	46.1	65.7	164.7	120	192
	15	200	333	51.8	46.1	56.2	141.1	74.9	57.6	82.1	205.9	110	176
	16	188	313	55.3	49.2	59.9	150.5	79.9	61.4	87.6	219.6	120	192
	20	150	250	69.1	61.4	74.9	188.2	99.8	76.8	109.4	274.6	120	192
	25	120	200	86.4	76.8	93.6	235.2	124.8	96.0	136.8	343.2	110	176
	32	94	156	110.6	98.3	119.8	301.1	159.7	122.9	175.1	439.3	120	192
	40	75	125	136.8	121.6	148.2	372.4	-	152.0	216.6	543.4	110	176
	64	47	78	-	-	-	-	-	-	-	-	50	80

Stall, rated and peak torque - M [Nm]

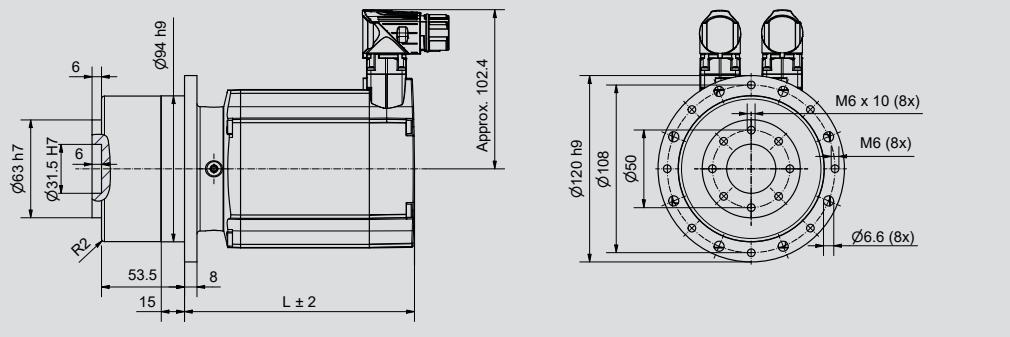
				HMD10-076...Vog ¹⁾				HMD10-105...Vog ¹⁾				Gear Vog ²⁾	
	i	$\eta_{out,3000\text{ rpm}}^3$	$\eta_{out,5000\text{ rpm}}^3$	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{n,3000\text{ rpm}}$	$M_{n,5000\text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
2-stage	9	333	556	56.7	41.9	66.3	165.9	75.1	48.0	91.7	229.6	117	187
	12	250	417	74.9	55.3	87.6	218.9	99.1	63.4	121.0	303.0	120	192
	15	200	333	93.6	69.1	109.4	273.6	123.8	79.2	151.2	378.7	110	176
	16	188	313	99.8	73.7	116.7	291.8	132.1	84.5	161.3	404.0	120	192
	20	150	250	124.8	92.2	145.9	364.8	165.1	105.6	201.6	505.0	120	192
	25	120	200	156.0	115.2	182.4	456.0	-	132.0	252.0	631.2	110	176
	32	94	156	-	147.5	233.5	583.7	-	169.0	322.6	807.9	120	192
	40	75	125	-	-	-	-	-	-	-	-	110	176
	64	47	78	-	-	-	-	-	-	-	-	50	80

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]
HMD10-039-...V09		without brake	-	-		148.2	169.2	7.30
		with brake	-	-		195.2	216.2	8.30
HMD10-057-...V09	1-stage	without brake	-	-	2-stage	163.2	184.2	7.80
		with brake	-	-		210.2	231.2	8.80
HMD10-076-...V09		without brake	-	-		178.2	199.2	8.30
		with brake	-	-		225.2	246.2	9.30
HMD10-105-...V09		without brake	-	-		208.2	229.2	9.30
		with brake	-	-		255.2	276.2	10.30

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD10-039-...V09		HMD10-057-...V09		HMD10-076-...V09		HMD10-105-...V09	
i	without brake	with brake						
1-stage	-	-			-	-		
	-	-			-	-		
	-	-			-	-		
	-	-			-	-		
	-	-			-	-		
	-	-			-	-		
	-	-			-	-		
2-stage	9	2.27E+00		+6.80E-01	3.08E+00	3.90E+00		+6.80E-01
	12	2.23E+00			3.04E+00	3.86E+00		
	15	2.21E+00			3.02E+00	3.84E+00		
	16	2.07E+00			2.88E+00	3.70E+00		
	20	2.02E+00			2.83E+00	3.65E+00		
	25	2.01E+00			2.82E+00	3.64E+00		
	32	1.97E+00			2.78E+00	3.60E+00		
	40	1.97E+00			2.78E+00	3.60E+00		
	64	1.97E+00			2.78E+00	3.60E+00		

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{zk} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Motor type HMD10-039 /-057 /-076 /-105

Gear V10



Stall, rated and peak torque - M [Nm]

				HMD10-039-...V10 ¹⁾				HMD10-057-...V10 ¹⁾				Gear V10 ²⁾	
	i	$\eta_{out,3000 \text{ rpm}}^3)$	$\eta_{out,5000 \text{ rpm}}^3)$	$M_{n,3000 \text{ rpm}}$	$M_{n,5000 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5000 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
2-stage	9	333	556	31.4	27.9	34.0	85.6	45.4	34.9	49.8	124.8	210	336
	12	250	417	41.5	36.9	44.9	112.9	59.9	46.1	65.7	164.7	260	416
	15	200	333	51.8	46.1	56.2	141.1	74.9	57.6	82.1	205.9	230	368
	16	188	313	55.3	49.2	59.9	150.5	79.9	61.4	87.6	219.6	260	416
	20	150	250	69.1	61.4	74.9	188.2	99.8	76.8	109.4	274.6	260	416
	25	120	200	86.4	76.8	93.6	235.2	124.8	96.0	136.8	343.2	230	368
	32	94	156	110.6	98.3	119.8	301.1	159.7	122.9	175.1	439.3	260	416
	40	75	125	138.2	122.9	149.8	376.3	199.7	153.6	218.9	549.1	230	368
	64	47	78	218.9	194.6	237.1	595.8	-	-	-	-	120	192

Stall, rated and peak torque - M [Nm]

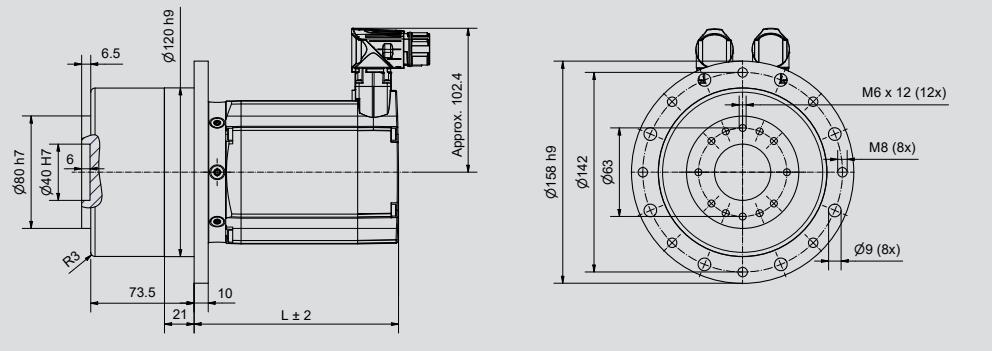
				HMD10-076-...V10 ¹⁾				HMD10-105-...V10 ¹⁾				Gear V10 ²⁾	
	i	$\eta_{out,3000 \text{ rpm}}^3)$	$\eta_{out,5000 \text{ rpm}}^3)$	$M_{n,3000 \text{ rpm}}$	$M_{n,5000 \text{ rpm}}$	M_o	M_{max}	$M_{n,3000 \text{ rpm}}$	$M_{n,5000 \text{ rpm}}$	M_o	M_{max}	$M_{G,n}$	$M_{G,max}$
1-stage	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
2-stage	9	333	556	56.7	41.9	66.3	165.9	75.1	48.0	91.7	229.6	210	336
	12	250	417	74.9	55.3	87.6	218.9	99.1	63.4	121.0	303.0	260	416
	15	200	333	93.6	69.1	109.4	273.6	123.8	79.2	151.2	378.7	230	368
	16	188	313	99.8	73.7	116.7	291.8	132.1	84.5	161.3	404.0	260	416
	20	150	250	124.8	92.2	145.9	364.8	165.1	105.6	201.6	505.0	260	416
	25	120	200	156.0	115.2	182.4	456.0	206.4	132.0	252.0	631.2	230	368
	32	94	156	199.7	147.5	233.5	583.7	264.2	169.0	322.6	807.9	260	416
	40	75	125	249.6	184.3	291.8	729.6	330.2	211.2	403.2	1009.9	230	368
	64	47	78	-	-	-	-	-	-	-	-	120	192

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

For UL approval, an S1 characteristic curve deviating by approx. 15 % applies.
The specifications on the nameplates correspond to the UL values.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	
HMD10-039-...V10	1-stage	without brake	-	-	2-stage	145.5	166.5	11.50	
with brake		-	-	-		192.5	213.5	12.50	
HMD10-057-...V10		without brake	-	-		160.5	181.5	12.00	
with brake		-	-	-		207.5	228.5	13.00	
HMD10-076-...V10		without brake	-	-		175.5	196.5	12.50	
with brake		-	-	-		222.5	243.5	13.50	
HMD10-105-...V10		without brake	-	-		205.5	226.5	13.50	
with brake		-	-	-		252.5	273.5	14.50	

Moment of inertia ⁵⁾ - J₁ [kg·cm²]

	HMD10-039-...V10		HMD10-057-...V10		HMD10-076-...V10		HMD10-105-...V10	
i	without brake	with brake						
1-stage	-	-	+6.80E-01	-	-	-	-	-
	-	-		-	-	-	-	-
	-	-		-	-	-	-	-
	-	-		-	-	-	-	-
	-	-		-	-	-	-	-
	-	-		-	-	-	-	-
	-	-		-	-	-	-	-
2-stage	9	3.06E+00	+6.80E-01	3.87E+00	+6.80E-01	4.69E+00	+6.80E-01	6.33E+00
	12	2.93E+00		3.74E+00		4.56E+00		6.20E+00
	15	2.88E+00		3.69E+00		4.51E+00		6.15E+00
	16	2.42E+00		3.23E+00		4.05E+00		5.69E+00
	20	2.23E+00		3.04E+00		3.86E+00		5.50E+00
	25	2.21E+00		3.02E+00		3.84E+00		5.48E+00
	32	2.05E+00		2.86E+00		3.68E+00		5.32E+00
	40	2.04E+00		2.85E+00		3.67E+00		5.31E+00
	64	2.03E+00		2.84E+00		3.66E+00		5.30E+00

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the gear rated torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{2k} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

**■ Motor type HMD₁₃-133 /-190 /-245
Gear V10**



Stall, rated and peak torque - M [Nm]

				HMD ₁₃ -133...V10 ¹⁾				HMD ₁₃ -190-...V10 ¹⁾				Gear V10 ²⁾	
	i	$\eta_{out, 2000 \text{ rpm}}^3$	$\eta_{out, 3600 \text{ rpm}}^3$	$M_{n_r, 2000 \text{ rpm}}$	$M_{n_r, 3600 \text{ rpm}}$	M_o	M_{max}	$M_{n_r, 2000 \text{ rpm}}$	$M_{n_r, 3600 \text{ rpm}}$	M_o	M_{max}	$M_{G, n}$	$M_{G, max}$
1-stage	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-	-	-	-	-
2-stage	9	222	400	100.4	78.6	116.1	290.7	139.7	97.8	165.9	414.7	210	336
	12	167	300	132.5	103.7	153.2	383.6	184.3	129.0	218.9	547.2	260	416
	15	133	240	165.6	129.6	191.5	479.5	230.4	161.3	273.6	684.0	230	368
	16	125	225	176.6	138.2	204.3	511.5	245.8	172.0	291.8	729.6	260	416
	20	100	180	220.8	172.8	255.4	639.4	307.2	215.0	364.8	912.0	260	416
	25	80	144	276.0	216.0	319.2	799.2	-	268.8	456.0	1140.0	230	368
	32	63	113	353.3	276.5	408.6	1023.0	-	344.1	583.7	1459.2	260	416
	40	50	90	-	-	-	-	-	-	-	-	230	368
	64	31	56	-	-	-	-	-	-	-	-	120	192

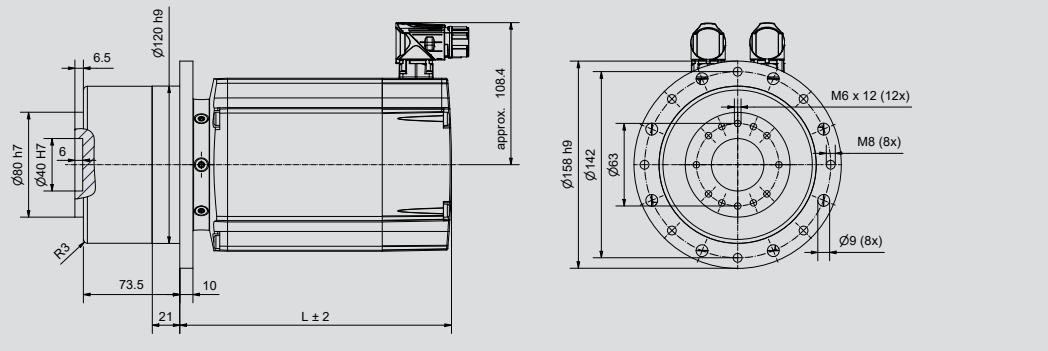
Stall, rated and peak torque - M [Nm]

				HMD ₁₃ -245...V10 ¹⁾				Gear V10 ²⁾	
	i	$\eta_{out, 2000 \text{ rpm}}^3$	$\eta_{out, 3600 \text{ rpm}}^3$	$M_{n_r, 2000 \text{ rpm}}$	$M_{n_r, 3600 \text{ rpm}}$	M_o	M_{max}	$M_{G, n}$	$M_{G, max}$
1-stage	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-
	-	-	-	-	-	-	-	-	-
2-stage	9	222	400	179.0	116.1	213.9	535.1	210	336
	12	167	300	236.2	153.2	282.2	706.2	260	416
	15	133	240	295.2	191.5	352.8	882.7	230	368
	16	125	225	314.9	204.3	376.3	941.6	260	416
	20	100	180	-	255.4	470.4	1177.0	260	416
	25	80	144	-	319.2	588.0	1471.2	230	368
	32	63	113	-	-	-	-	260	416
	40	50	90	-	-	-	-	230	368
	64	31	56	-	-	-	-	120	192

We refer to pages 4 and 5 to compile the type code correctly.

When selecting the drive, please note that your required application torques must not exceed the corresponding values of either the motor-gear combination or the gear alone listed in the table. The respective lower value of combination or gear unit alone is the limiting value.

Dimensions



Motor type	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]	Stage	L _{short} [mm] ⁴⁾	L _{long} [mm] ⁴⁾	m [kg]
HMD13-133-...V10		without brake	-	-		-	207.3	15.40
		with brake	-	-		-	245.0	16.50
HMD13-190-...V10	1-stage	without brake	-	-	2-stage	-	237.3	18.00
		with brake	-	-		-	275.0	19.10
HMD13-245-...V10		without brake	-	-		-	267.3	20.50
		with brake	-	-		-	328.3	23.50

Moment of inertia ⁵⁾ - J₁ [kg-cm²]

	HMD13-133-...V10		HMD13-190-...V10		HMD13-245-...V10	
i	without brake	with brake	without brake	with brake	without brake	with brake
1-stage	-	-	-	-	-	-
	-	-	-	-	-	-
	-	-	-	-	-	-
	-	-	-	-	-	-
	-	-	-	-	-	-
	-	-	-	-	-	-
	-	-	-	-	-	-
2-stage	9	9.32E+00	+1.90E+00	1.31E+01	+1.90E+00	1.69E+01
	12	9.19E+00		1.30E+01		1.68E+01
	15	9.14E+00		1.29E+01		1.67E+01
	16	8.68E+00		1.25E+01		1.63E+01
	20	8.49E+00		1.23E+01		1.61E+01
	25	8.47E+00		1.23E+01		1.61E+01
	32	8.31E+00		1.21E+01		1.59E+01
	40	8.30E+00		1.21E+01		1.59E+01
	64	8.29E+00		1.21E+01		1.59E+01

1) Data calculated with a gear efficiency grade defined at $n_g=1000\text{rpm}$ and the geared torque and a reference temperature of 70°C .

2) Data refer to an output shaft speed of $n_{out}=100\text{rpm}$ and an application factor $K_a=1$ as well as S1 operating mode.

3) Observe the notes on the average thermal input speed of the gear in chapter „Technical data and additional information“.

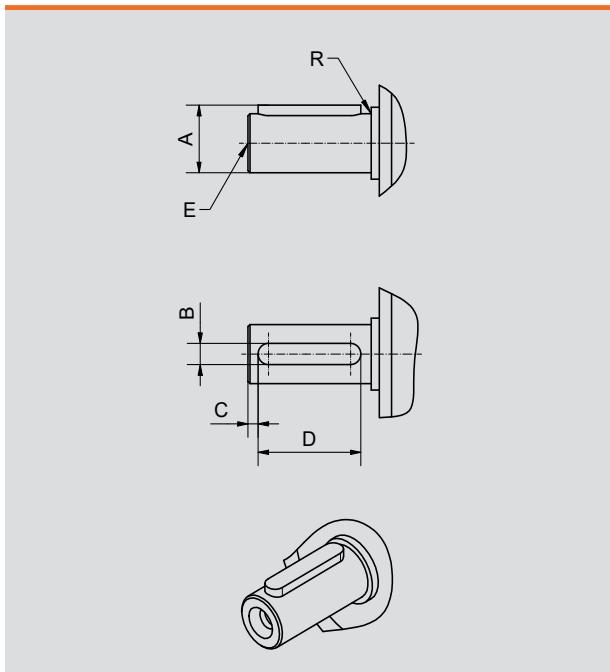
4) Short version only possible with resolver, ECI1118, SEK/SEL 37, HESx / HEMx, HS/M 16 and only for versions with $U_{zk} = 320/560 \text{ V}_{DC}$. With other encoder / voltage variant, only the long version is possible.

5) Mass moments of inertia incl. gear and motor refer to the motor output shaft (additionally with brake by summation of the specified value).

■ Overview output shaft and feather key

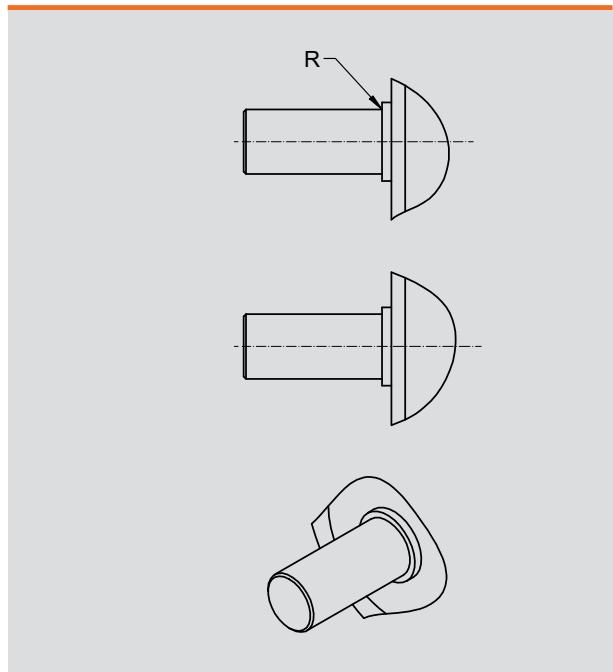
Option drive - with feather key

Feather keys according to DIN6885,
Form A + Centering hole according
to DIN332, Form DR



Option drive - without feather key

Design with smooth shaft and without
centering hole



Gear type	Feather key				E (center hole according to DIN 332, form DR)	Max. Radius R
	A	B	C	D		
E06	16	5h9	2.5	25	M5 x 12,5	0.6
E07	18	5h9	4	20	M5 x 12,5	1.0
E08	22.5	6h9	4	28	M6 x 16	1.0
E09	22.5	6h9	4	28	M6 x 16	1.2
E10	28	8h9	5	40	M10 x 22	1.2
P07	18	5h9	2	25	M5 x 12,5	1.0
P09	24.5	6h9	2	32	M8 x 19	1.2
H06	18	5h9	2	25	M5 x 12,5	1.0
H08	24.5	6h9	4	28	M8 x 19	1.0

■ Option angular gearbox with direct mounting

Angular gearbox stage for HeiMotion Servo modular system

The angular gear stage is available in two transmission ratios ($i=1$ and $i=2$). These can be combined in any order, resulting in up to 120 different combinations.

Due to the ratio $i=2$ in the angle, a reduction to a 1-stage planetary gear at the output can be achieved in many applications, which lowers the costs and space requirements significantly.

The angle gearbox is made of a lightweight die-cast aluminum body and stands out with its thermally optimized and compact design. In addition to its efficiency-optimized bevel gears with low noise emission, it also offers a reduced torsional backlash. The gear units are maintenance-free due to a lifetime lubrication with grease.



Option angular gearbox with direct mounting

Order code

Order designation: HMD06-019-320-30-BPR1PY17**ED616**

Gear type*

Economy series → E
Powerful economy → P
Heavy duty → H
Flange output → F¹⁾
Vehicle optimized → V^{1,2)}

Mounting variant

Angular gear

- V1(i=1) A
- V1(i=2) B
- V2(i=1) C
- V2(i=2) D
- V3(i=1) E
- V3(i=2) F
- V4(i=1) G
- V4(i=2) H

Gear size*

- 60 mm → 6
- 60/70 mm → 7
- 80 mm → 8
- 80/90 mm → 9

Complete ratio

i_{ges}	Winkel i=1 (Variante A,C,E,G)	Winkel i=2 (Variante B,D,F,H)
03	x ³⁾	-
04	x ³⁾	-
05	x ³⁾	-
06	-	x ³⁾
07	x ³⁾	-
08	-	x ³⁾
09	x	-
10	-	x ³⁾
12	x	-
14	-	x ³⁾
15	x	-
16	x	x ³⁾
18	-	x
20	x	x ³⁾
24	-	x
25	x	-
30	-	x
32	-	x
40	-	x
50	-	x
64	-	x
80	-	x

Possible combinations

Motor size	Angle size	Planetary gear size
60	60	60
80	60	60
80	80	80
100	80	80

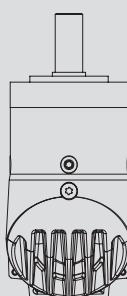
*See also catalog HMXG

1) Combinations of motor size 80 with angle 60 and motor size 100 with angle 80 not possible for technical reasons.

2) Mounting variants V1 not possible for mounting reasons.

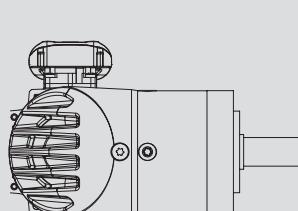
3) Total gear ratio not possible for gear unit type V, as single-stage V gear units are not available.

Explanation of the order key



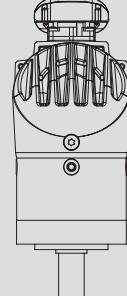
Mounting variant V1
Encryption:

- A i=1 Angular toothings
- B i=2 Angular toothings



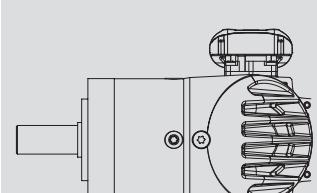
Mounting variant V2
Encryption:

- C i=1 Angular toothings
- D i=2 Angular toothings



Mounting variant V3
Encryption:

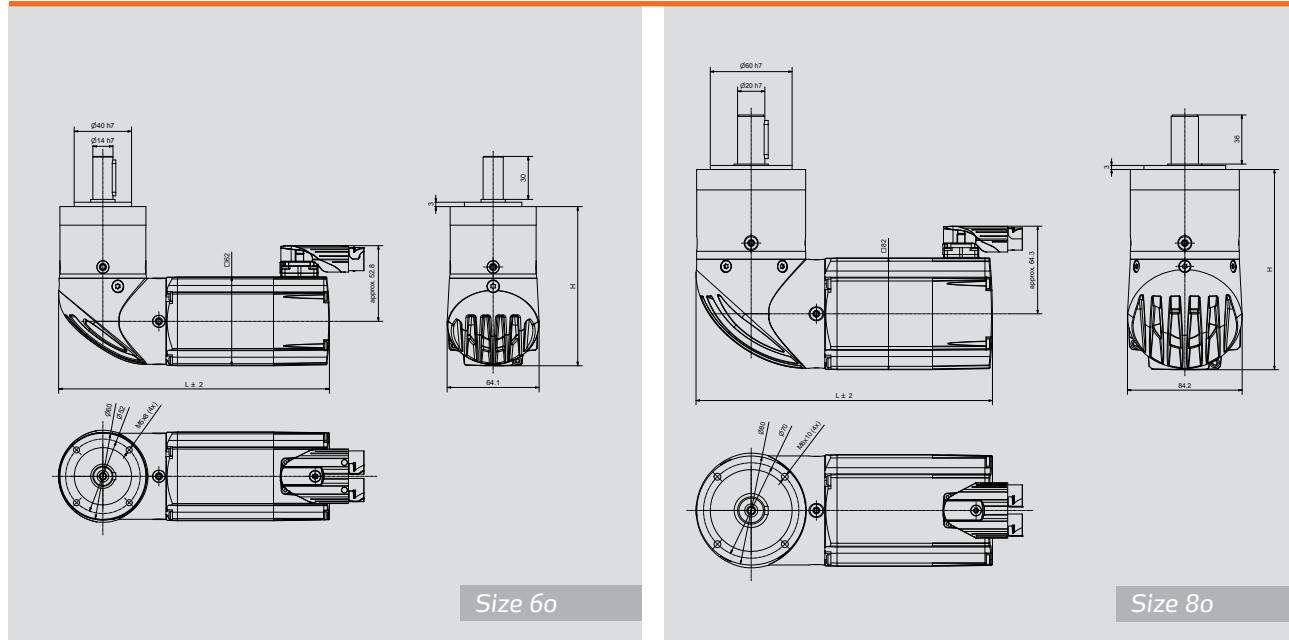
- E i=1 Angular toothings
- F i=2 Angular toothings



Mounting variant V4
Encryption:

- G i=1 Angular toothings
- H i=2 Angular toothings

Dimensions - Example of Economy series Gearbox from the HMDG modular system



Motor type	L _{short} [mm]	H [mm]
HMD06-011	without brake with brake	165.6 205.1
HMD06-019	without brake	190.6
	with brake	230.1
HMD06-026	without brake	220.6
	with brake	260.1
HMD08-024	without brake	201.0
	with brake	249.5
HMD08-032	without brake	216.0
	with brake	264.5
HMD08-042	without brake	231.0
	with brake	279.5
HMD08-057	without brake	261.0
	with brake	309.5

Technical data subject to change! Last changes 11/2023



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